LOGIC-BASED EXPLAINABLE ARTIFICIAL INTELLIGENCE

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Lecture 04

- Logic encoding for explaining DLs
	- And status of (in)tractability in logic-based XAI
- Query: enumeration of explanations
- Query: feature necessity, AXp & CXp
- Query: feature relevancy

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	- No! Thus, feature 3 is not AXp-necessary
- Are there CXp-necessary features?
	- No! There are no singleton AXps
- Confirmation:
	- CXps: $\{\{1\}, \{2\}, \{3, 4\}\}$ (2 is also AXp-necessary)
	- \cdot AXps: { $\{1, 2, 3\}, \{1, 2, 4\}$ }

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- Confirmation:
	- AXps: $\{\{1\}, \{2\}, \{3, 4\}\}\$
	- CXps: $\{\{1, 2, 3\}, \{1, 2, 4\}\}\$

• Classifier: $\mathcal{F} = \{1, 2, 3, 4, 5\}$; $\mathcal{D}_i = \{0, 1\}$, $i = 1, \ldots, 5$; $\mathcal{K} = \{0, 1\}$

 κ (*x*₁, *x*₂, *x*₃, *x*₄, *x*₅) :=

 $\int 1$ IF $(10x_1 + 5x_2 + 5x_3 + 2x_4 + x_5 \ge 15)$ 0 otherwise

• Instance: $((1, 1, 1, 1, 1, 1), 1)$

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\kappa(x_1, x_2, x_3, x_4, x_5) \quad := \quad \begin{cases} \ 1 & \text{IF } (10x_1 + 5x_2 + 5x_3 + 2x_4 + x_5 \geq 15) \\ \ 0 & \text{otherwise} \end{cases}
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• Decide feature necessity

Q: What can we do if human decision maker finds computed AXp/CXp to be unsatisfactory?

• Partially enumerate AXps/CXps, exploiting bias in enumeration

- \cdot Lecture 01 units:
	- #01: Foundations
- \cdot Lecture 02 units:
	- #02: Principles of symbolic XAI feature selection
	- #03: Tractability in symbolic XAI (& myth of interpretability)
- \cdot Lecture 03 units:
	- #04: Intractability in symbolic XAI (& myth of model-agnostic XAI)
	- #05: Explainability queries
- \cdot Lecture 04 units:
	- #06: Advanced topics
- Lecture 05 units:
	- #07: Principles of symbolic XAI feature attribution (& myth of Shapley values in XAI)
	- #08: Conclusions & research directions

Detour: Monotonic Classification & Voting Power

- Monotonic classifier $M = (\mathcal{F}, \mathbb{F}, \mathcal{K}, \kappa)$, such that each $\mathcal{D}_i = \{0, 1\}$ and $\mathcal{K} = \{0, 1\}$ are ordered (i.e. $0 < 1$), and
	- \cdot *κ*(1) = 1 ;
	- Non-constant classifier, i.e. $\kappa(0) = 0$; and
	- \cdot $\kappa(\mathbf{x}_1) \leqslant \kappa(\mathbf{x}_2)$ when $\mathbf{x}_1 \leqslant \mathbf{x}_2$

- Monotonic classifier $\mathcal{M} = (\mathcal{F}, \mathbb{F}, \mathcal{K}, \kappa)$, such that each $\mathcal{D}_i = \{0, 1\}$ and $\mathcal{K} = \{0, 1\}$ are ordered (i.e. $0 < 1$), and
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- Let $\mathbf{v}_1, \mathbf{v}_2 \in \mathbb{F}$ be such that $\kappa(\mathbf{v}_1) = \kappa(\mathbf{v}_2) = 1$, and $\mathbf{v}_1 \leq \mathbf{v}_2$ Define the explanation problems:
	- $\cdot \mathcal{E}_1 = (\mathcal{M}, (\mathbf{v}_1, 1))$
	- $\cdot \mathcal{E}_2 = (\mathcal{M}, (\mathbf{v}_2, 1))$
	- $\mathcal{E}_1 = (\mathcal{M}, ((1, \ldots, 1), 1)) = (\mathcal{M}, (1, 1))$

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	- \cdot $\kappa(1) = 1$:
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- Let $\mathbf{v}_1, \mathbf{v}_2 \in \mathbb{F}$ be such that $\kappa(\mathbf{v}_1) = \kappa(\mathbf{v}_2) = 1$, and $\mathbf{v}_1 \leq \mathbf{v}_2$ Define the explanation problems:
	- $\cdot \mathcal{E}_1 = (\mathcal{M}, (\mathbf{v}_1, 1))$
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	- $\mathcal{E}_{\mathbb{1}} = (\mathcal{M}, ((1, \ldots, 1), 1)) = (\mathcal{M}, (1, 1))$
- Then,
	- If WAXp $(S; \mathcal{E}_1)$ holds, then WAXp $(S; \mathcal{E}_2)$ holds; in particular:
	- \cdot A(\mathcal{E}_1) contains all the AXps of any instance of the form $(\mathbf{v}_r, 1)$
		- Why?
			- \cdot Pick any explanation problem \mathcal{E}_r with instance (\mathbf{v}_r , 1)
			- \cdot Start from $1 = (1, 1, \ldots, 1)$
			- \cdot Remove features that take value 0 in v_r ; we still have an WAXp
			- \cdot Then compute any AXp starting from features taking value 1 in \mathbf{v}_r
			- \therefore Suffices to find explanations for $\mathcal{E}_\mathbf{1}$ (or alternatively, the global explanations for prediction 1)

- ML model $M = (\mathcal{F}, \mathbb{F}, \mathcal{K}, \kappa)$:
	- Boolean classifier: $K = \{0, 1\}$
	- Defined on 6 boolean features: $\mathcal{F} = \{1, 2, 3, 4, 5, 6\}$
		- I.e. $\mathcal{D}_i = \{0, 1\}, i = 1, \ldots, 6$
	- With classification function:

$$
\kappa(x_1, x_2, x_3, x_4, x_5, x_6) \quad := \quad \begin{cases} \ 1 & \text{if } (4x_1 + 4x_2 + 4x_3 + 2x_4 + 2x_5 + x_6 \geqslant 12) \\ \ 0 & \text{otherwise} \end{cases}
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		- Feature 6: can be dropped
		- AXp: $\{2, 3, 4, 5\}$; **Q**: Is feature 6 relevant?

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- Instance: $(1,1)$
- Computing the AXps:
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\mathbb{C} = \{ \{1, 2\}, \{1, 3\}, \{2, 3\}, \{1, 4\}, \{1, 5\}, \{2, 4\}, \{2, 5\}, \{3, 4\}, \{3, 5\} \}
$$

• General set-up of weighted voting games:

What is a priori voting power?

- General set-up of weighted voting games:
	- Assembly A of voters, with $m = |A|$
	- \cdot Each voter *i* \in *A* votes Yes with *n_i* votes; otherwise no votes are counted (and he/she votes No)
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	- Quota *q* is the sum of votes required for a proposal to be approved
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	- A weighted voting game (WVG) is a tuple $[q; n_1, \ldots, n_m]$
		- Example: [12; 4*,* 4*,* 4*,* 2*,* 2*,* 1]
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	- A weighted voting game (WVG) is a tuple $[q; n_1, \ldots, n_m]$
		- Example: [12; 4*,* 4*,* 4*,* 2*,* 2*,* 1]
	- Problem: find a measure of importance of each voter !
		- I.e. measure the a priori voting power of each voter

• WVG: $[12; 4, 4, 4, 2, 2, 1]$

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- Can Luxembourg (L) *matter* for some winning coalition?

- WVG: $[12; 4, 4, 4, 2, 2, 1]$
- Q: What should be the voting power of Luxembourg?
- Can Luxembourg (L) *matter* for some winning coalition?
- Perhaps surprisingly, answer is **No!**
	- In 1958, Luxembourg was a dummy voter/player

Understanding weighted voting games

- Obs: A WVG is a monotonically increasing boolean classifier
- Each subset-minimal winning coalition is an AXp of the instance (**1***,* 1)

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• The corresponding classifier is:

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which we have seen before! E.g. $\{2, 3, 4, 5\}$ is an AXp & feature 6 (L) is irrelevant

 \cdot WVG: [21; 12, 9, 4, 4, 1, 1, 1]

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- Computing the AXps:
	- Must include feature 1; sum of weights of others equals 20...
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• Q: How should features be ranked in terms of importance?

• WVG: [16; 9, 9, 7, 3, 1, 1]

- \cdot WVG: [16; 9, 9, 7, 3, 1, 1]
- Computing the AXps:
	- Sum of any pair of the first three features (i.e. voters) exceeds/matches the quota
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• SHAP scores, i.e. the use of Shapley values for XAI, exhibit critical theoretical flaws **(MORE TOMORTOW)** [MSH24, HMS24, HM23b]

• Recently, we have devised ways of **correcting** SHAP scores **Example 24 IDEN 240** [LHMS24]

Unit #06

Advanced Topics

General definition of prediction sufficiency

- \cdot Instance (\mathbf{v}, c)
- Let $S \subset \mathcal{F}$:
	- Recall,

$$
\Upsilon(\mathcal{S};v) = \{x \in \mathbb{F} \mid x_{\mathcal{S}} = v_{\mathcal{S}}\}
$$

 \cdot *S* \subseteq *F* suffices for prediction *c* if:

$$
\forall (x \in \mathbb{F}). (x \in \Upsilon(\mathcal{S}; v)) \rightarrow (\sigma(x))
$$

- Obs: a WAXp is just one possible example
- But there are other ways to study prediction sufficiency:
	- \cdot One can envision defining other sets of points Γ, parameterized by $\mathcal{E} = (\mathcal{M}, (\mathbf{v}, c))$; $S \subseteq F$ suffices for prediction *c* if:

$$
\forall (x\in\mathbb{F}).(x\in\Gamma(\mathcal{S};\mathcal{E}))\!\rightarrow\!(\sigma(x))
$$

• And one can also envision generalizations of *σ*!

Outline – Unit #06

Changing Assumptions

Inflated Explanations

Probabilistic Explanations

Constrained Explanations

Distance-Restricted Explanations

Additional Topics

Towards more expressive explanations – inflated explanations

[IISM24]

• Recall:

$$
WAXp(\mathcal{X}) \quad := \quad \forall (\mathbf{x} \in \mathbb{F}). \bigwedge\nolimits_{j \in \mathcal{X}} (x_j = v_j) \rightarrow (\kappa(\mathbf{x}) = c)
$$

 \cdot For non-boolean features, use of $=$ may convey little information, e.g. with real-valued features, having *x*¹ = 1*.*157 does not help in understanding what values of feature 1 are also acceptable

Towards more expressive explanations – inflated explanations

[IISM24]

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- \cdot For non-boolean features, use of $=$ may convey little information, e.g. with real-valued features, having *x*¹ = 1*.*157 does not help in understanding what values of feature 1 are also acceptable
- \cdot Inflated explanations allow for more expressive literals, i.e. = replaced with ϵ , and individual values replaced by ranges of values
	- Operational definition: Given an AXp, expand set of values of each feature, in some chosen order, such that the set of picked features remains unchanged

Inflated explanations – an example

[IIM22]

Inflated explanations – an example

[IIM22]

• Explanation for $((2, 20, 0), Y)$? (Obs: MnA = 18; MxP > 4) • AXp: ${1, 2}$
[IIM22]

- AXp: {1, 2}
- Default interpretation:

$$
\forall (\mathbf{x} \in \mathbb{F}).(\mathbf{x}_1 = 2 \land \mathbf{x}_2 = 20) \rightarrow (\kappa(\mathbf{x}) = \mathbf{Y})
$$

 x_2

3

N

5

 \equiv {26..MxA}

Y

7

 $\{1\}$

*x*1

 \in {4*..*MxP} $\left\{ \begin{array}{c} 1 \\ 1 \end{array} \right\}$ \in {0*..*3}

*x*3

4

 ${0, 1}$

 \in {MnA..25}

 $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

6

 $\in \{0\}$

 $\frac{Y}{2}$

Y N

8 9

[IIM22]

- Explanation for $((2, 20, 0), Y)$? (Obs: MnA = 18; MxP > 4)
	- AXp: {1, 2}
	- Default interpretation:

 \forall ($\mathbf{x} \in \mathbb{F}$).($x_1 = 2 \land x_2 = 20$) \rightarrow ($\kappa(\mathbf{x}) = \forall$)

• Corresponding rule:

IF $(x_1 = 2 \land x_2 = 20)$ THEN $(\kappa(\mathbf{x}) = Y)$

*x*1

 \boxed{Y} $\boxed{x_2}$

 \in {4*..*MxP} $\left\langle \begin{array}{c} 1 \\ 0.3 \end{array} \right\rangle$

*x*3

4

 \in {MnA..25}

 \boxed{Y}

7

 $\{1\}$

3

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 \equiv {26..MxA}

 $\overline{\mathsf{N}}$

 ${0, 1}$

 (x_1)

6

8 9

 $\in \{0\}$

[IIM22]

- Explanation for $((2, 20, 0), Y)$? (Obs: MnA = 18; MxP > 4)
	- AXp: ${1, 2}$
	- Default interpretation:

 \forall ($\mathbf{x} \in \mathbb{F}$).($x_1 = 2 \land x_2 = 20$) \rightarrow ($\kappa(\mathbf{x}) = \forall$)

• Corresponding rule:

IF $(x_1 = 2 \land x_2 = 20)$ THEN $(\kappa(\mathbf{x}) = Y)$

• With inflated explanations:

 \forall ($\mathbf{x} \in \mathbb{F}$).($x_1 \in \{2..MxP\} \land x_2 \in \{MnA..25\}$) \rightarrow ($\kappa(\mathbf{x}) = Y$)

[IIM22]

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• With inflated explanations:

 $\forall (x \in \mathbb{F}) \ldotp (x_1 \in \{2 \ldotp \mathsf{M} \mathsf{x} \mathsf{P}\} \land x_2 \in \{\mathsf{MnA}..25\}) \rightarrow (\kappa(\mathbf{x}) = \mathsf{Y})$

• Corresponding rule:

IF ($x_1 \in \{2..MxP\} \land x_2 \in \{MnA..25\}$) THEN ($\kappa(\mathbf{x}) = Y$)

- Compute AXp *X*
- For each feature:
	- Categorical: iteratively add elements to literal
	- Ordinal:
		- Expand literal for larger values;
		- Expand literal for smaller values
- Compute AXp *X*
- For each feature:
	- Categorical: iteratively add elements to literal
	- Ordinal:
		- Expand literal for larger values;
		- Expand literal for smaller values
- Obs: More complex alternative is to find AXp and expand domains simultaneously
	- This is conjectured to change the complexity class of finding one explanation

Outline – Unit #06

Changing Assumptions

Inflated Explanations

Probabilistic Explanations

Constrained Explanations

Distance-Restricted Explanations

Additional Topics

Probabilistic (formal) explanations

 $[WMHK21, IIN+22, IHI+22, ABOS22, IHI+23, IMM24]$ • Explanation size is critical for human understanding \blacksquare • Probabilistic explanations provide smaller explanations, by trading off rigor of explanation by explanation size

Probabilistic (formal) explanations

 $[WMHK21, 11N+22, 1H1+22, ABOS22, 1H1+23, 1MM24]$

• Explanation size is critical for human understanding **Explanation State Industry** [Mil56]

- Probabilistic explanations provide smaller explanations, by trading off rigor of explanation by explanation size
- Definition of weak probabilistic AXp $X \subseteq \mathcal{F}$:

 $WPAXp(X) \equiv Pr(\kappa(\mathbf{x}) = c) | \mathbf{x}_{\mathcal{X}} = \mathbf{v}_{\mathcal{X}}) \geq \delta$

- Obs: $x_x = v_x$ requires points $x \in \mathbb{F}$ to match the values of v for the features dictated by X
- Obs: for $\delta = 1$ we obtain a WAXp

• Weak probabilistic AXp (WPAXp):

$$
\text{WeakPAXp}(\mathcal{X}; \mathbb{F}, \kappa, \mathbf{v}, c, \delta) :=
$$
\n
$$
\text{Pr}_{\mathbf{x}}(\kappa(\mathbf{x}) = c \mid \mathbf{x}_{\mathcal{X}} = \mathbf{v}_{\mathcal{X}}) \geq \delta := \frac{|\{\mathbf{x} \in \mathbb{F} : \kappa(\mathbf{x}) = c \land (\mathbf{x}_{\mathcal{X}} = \mathbf{v}_{\mathcal{X}})\}|}{|\{\mathbf{x} \in \mathbb{F} : (\mathbf{x}_{\mathcal{X}} = \mathbf{v}_{\mathcal{X}})\}|} \geq \delta
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$$

• Probabilistic AXp (PAXp):

 $PAXp(X; \mathbb{F}, \kappa, \mathbf{v}, \mathbf{c}, \delta) :=$ W eakPAXp $(\mathcal{X}; \mathbb{F}, \kappa, \mathbf{v}, \mathsf{c}, \delta) \wedge \forall (\mathcal{X}' \subsetneq \mathcal{X})$. \neg WeakPAXp $(\mathcal{X}'; \mathbb{F}, \kappa, \mathbf{v}, \mathsf{c}, \delta)$

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• Locally-minimal PAXp (LmPAXp):

 $LmPAXp(X;F,\kappa,\mathbf{v},\mathcal{C},\delta) :=$ W eakPAXp(\mathcal{X} ; \mathbb{F}, κ , \mathbf{v}, c, δ) $\wedge \forall (j \in \mathcal{X})$. \neg WeakPAXp($\mathcal{X}\backslash\{j\}$; \mathbb{F}, κ , \mathbf{v}, c, δ)

• Weak probabilistic AXp (WPAXp): \overline{a} effinition is non-monotonic

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\text{WeakPAXp}(\mathcal{X}; \mathbb{F}, \kappa, \mathbf{v}, c, \delta) :=
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\n
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• Probabilistic AXp (PAXp):

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• Locally-minimal PAXp (LmPAXp): – may differ from PAXp due to non-monotonicity $LmPAXp(X;F,\kappa,\mathbf{v},\mathcal{C},\delta) :=$ W eakPAXp(\mathcal{X} ; \mathbb{F}, κ , $\mathbf{v}, \mathcal{C}, \delta$) $\wedge \forall (i \in \mathcal{X})$. WeakPAXp($\mathcal{X}\backslash\{i\}$; \mathbb{F}, κ , $\mathbf{v}, \mathcal{C}, \delta$)

• Obs: Definition of WPAXp is non-monotonic (from previous slide)

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	- For DTs, finding on PAXp is computationally hard $[ABOS22]$

- Obs: Definition of WPAXp is non-monotonic (from previous slide)
	- Standard algorithms for finding one AXp cannot be used
	- For DTs, finding on PAXp is computationally hard $[ABOS22]$ • In general, complexity is unwiedly **complexity** $\frac{1}{2}$ [WMHK21]

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Results for decision trees

Results for naive Bayes classifiers

Results for decision diagrams

Remarks on LmPAXps

- LmPAXps ignore non-monotonicity, and so overapproximate PAXps • Theoretical guarantees, but may be reducible
- For DTs, computation of LmPAXps is in P
- Experimental results confirm LmPAXps match PAXps in most cases
- Recent results on approximating LmPAXps for RFs **EXAPC 2018 12 (IMM24]**

Outline – Unit #06

Changing Assumptions

Inflated Explanations

Probabilistic Explanations

Constrained Explanations

Distance-Restricted Explanations

Additional Topics

 $[GR22, YIS+23]$

• The (implicit) assumption that all inputs are possible is often unrealistic

• I.e. it may be impossible for some points in feature space to be observed

 $[GR22, Y1S+23]$

- The (implicit) assumption that all inputs are possible is often unrealistic
	- I.e. it may be impossible for some points in feature space to be observed
- Infer constraints on the inputs
	- Learn simple rules relating inputs
	- Represent rules as a constraint set, e.g. *C*(x)

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- Redefine WAXps/WCXps to account for input constraints:

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\forall (\mathbf{x} \in \mathbb{F}). \left[\bigwedge_{j \in \mathcal{X}} (\mathsf{x}_j = \mathsf{v}_j) \land \mathcal{C}(\mathbf{x}) \right] \to (\kappa(\mathbf{x}) = \mathsf{c})
$$

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\exists (\mathbf{x} \in \mathbb{F}). \left[\bigwedge_{j \in \mathcal{X}} (\mathsf{x}_j = \mathsf{v}_j) \land \mathcal{C}(\mathbf{x}) \right] \land (\kappa(\mathbf{x}) \neq \mathsf{c})
$$

• Compute AXps/CXps given new definitions

 $[GR22, Y1S+23]$

- The (implicit) assumption that all inputs are possible is often unrealistic
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$$

- Compute AXps/CXps given new definitions
- Constrained AXps/CXps find other applications!
- Instance: $((1, 1, 1, 1), 1)$
- Unconstrained AXps:

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	- AXps: $\{\{1\}, \{2\}, \{3, 4\}\}\$

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	- If feature 3 is fixed (with value 1), then feature 4 must be assigned value 1

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- Instance: $((1, 1, 1, 1), 1)$
- Unconstrained AXps:
	- AXps: $\{\{1\}, \{2\}, \{3, 4\}\}\$
- Constrained AXps:
	- \cdot If feature 3 is fixed (with value 1), then feature 4 must be assigned value 1
	- If feature 4 is fixed (with value 1), then feature 3 must be assigned value 1
	- AXps: $\{\{1\}, \{2\}, \{3\}, \{4\}\}\$

• Constraint: $\{(x_3 \rightarrow x_4), (x_4 \rightarrow x_3)\}$

Outline – Unit #06

Changing Assumptions

Inflated Explanations

Probabilistic Explanations

Constrained Explanations

Distance-Restricted Explanations

Additional Topics

• For NNs, computation of plain AXps scales to a few tens of neurons [INM19a]

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- But, robustness tools scale for much larger NNs

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	- Q: can we relate AXps with adversarial examples?

- For NNs, computation of plain AXps scales to a few tens of neurons **[INM19a]** • But, robustness tools scale for much larger NNs • Q: can we relate AXps with adversarial examples? • Obs: we already proved some basic (duality) properties for global explanations [[INM19b] \cdot Change definition of WAXp/WCXp to account for l_p distance to v: \forall (**x** \in **F**). \bigwedge $\int_{\mathcal{F}} f(x_j = v_j) \wedge (||\mathbf{x} - \mathbf{v}||) \leq \epsilon)$ $\left[\rightarrow (\sigma(\mathbf{x})) \right]$ \exists (**x** \in **F**). \bigwedge $\mathbf{y}_{j\in\mathcal{X}}(x_j = v_j) \wedge (\|\mathbf{x} - \mathbf{v}\|_{l_p} \leqslant \epsilon) \mathbf{0} \wedge (\neg \sigma(\mathbf{x}))$
	- Norm *l^p* is arbitrary, e.g. Hamming, Manhattan, Euclidean, etc.
	- Distance-restricted explanations: 0AXp/0CXp

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An example – DT & instance ((1*,* 1*,* 1*,* 1)*,* 1)

• Plain AXps/CXps:

- Plain AXps/CXps:
	- AXps?

- Plain AXps/CXps:
	- \cdot AXps? {{1, 3, 4}, {2, 3, 4}}
	- CXps?

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- Distance-restricted AXps/CXps, 0AXp/0CXp, with Hamming distance (l_0) and $\epsilon = 1$:

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- Distance-restricted AXps/CXps, 0AXp/0CXp, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:

t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- Distance-restricted AXps/CXps, 0AXp/0CXp, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:
		- t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u
	- dAXps?

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- \cdot Distance-restricted AXps/CXps, ∂ AXp/ ∂ CXp, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:
		- t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u
	- \cdot ∂ AXps? {{3, 4}}
	- dCXps?

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- \cdot Distance-restricted AXps/CXps, ∂ AXp/ ∂ CXp, with Hamming distance (l_0) and $\epsilon = 1$:
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		- t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u
	- \cdot **dAXps?** {{3, 4}}
	- \cdot ∂ CXps? {{3}, {4}}

- Plain AXps/CXps:
	- AXps? $\{\{1, 3, 4\}, \{2, 3, 4\}\}\$
	- CXps? $\{\{1, 2\}, \{3\}, \{4\}\}\$
- \cdot Distance-restricted AXps/CXps, $\partial A Xp / \partial C Xp$, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:
		- t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u
	- \cdot ∂ AXps? {{3, 4}}
	- \cdot ∂ CXps? {{3}, {4}}

• Given *ϵ*, larger adversarial examples are excluded

Another example – DT & instance $((1, 1, 1, 1), 1)$

• Plain AXps/CXps:

- Plain AXps/CXps:
	- AXps?

- Plain AXps/CXps:
	- AXps? $\{\{1\}, \{2\}\{3, 4\}\}\$
	- CXps?

- Plain AXps/CXps:
	- AXps? $\{\{1\}, \{2\}\{3, 4\}\}\$
	- \cdot CXps? {{1, 2, 3}, {1, 2, 4}}

- Plain AXps/CXps:
	- AXps? $\{\{1\}, \{2\}\{3, 4\}\}\$
	- CXps? $\{\{1, 2, 3\}, \{1, 2, 4\}\}\$

- Distance-restricted AXps/CXps, dAXp/dCXp, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:

t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u

- Plain AXps/CXps:
	- AXps? $\{\{1\}, \{2\}\{3, 4\}\}\$
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- \cdot Distance-restricted AXps/CXps, ∂ AXp/ ∂ CXp, with Hamming distance (l_0) and $\epsilon = 1$:
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	- Constant function...

- Plain AXps/CXps:
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	- Constant function...
	- dAXps?

- Plain AXps/CXps:
	- AXps? $\{\{1\}, \{2\}\{3, 4\}\}\$
	- \cdot CXps? { $\{1, 2, 3\}, \{1, 2, 4\}$ }

- \cdot Distance-restricted AXps/CXps, ∂ AXp/ ∂ CXp, with Hamming distance (l_0) and $\epsilon = 1$:
	- Points of interest:

t(1*,* 1*,* 1*,* 1)*,*(0*,* 1*,* 1*,* 1)*,*(1*,* 0*,* 1*,* 1)*,*(1*,* 1*,* 0*,* 1)*,*(1*,* 1*,* 1*,* 0)u

- Constant function...
- \cdot dAXps? $\{\emptyset\}$

• Distance-restricted WAXps/WCXps:

$$
\forall (\mathbf{x} \in \mathbb{F}). \left[\bigwedge_{j \in \mathcal{X}} (x_j = v_j) \land (\|\mathbf{x} - \mathbf{v}\|_{l_p} \leq \epsilon) \right] \rightarrow (\sigma(\mathbf{x}))
$$

$$
\exists (\mathbf{x} \in \mathbb{F}). \left[\bigwedge_{j \in \mathcal{X}} (x_j = v_j) \land (\|\mathbf{x} - \mathbf{v}\|_{l_p} \leq \epsilon) \right] \land (\neg \sigma(\mathbf{x}))
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$$

- Given norm *l^p* and distance *ϵ*, there exists a (distance-restricted) WCXp iff there exists an adversarial example
	- Use robustness tool to decide existence of WCXp
	- But, WAXp decided given non existence of CXp!

• Distance-restricted WAXps/WCXps:

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	- Use robustness tool to decide existence of WCXp
	- But, WAXp decided given non existence of CXp!
- Efficiency of distance-restricted explanations correlates with efficiency of finding adversarial examples
	- One can use most complete robustness tools, e.g. VNN-COMP $[{\text{\tiny{BMB}}+23}]$

• Distance-restricted WAXps/WCXps:

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\forall (\mathbf{x} \in \mathbb{F}). \left[\bigwedge_{j \in \mathcal{X}} (x_j = v_j) \land (\|\mathbf{x} - \mathbf{v}\|_{l_p} \leq \epsilon) \right] \rightarrow (\sigma(\mathbf{x}))
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• Given norm *l^p* and distance *ϵ*, there exists a (distance-restricted) WCXp iff there exists an adversarial example

• Use robustness tool to decide existence of WCXp

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- Efficiency of distance-restricted explanations correlates with efficiency of finding adversarial examples
	- One can use most complete robustness tools, e.g. VNN-COMP $_{[BMB^+23]}$

• Clear scalability improvements for explaining NNs (see next) [HM23a, WWB23, IHM+24a, IHM+24b]

$\textbf{Basic algorithm} \begin{picture}(10,10) \put(0,0){\vector(1,0){100}} \put(0$

$\textbf{Basic algorithm}$ and $\textbf{H}_{\text{H}_{\text{M}_{\text{M}_{\text{M}_{\text{M}_{\text{M}_{\text{M}}}}}}}$

• Obs: Efficiency of logic-based XAI tracks efficiency of robustness tools

$\textbf{Basic algorithm}$ and $\textbf{H}_{\text{H}_{\text{M}_{\text{M}_{\text{M}_{\text{M}_{\text{M}_{\text{M}}}}}}}$

- Obs: Efficiency of logic-based XAI tracks efficiency of robustness tools
- Limitation: Running time grows with number of features

Results for NNs in 2023 (using Marabou [KHI+19]) \blacksquare

Results for NNs in 2023 (using Marabou [KHI+19]) \blacksquare

Scales to a few hundred neurons
Recent improvements

Input: Arguments: *ϵ*; Parameters: *E*, *p* Output: One dAXp *S*

- 1: **function** FindAXpDel(ϵ ; \mathcal{E} , p)
2: $\mathcal{S} \leftarrow \mathcal{F}$
-
-
- $S \leftarrow S \setminus \{i\}$
- 5: outc ← FindAdvEx(ϵ , S ; E , p)
6: **if** outc **then**
- if outc then
- 7: $S \leftarrow S \cup \{i\}$
-

2: $S \leftarrow \mathcal{F}$
3: **for** $i \in \mathcal{F}$ **do**
3: **for** $i \in \mathcal{F}$ **do** 3: for $i \in \mathcal{F}$ do \Rightarrow Invariant: $\partial \mathsf{WAXp}(\mathcal{S})$
4: $\mathcal{S} \leftarrow \mathcal{S}\backslash\{i\}$

8: return *S* $\Rightarrow \text{dWAXp}(\mathcal{S}) \land \text{minimal}(\mathcal{S}) \rightarrow \text{dXp}(\mathcal{S})$

Recent improvements

Input: Arguments: *ϵ*; Parameters: *E*, *p* Output: One dAXp *S* 1: **function** FindAXpDel(ϵ ; \mathcal{E} , p)
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3: **for** $i \in F$ **do**
3: **for** *F* **do** 3: for $i \in \mathcal{F}$ do \Rightarrow Invariant: $\partial \mathsf{WAXp}(\mathcal{S})$
4: $\mathcal{S} \leftarrow \mathcal{S}\backslash\{i\}$ $S \leftarrow S \setminus \{i\}$ 5: outc ← FindAdvEx(ϵ , S ; E , p)
6: **if** outc **then** if outc then 7: $S \leftarrow S \cup \{i\}$ 8: return *S* $\Rightarrow \text{dWAXp}(\mathcal{S}) \land \text{minimal}(\mathcal{S}) \rightarrow \text{dXp}(\mathcal{S})$ • To drop features from $S \subseteq \mathcal{F}$, it is open whether paralellization might be applicable • Algorithm FindAXpDel is mostly sequential (see above)

• Exploit parallelization for other algorithms, e.g. dichotomic search $[HM+24b]$

Recent improvements

More recent results (from 2024)... More and More and More Mone Mone

More recent results (from 2024)... $\frac{1}{\text{min} + 24a, \text{lim} + 24b}$

Scales to tens of

thousands of neurons!

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Scales to tens of thousands of neurons!

Largest for MNIST: 10142 neurons Largest for GSTRB: 94308 neurons

Outline – Unit #06

Changing Assumptions

Inflated Explanations

Probabilistic Explanations

Constrained Explanations

Distance-Restricted Explanations

Additional Topics

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- Report computed explanation as explanation for the complex ML model

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Plan for this course – light at the end of the tunnel...

- Lecture 01 units:
	- #01: Foundations
- \cdot Lecture 02 units:
	- #02: Principles of symbolic XAI feature selection
	- #03: Tractability in symbolic XAI (& myth of interpretability)
- \cdot Lecture 03 units:
	- #04: Intractability in symbolic XAI (& myth of model-agnostic XAI)
	- #05: Explainability queries
- \cdot Lecture 04 units:
	- #06: Advanced topics
- Lecture 05 units:
	- #07: Principles of symbolic XAI feature attribution (& myth of Shapley values in XAI)
	- #08: Conclusions & research directions

Questions?

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