LOGIC-BASED EXPLAINABLE ARTIFICIAL INTELLIGENCE

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Lecture 03

• Rigorous definitions of abductive and contrastive explanations

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- Example algorithm for finding one AXp/CXp
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- Explanations for XpGs
- Explanations for monotonic classifiers

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	- I_5 : $\{1\}$
	- $\mathcal{L} = \{\{1\}, \{4\}, \{5\}\}\$

- Instance: $(\mathbf{v}, c) = ((0, 0, 1, 2), 1)$
- AXp's: $\{1, 4\}$ (prediction unchanged)
- CXp's:
	- \cdot {1}, by flipping the value of feature 1
	- \cdot {4}, by flipping the value of feature 4
	- But also, $\{\{1\}, \{4\}\}\$ by MHS duality

- \cdot Lecture 01 units:
	- #01: Foundations
- \cdot Lecture 02 units:
	- #02: Principles of symbolic XAI feature selection
	- #03: Tractability in symbolic XAI (& myth of interpretability)
- \cdot Lecture 03 units:
	- #04: Intractability in symbolic XAI (& myth of model-agnostic XAI)
	- #05: Explainability queries
- \cdot Lecture 04 units:
	- #06: Advanced topics
- Lecture 05 units:
	- #07: Principles of symbolic XAI feature attribution (& myth of Shapley values in XAI)
	- #08: Conclusions & research directions

Some comments...

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- For high-risk and safety-critical domains:
	- Would you use an ML model that you cannot explain with rigor, and whose heuristic explanations are likely to be wrong, and so debugging/understanding with rigor is all but impossible?

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- What is the bottom line?
	- \cdot For high-risk and safety-critical domains, one **ought** to deploy models that can be explained with rigor
	- If that means using a fairly unexciting NN with up to 100K neurons, that is the cost of trust; for anything else, one is trying his/her luck, in situations that could become catastrophic!

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	- More examples next...

BTW, highly problematic decision trees also in precision medicine...

Source: G. Valdes, J.M. Luna, E. Eaton, C.B. Simone, L.H. Ungar, & T.D. Solberg.

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- However, it is relatively simple to implement tree learners
- Can one really trust the operation of more complex ML models, even those subject to extensive testing?
- And how to debug complex ML models if heuristic explanations are also incorrect (more later)?
- For trustworthy AI, there exists no alternative to rigorous logic-based explanations!

Unit #04

(Efficient) Intractability in Symbolic XAI

- Clauses for encoding ϕ : $\mathfrak{E}_{\phi}(z_1,\ldots)$, such that $z_1 = 1$ iff $\phi = 1$
- \cdot For τ_j : $\mathfrak{E}_{\tau_j}(t_j,\ldots)$
- For $x_i = v_i$: $\mathfrak{E}_{x_i = v_i}(l_i, \ldots)$
- Let $e_i = 1$ iff d_i matches c
- \cdot Prediction change with rule up to R $_j$ (with $d_j\neq c$), if $\tau_j\not\models\bot$ and $\tau_k\models\bot$, for $1\leqslant k< j$, with $e_k = 1$:

$$
\left[f_j \leftrightarrow \left(t_j \wedge \bigwedge\nolimits_{1\leq k < j, e_k = 1} \neg t_k\right)\right]
$$

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- Let $e_i = 1$ iff d_i matches c
- \cdot Require that at least one f_j , with $e_j=0$ and $1\leqslant j\leqslant n$, to be consistent (i.e. some rule up to *j* with prediction other than *c* to fire):

$$
\left(\bigvee\nolimits_{1\leq j\leq n, e_j=0} f_j\right)
$$

- The set of soft clauses is given by: $S \triangleq \{(l_i), i = 1, \ldots, m\}$
- The set of hard clauses is given by:

$$
\mathcal{B} \triangleq \bigwedge\nolimits_{1 \leq i \leq m} \mathfrak{E}_{x_i = v_i}(l_i, \ldots) \land \bigwedge\nolimits_{1 \leq j \leq n} \mathfrak{E}_{\tau_j}(t_j, \ldots) \land \bigwedge\nolimits_{1 \leq i \leq n, e_j = 0} \left(f_j \leftrightarrow \left(t_j \land \bigwedge\nolimits_{1 \leq k < j, e_k = 1} \neg t_k \right) \right) \land \left(\bigvee\nolimits_{1 \leq j \leq n, e_j = 0} f_j \right)
$$

- \cdot *B* \cup *S* \vdash 1
	- MUSes are AXp's & MCSes are CXp's

Outline – Unit #04

Explaining Decision Lists

Myth #02: Model-Agnostic Explainability

Progress Report on Symbolic XAI

• Q: Are model-agnostic explanations rigorous?

• Example instance:

• But, explanation incorrectly "explains" another instance (from training data!)

```
IF (animal_name = toad) \land \neghair \land \negfeathers \land eggs \land \negmilk \land¬airborne ∧ ¬aquatic ∧ ¬predator ∧ ¬toothed ∧ backbone ∧ breathes ∧
         \negvenomous \land \negfins \land (legs = 4) \land \negtail \land \negdomestic \land \negcatsize
THEN (class = amplibian)
```
Model-agnostic explainers cannot be trusted \blacksquare

Incorrect explanations: Classifier for deciding bank loans

Model-agnostic explainers cannot be trusted **Internal Control** Elimination and International

Incorrect explanations: Classifier for deciding bank loans

Two samples: Bessie $:= (v_1, Y)$ and Clive $:= (v_2, N)$

Model-agnostic explainers cannot be trusted **Indian Indian Industries**

Incorrect explanations:

Classifier for deciding bank loans

Two samples: Bessie = (v_1, Y) and Clive = (v_2, N)

Explanation *X*: $age = 45$, salary = 50K

Model-agnostic explainers cannot be trusted **Internal Connect Connect Connect C**INM19b]

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Explanation $X: \text{age} = 45, \text{ salary} = 50K$

And,

X is consistent with Bessie = $(\mathbf{v}_1, \mathbf{Y})$

X is consistent with Clive $:= (\mathbf{v}_2, \mathbf{N})$

 \therefore different outcomes & same explanation !?

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	- 1. *X* is sufficient for prediction:

$$
\forall (\mathbf{x} \in \mathbb{F}). \bigwedge_{j \in \mathcal{X}} (X_j = V_j) \rightarrow (\kappa(\mathbf{x}) = c)
$$

2. And, X is subset-minimal:

$$
\forall (t \in \mathcal{X}). \exists (\mathbf{x} \in \mathbb{F}). \bigwedge_{j \in (\mathcal{X} \setminus \{t\})} (x_j = v_j) \rightarrow (\kappa(\mathbf{x}) \neq c)
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Depending on logic encoding used for classifier, different automated reasoners can be employed

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• Approach is bounded by scalability of rigorous explanations...

• Obs: Lack of rigor of model-agnostic explanations known since 2019 [INM19b, Ign20, YIS+23]

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- For feature attribution we proposed different ways of assessing rigor [INM19b, NSM+19, Ign20, YIS+23]

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Outline – Unit #04

Explaining Decision Lists

Myth #02: Model-Agnostic Explainability

Progress Report on Symbolic XAI

Efficacy map – progress until 2022 $\text{M}_{\text{M122, M1322, M523}}$

 $[IMM19b, Ign20, IIM20, MGC⁺20, MGC⁺21, HIM21, IMS21, IM21, CM21, HII⁺22, IISMS22]$

• Formal explanations efficient for several families of classifiers • Polynomial-time:

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Efficacy map – recent progress $\mathbb{E}[\text{HMOZ}(\mathbb{H})]$

 $[INM19b, Ign20, IIM20, MGC⁺20, MGC⁺21, HIM21, IMS21, IM21, CM21, HII⁺22, IISMS22]$

• Comp. hard, but effective (efficient in practice):

Results for NNs in 2019 (with SMT/MILP) $\frac{1}{\text{[INM19a]}}$

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Results for NNs in 2023 (using Marabou [KHI+19])

Results for NNs in 2023 (using Marabou [KHI+19]) $\frac{[HH]}{[HH]}$

Scales to a few hundred neurons © J. Marques-Silva 24 / 43

More recent results (from 2024)... $\mathbb{I}_{\text{HMM}^+24}$

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Scales to tens of

thousands of neurons!

More recent results (from 2024)... $\lim_{[HM^+24]}$

Scales to tens of thousands of neurons!

Largest for MNIST: 10142 neurons Largest for GSTRB: 94308 neurons

Unit #05

Queries in Symbolic XAI

Outline – Unit #05

Enumeration of Explanations

Feature Necessity & Relevancy

• Goal: iteratively list yet unlisted XPs (either AXp's or CXp's)

• Complexity results:

- For NBCs: enumeration with polynomial delay $W_{\text{MGC}+20}$
- For monotonic classifiers: enumeration is computationally hard M_{MGC+21}
- Recall: for DTs, enumeration of CXp's is in P

HIIM21, IIM22, IIM22]

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- For NBCs: enumeration with polynomial delay $M_{\text{MGC}+20}$
- For monotonic classifiers: enumeration is computationally hard M_{MGC+21}
- Recall: for DTs, enumeration of CXp's is in P [HIIM21, IIM22]

- There are algorithms for direct enumeration of CXp's
	- Akin to enumerating MCSes

• Goal: iteratively list yet unlisted XPs (either AXp's or CXp's)

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Input: Predicate P , parameterized by T , M Output: One XP *S*

- 1: procedure oneXP(**P**)
-
-
- 4: if $\mathbb{P}(\mathcal{S}\backslash\{i\})$ then
5: $\mathcal{S} \leftarrow \mathcal{S}\backslash\{i\}$
-
-

2: $S \leftarrow F$

3: **for** $i \in F$ **do**

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5: $S \leftarrow S \setminus \{i\}$ \triangleright \cup pdate *S* only if $\mathbb{P}(S \setminus \{i\})$ holds 6: **return** *S* \triangleright **Returned set** *S***:** $\mathbb{P}(S)$ **holds**

Generic oracle-based enumeration algorithm

```
Input: Parameters \mathbb{P}_{\text{axp}}, \mathbb{P}_{\text{cxa}}, \mathcal{T}, \mathcal{F}, \kappa, \bf{v}1: \mathcal{H} \leftarrow \emptyset Example 2 \mapsto \mathcal{H} defined on set U = \{u_1, \ldots, u_m\}; initially no constraints
 2: repeat
 3: (outc, u) \leftarrow SAT(H) \leftarrow SAT oracle to pick assignment s.t. known constraints in H \frac{1}{2} if outc = true then
            \mathsf{if} \cap \mathsf{if} \subset \mathsf{tr} \mathsf{if} \mathsf{then}5: S \leftarrow \{i \in \mathcal{F} | u_i = 0\}<br>6: \mathcal{U} \leftarrow \{i \in \mathcal{F} | u_i = 1\}<br>5: \mathcal{U} \leftarrow \{i \in \mathcal{F} | u_i = 1\}6: \mathcal{U} \leftarrow \{i \in \mathcal{F} \mid u_i = 1\}<br>
7: if \mathbb{P}_{\infty}(\mathcal{U}; \mathcal{T}, \mathcal{F}, \kappa, \mathbf{v}) then \triangleright \mathcal{U} = \mathcal{F} \setminus \mathcal{S} \supseteq \text{some } \mathbb{C} \times \mathbb{P}7: if \mathbb{P}_{\text{exp}}(\mathcal{U}; \mathcal{T}, \mathcal{F}, \kappa, \mathbf{v}) then \mathcal{P}_{\leftarrow} one \mathbb{Z}P(\mathcal{U}: \mathbb{P}_{\text{exp}} \mathcal{T})8: \mathcal{P} \leftarrow \text{oneXP}(\mathcal{U}; \mathbb{P}_{\text{Cxp}}, \mathcal{T}, \mathcal{F}, \kappa, \mathbf{v})<br>9. report\text{CKn}(\mathcal{P})9: reportCXp(P)<br>10: H \leftarrow H \cup \{(\}10: \mathcal{H} \leftarrow \mathcal{H} \cup \{(\vee_{i \in \mathcal{P}} \neg u_i)\}\<br>11: else
                                                                                                         P \subseteq U: one 1-value variable must be 0 in future iterations P \subseteq U: one AXD
 11: else \triangleright \mathcal{S} \supseteq some AXp
12: \mathcal{P} \leftarrow \text{oneXP}(\mathcal{S}; \mathbb{P}_{\text{axp}}, \mathcal{T}, \mathcal{F}, \kappa, \mathbf{v})<br>13: report\text{AXn}(\mathcal{P})13: reportAXp(\mathcal{P})<br>14: \mathcal{H} \leftarrow \mathcal{H} \cup \{(\chi) \}\mathcal{H} \leftarrow \mathcal{H} \cup \{(\vee_{i \in \mathcal{P}} u_i)\}P \subseteq S: one 0-value variable must be 1 in future iterations
15: until outc = false
```
DT classifier – example run of enumerator

DT classifier – another example run of enumerator

 \in {

DTs admit more efficient algorithms

- Recall:
	- Given instance (v*, c*), create set *I*
	- For each path P_k with prediction $d \neq c$:
		- \cdot Let I_k denote the features with literals inconsistent with \bf{v} • Add *I^k* to *I*
	- \cdot Remove from $\mathcal I$ the sets that have a proper subset in $\mathcal I$, and duplicates
- \cdot *I* is the set of CXp's algorithm runs in poly-time

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- \cdot *I* is the set of CXp's algorithm runs in poly-time
- For AXp's: run std dualization algorithm [FK96]
	- Obs: starting hypergraph is poly-size!
	- And each MHS is an AXp

DTs admit more efficient algorithms

Outline – Unit #05

Enumeration of Explanations

Feature Necessity & Relevancy

 $[$ HCM $+$ 23]

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 \cdot Given $c \in \mathcal{K}$, CDP is to decide whether the following statement holds:

$$
\exists (\mathbf{x} \in \mathbb{F}).(\kappa(\mathbf{x}) = c)
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 $[HCM+23]$

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$$

• Given $S \subseteq \mathcal{F}$, instance (v, c) , CCDP is to decide whether the following statement holds:

$$
\exists(\mathbf{x}\in\mathbb{F})\ldotp\bigwedge_{i\in\mathcal{S}}(x_i=v_i)\land(\kappa(\mathbf{x})=c)
$$

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• Claim: (C)CDP is in polynomial-time for DTs, decision graphs, monotonic classifiers, among others

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$$

- Claim: (C)CDP is in polynomial-time for DTs, decision graphs, monotonic classifiers, among others
- Claim: (C)CDP is in NP-complete for DLs, RFs, BTs, boolean NNs and BNNs

- Consider instance (v*, c*)
- Sets of all AXp's & CXp's:

 $A \coloneqq \{ \mathcal{X} \subseteq \mathcal{F} \mid A \mathsf{X} \mathsf{p}(\mathcal{X}) \}$ $\mathbb{C} \coloneqq \{ \mathcal{X} \subseteq \mathcal{F} \mid C\mathsf{Xp}(\mathcal{X}) \}$

A: encodes the set of all irreducible rules for prediction *c* given v

- Consider instance (v*, c*)
- Sets of all AXp's & CXp's:

 $\mathbb{A} \coloneqq \{ \mathcal{X} \subseteq \mathcal{F} \mid \mathsf{AXp}(\mathcal{X}) \}$ $\mathbb{C} \coloneqq \{ \mathcal{X} \subseteq \mathcal{F} \mid C\mathsf{Xp}(\mathcal{X}) \}$

A: encodes the set of all irreducible rules for prediction *c* given v

• Features common to all AXps in **A** and all CXps in **C**:

 $N_{\mathbb{A}} := \bigcap_{\mathcal{X} \in \mathbb{A}} \mathcal{X}$ $N_{\mathbb{C}} \coloneqq \bigcap_{\mathcal{X} \in \mathbb{C}} \mathcal{X}$

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More on feature necessity

 $[$ HCM $+$ 23]
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	- Let **u** be obtained from **v** by replacing the constant v_t by some variable $u_t \in \mathcal{D}_t$
	- Feature *t* is AXp-necessary if $\kappa(\mathbf{u}) \neq \kappa(\mathbf{v})$ for some value $u_t \in \mathcal{D}_t$

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- Features 1, 2, 3 are irrelevant, since there are not included in any AXp/CXp
	- Obs: irrelevant features are absolutely unimportant!

We could propose some other explanation by adding features 1, 2 or 3 to AXp $\{4\}$, but prediction would remain unchanged for any value assigned to those features

• And we aim for irreducibility (Occam's razor is a mainstay of AI/ML)

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- General case: best solution is to exploit abstraction refinement

• **Claim**: $\mathcal{X} \subseteq \mathcal{F}$ and $t \in \mathcal{X}$. If WAXp(\mathcal{X}) holds and WAXp($\mathcal{X}\setminus\{t\}$) does not hold, then any $AXp \mathcal{Z} \subseteq \mathcal{X} \subseteq \mathcal{F}$ must contain feature *t*.
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Proof:

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	- Block counterexamples in both cases

Input: Instance v, Target Feature *t*; Feature Set *F*, Classifier *κ*

1: function FRPCGR(**v**, *t*; *F*, *κ*)
2: $\mathcal{H} \leftarrow \emptyset$ 2: $\mathcal{H} \leftarrow \emptyset$ $\Rightarrow \mathcal{H}$ overapproximates the subsets of \mathcal{F} that do not contain an AXp containing *t* **repeat** repeat 4: (OUtc, s) \leftarrow SAT(*H*, *s*_t) \Rightarrow **Dise SAT oracle to pick candidate WAXp containing** *t* $\frac{1}{2}$. $\frac{1}{2}$ if $\frac{1}{2}$ outc = true then 6: *P* Ð t*i* P *F* | *sⁱ* = 1u Ź Set *P* is the candidate WAXp, and *t* P *P* 7: *D* Ð t*i* P *F* | *sⁱ* = 0u Ź Set *D* contains the features not included in *P* 8: **if** \neg WAXp(P) then **Z** Is P not a WAXp? 9: $\mathcal{H} \leftarrow \mathcal{H} \cup \text{newPosCl}(\mathcal{D}; t, \kappa)$ $\triangleright \mathcal{P}$ is *not* a WAXp; must pick some non-picked feature
10: $\triangleright \mathcal{P}$ is a WAXp 10: **else else** \triangleright *P* is a WAXp 11: if \neg WAXp($\mathcal{P}\setminus\{t\}$) then \Rightarrow *P* without *t* not a WAXp?
12: **if** \neg PoportWeakAXb(\mathcal{P}) \Rightarrow Feature *t* is included in any AXb *X* ⊂ *P* 12: reportWeakAXp(\mathcal{P}) \Rightarrow Feature *t* is included in any AXp $\mathcal{X} \subseteq \mathcal{P}$
13: return true 14: $\mathcal{H} \leftarrow \mathcal{H}$ \cup new NegCl(\mathcal{P}, t, κ) \Rightarrow WAXp($\mathcal{P}\setminus\{t\}$) holds; some feature in \mathcal{P} must not be picked $15:$ until outc = false 16: **return false** *c n*

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Another example

- Instance: $(\mathbf{v}, c) = ((1, 1, 1, 1), 1)$
- \cdot Is $t = 4$ relevant?

Questions?

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