

# Formal Aspects of Strategic Reasoning

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# Alternating-Time Temporal-Logic

[...from two...to multi-player games...]

# From Two-Player to Multi-Player

- ❑ Module Checking is a basic setting to check for system correctness against an adversarial environment: two-player game «**Sys vs. Env**»

- ❑ It is suitable for several system verification scenario, but very specific:

  - The system has only **one strategy**

  - The environment has the ability to **non-deterministically** disable possible evolution of the game

- ❑ Nowadays systems are composed of **several agents**, autonomous and rational, each one with its own goal, interacting among them and sensing the other agents.

- ❑ An important contribution in this field:

**Alternating-Time Temporal Logic**

**[Alur, Kupferman, Henzinger. J. of ACM 2002]**

# Agents in ATL

- ❑ ATL generalizes CTL: temporal operators are indexed by coalitions of agents.
- ❑ Formally, path quantifiers A and E are replaced with the strategic cooperative quantifiers  $\langle\langle A \rangle\rangle$  and  $[[A]]$ , where **A is a team of agents**.
- ❑  $\langle\langle A \rangle\rangle\phi$  means that coalition A has a (collective) strategy to enforce  $\phi$ , no matter what the other agents (not in A) will behave.
- ❑ Strategic quantifiers allow for a selective extraction of paths over a (game) model.
- ❑ As for CTL\*, we can have ATL\*

# Syntax of ATL and ATL\*

- ATL\* contains state-formulas and path-formulas.
- ATL\* state-formulas are formed according to the grammar:
  - $\phi := \text{true} \mid p \mid \phi \wedge \phi \mid \neg\phi \mid \langle\langle A \rangle\rangle \psi$   
where  $p \in AP$  and  $\psi$  is a path-formula
- ATL\* path-formulas are as in CTL\*:
  - $\psi := \phi \mid \psi \wedge \psi \mid \neg\psi \mid X\psi \mid \psi \cup \psi$   
where  $\phi$  is a state-formula, and  $\psi$  a path-formula

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- ❑ ATL\* path-formulas are as in CTL\*:
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where  $\phi$  is a state-formula, and  $\psi$  a path-formula
- ❑ In ATL path-formulas are reduced to:
  - $\psi := X\phi \mid \phi U \phi$   
where  $\phi$  is a state-formula.
- ❑ Note that in ATL, X and U alternate with  $\langle\langle A \rangle\rangle$  and its dual  $[[A]]$

# Example

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□ Agents = {



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□  $\llcorner\text{Lupin}\lrcorner$  (G run away  $\wedge$  F diamonds)

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- «Lupin, Margot» fun Until caught

“Lupin and Margot have fun with money until they get caught from Zenigata”



# ATL Semantics: CGS

- ATL can be interpreted over **Concurrent Game Structures** (CGS):

$$C = (AP, Ag, Ac, S, S_0, R, Lab)$$

- AP is a set of atomic propositions
- Ag is a set of agents
- Ac is a set of Actions
- S is a set of states
- $S_0 \subseteq S$  is the set of initial states
- $Lab : S \rightarrow 2^{AP}$  labels each state with propositions true in the state
- Let  $Dc: Ag \rightarrow Ac$  be the set of agent's decisions (action choices). Then, we have  $R : S \times Dc \rightarrow S$

# Example

- Let  $M = (AP, Ag, Ac, S, S_0, R, Lab)$  be a GCS representing a city with a Bank and a Museum in which Lupin and Zenigata, starting from Home, compete

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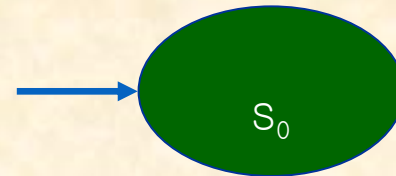
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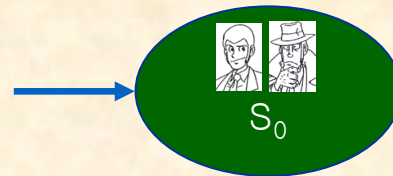
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  - $AP = \{Win_L, Win_Z\}$
  - Lab:
    - Lupin's winning states  $\rightarrow Win_L$
    - Lupin's losing states  $\rightarrow Win_Z$



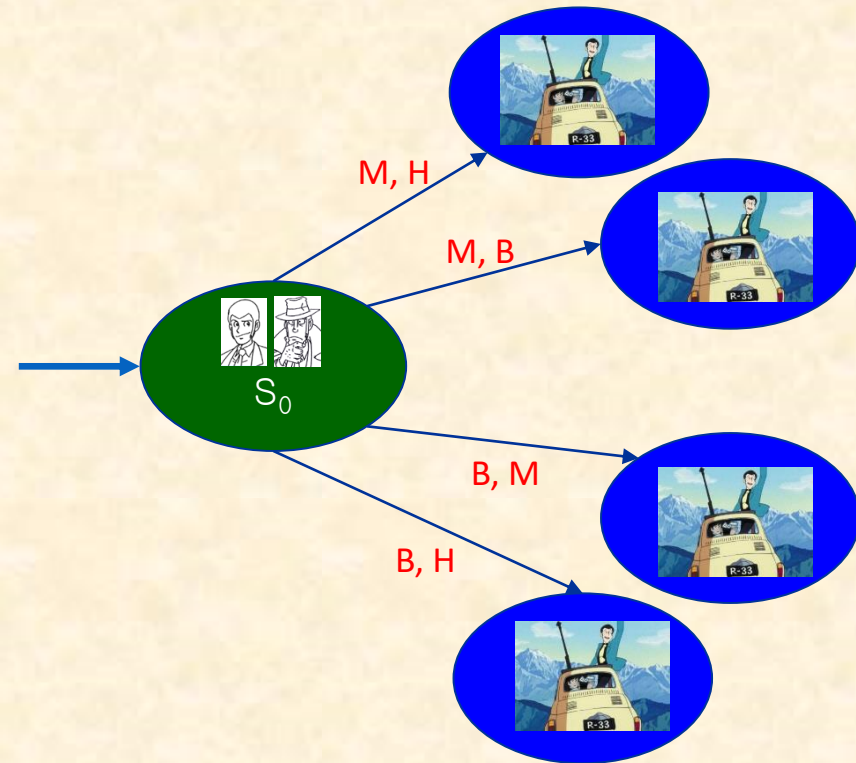


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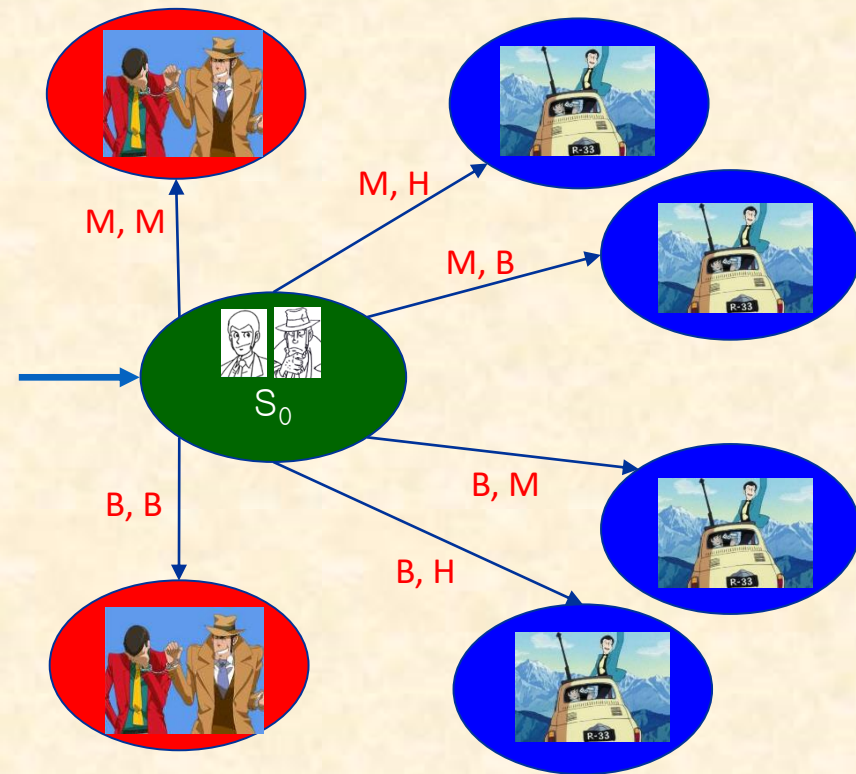
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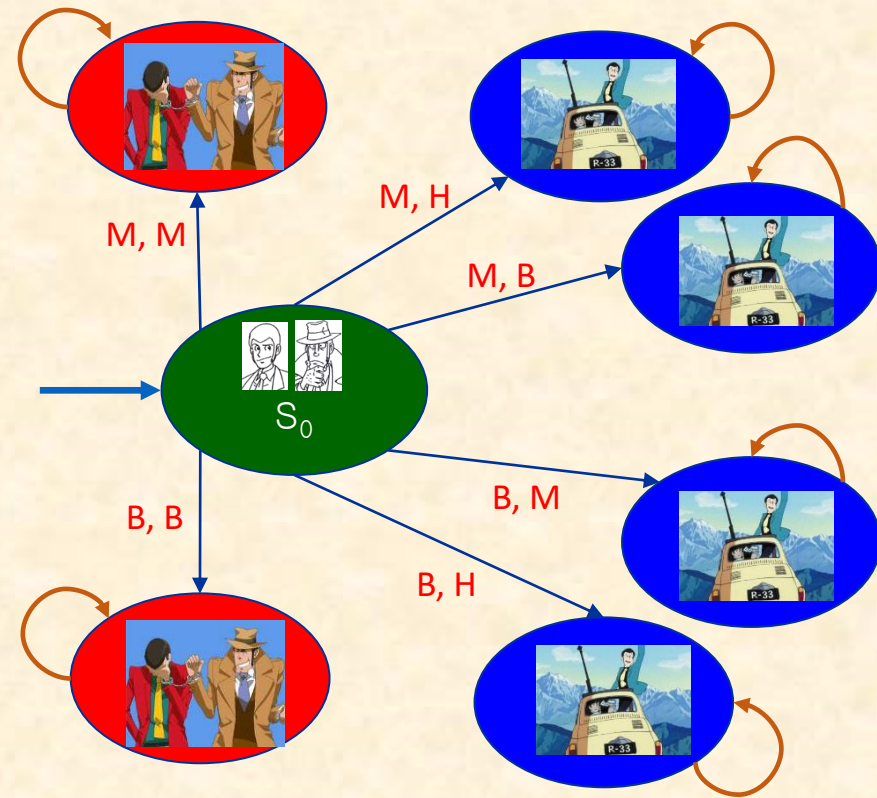


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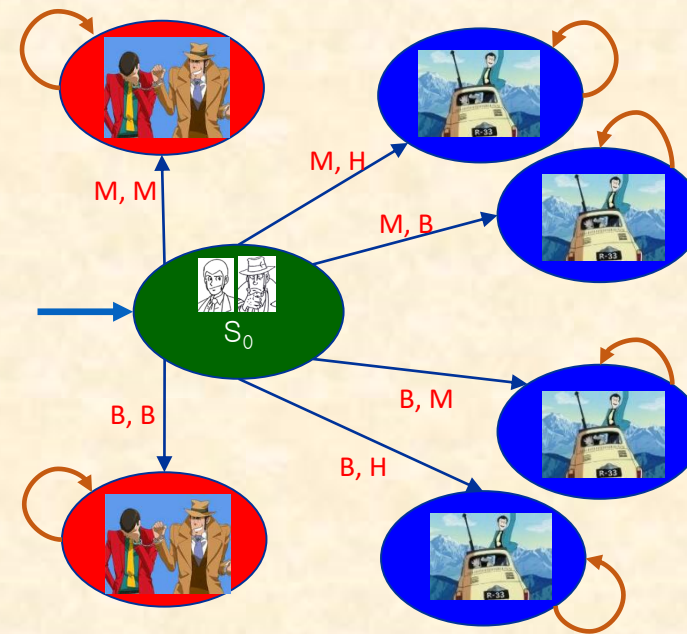


# ATL Semantics: Strategies

- ❑ A strategy for an agent  $a$  is  $s_a: St^+ \rightarrow Act$
- ❑ It is a **memoryfull** conditional plan that specifies which decision the agent  $a$  has to take in every possible situation.
- ❑ Formally, it is considered a **perfect recall** strategy
- ❑ As in Module Checking, we can have a memoryless (imperfect recall) strategy  $is_a: St \rightarrow Act$ . We will come back on this later...
- ❑ A collective strategy  $S_A$  for a group of agents  $A$  is a tuple of strategies, one for each agent in  $A$ .
- ❑ The **outcome** of the team  $A$  from a state  $q$ ,  $out(q, S_A)$ , is the set of all paths that result from agents  $A$  executing  $S_A$  (concurrently)
- ❑  $M, q \models \langle\langle A \rangle\rangle \phi$  iff there is  $S_A$ , such that  $M, \pi \models \phi$  for every  $\pi \in out(q, S_A)$ .
- ❑ CTL path quantifiers can be embedded in ATL:
  - $E\phi \equiv \langle\langle Agt \rangle\rangle \phi$
  - $A\phi \equiv \langle\langle \emptyset \rangle\rangle \phi$

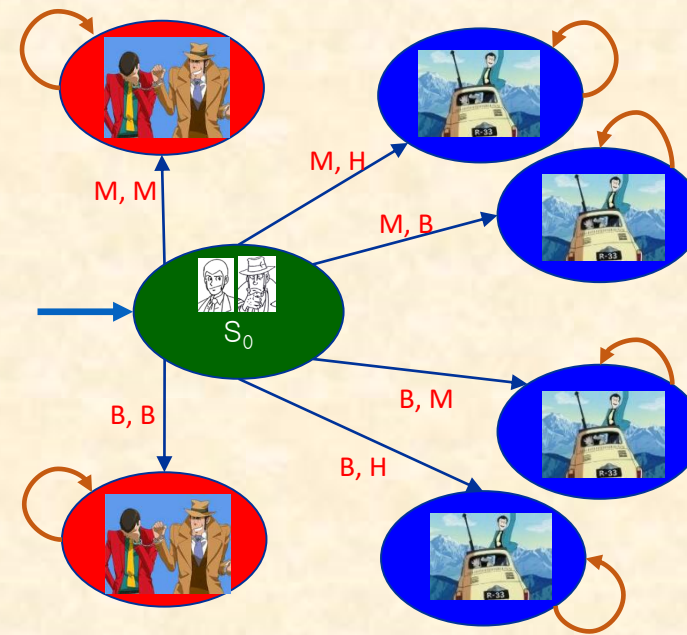
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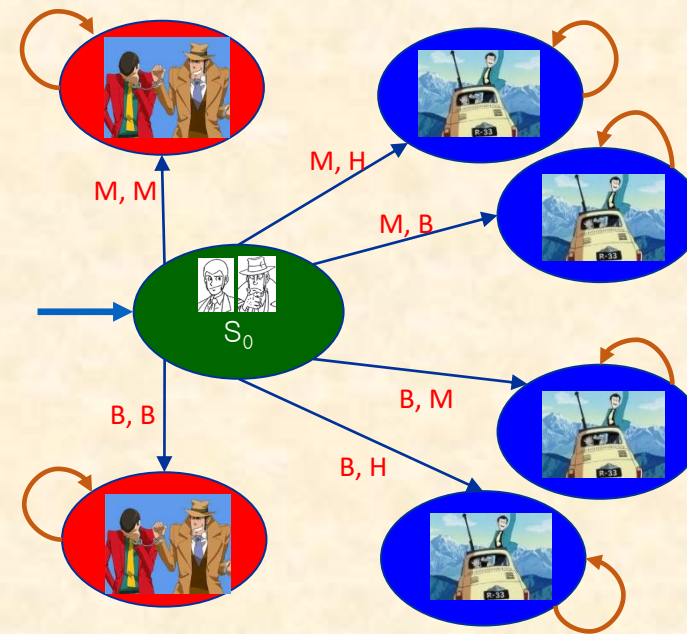
- Let us consider again the Lupin-Zenigata game  $M$
- Recall that  $M, q \models \langle\langle A \rangle\rangle \phi$  iff there exists a collective strategy  $S_A$ , such that  $G, \pi \models \phi$  for every  $\pi \in \text{out}(q, S_A)$



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- Let us consider again the Lupin-Zenigata game  $M$
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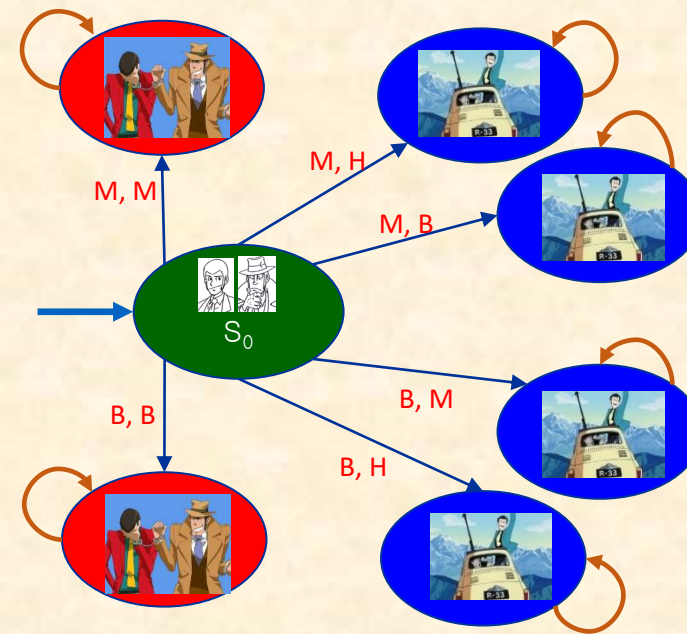
- $M \not\models \ll \text{Lupin} \gg G \text{Win}_L$ 
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- Recall that  $M, q \models \ll A \gg \phi$  iff there exists a collective strategy  $S_A$ , such that  $G, \pi \models \phi$  for every  $\pi \in \text{out}(q, S_A)$

- $M \not\models \ll \text{Lupin} \gg G \text{Win}_L$ 
  - Lupin does not have a strategy to Win
- $M \models \ll \text{Lupin, Zenigata} \gg F \text{Win}_L$ 
  - Lupin wins if he cooperates with Zenigata
  - Note: this is a Liveness property, e.g., something good will happen





# ATL and ATL\* Model checking

- For ATL, a fix-point algorithm is easy and effective:
  - You need to calculate  $\text{Pre}(A, Q)$ : the states  $q$  from which the coalition  $A$  can force the game to reach  $Q$ , no matter how the other agents will play.
- For ATL\*, one can reduce to parity games, or use an automata-theoretic approach via Parity condition. The latter extends the one used for CTL\*

```
function mcheck( $\mathcal{M}, \varphi$ ).  
  Global model checking formulae of ATL.  
  Returns the exact subset of  $St$  for which formula  $\varphi$  holds.  
case  $\varphi \equiv p$  : return  $\mathcal{V}(p)$   
case  $\varphi \equiv \neg\psi$  : return  $St \setminus \text{mcheck}(\mathcal{M}, \psi)$   
case  $\varphi \equiv \psi_1 \wedge \psi_2$  : return  $\text{mcheck}(\mathcal{M}, \psi_1) \cap \text{mcheck}(\mathcal{M}, \psi_2)$   
case  $\varphi \equiv \langle\langle A \rangle\rangle X\psi$  : return  $\text{pre}(A, \text{mcheck}(\mathcal{M}, \psi))$   
case  $\varphi \equiv \langle\langle A \rangle\rangle G\psi$  :  
   $Q_1 := Q$ ;  $Q_2 := Q_3 := \text{mcheck}(\mathcal{M}, \psi)$ ;  
  while  $Q_1 \not\subseteq Q_2$  do  $Q_1 := Q_1 \cap Q_2$ ;  $Q_2 := \text{pre}(A, Q_1) \cap Q_3$  od;  
  return  $Q_1$   
case  $\varphi \equiv \langle\langle A \rangle\rangle \psi_1 U \psi_2$  :  
   $Q_1 := \emptyset$ ;  $Q_2 := \text{mcheck}(\mathcal{M}, \psi_2)$ ;  $Q_3 := \text{mcheck}(\mathcal{M}, \psi_1)$ ;  
  while  $Q_2 \not\subseteq Q_1$  do  $Q_1 := Q_1 \cup Q_2$ ;  $Q_2 := \text{pre}(A, Q_1) \cap Q_3$  od;  
  return  $Q_1$   
end case
```

$$\text{pre}(A, Q) = \{q \mid \exists \alpha_A \forall \alpha_{\text{Agt} \setminus A} o(q, \alpha_A, \alpha_{\text{Agt} \setminus A}) \in Q\}$$

# ATL decision problems

Complexity Results for ATL			
Logic	Model Checking w.r.t.system	Model Checking	Satisfiability
LTL	NLOGSPACE [4]	PSPACE [5]	PSPACE [4]
CTL	NLOGSPACE [6]	PTIME [5]	EXPTIME [2]
CTL*	NLOGSPACE [6]	PSPACE [5]	2EXPTIME [4]
ATL	PTIME [3]	PTIME [3]	EXPTIME [7]
ATL*	PTIME [3]	2EXPTIME [3]	2EXPTIME [8]

- [2] Clarke, Emerson: Logics of Programs 1981
- [3] Alur, Henzinger, Kupferman: JACM 2002
- [4] Emerson: Temporal and modal logic. MIT Press 1990
- [5] Clarke, Emerson, Sistla. TOPLAS 1986
- [6] Kupferman, Vardi, Wolper. JACM 2000
- [7] Walther, Lutz, Wolter, Wooldridge: J. of Logic and Computation 2006
- [8] Schewe. ICALP 2008

# ATL vs. Module Checking

## □ Module checking

- Two-player game (system vs. environment)
- Environment strategies come through  $\text{Exec}(M)$
- CTL Module Ckecking is EXPTIME-complete (PTime in the model)

## □ ATL

- Multi-player
- Strategies come from coalition of agents.
- ATL model checking is PTIME in  $|\text{states}|$  of  $M$  and  $|\phi|$ , but notice that  $|M|$  is exponential in the number of agents

# Part 2

- ❑ We keep talking about logics for strategic reasoning
- ❑ We introduce Strategy Logic as a powerful extension of ATL
- ❑ In ATL
  - Strategies are treated implicitly
  - Agents cannot share strategies nor reuse some from the past.
  - Every time an agent appears in a formula, previous strategies are reset
- ❑ In Strategy Logic
  - Strategies are unpacked from agents and used as first order objects.
  - Strategies can be reused and shared among agents.
  - Several complex and useful specifications can be expressed without effecting the overall decision complexities. Among the others: **Nash Equilibrium**.

Let's have a break!

