

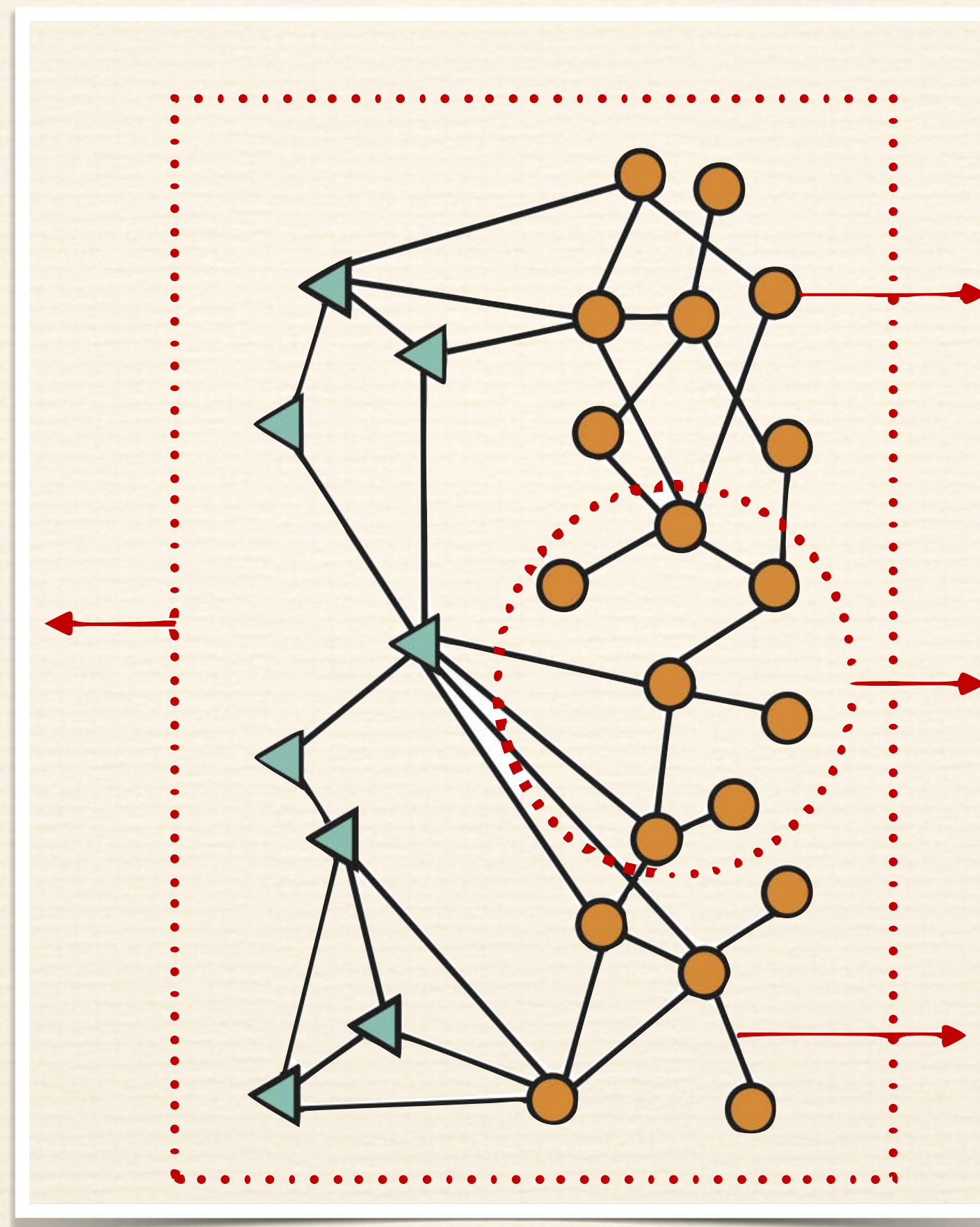
The Power of Graph Learning

Floris Geerts (University of Antwerp, Belgium)

Graph learning

Prediction and classification problems on graphs

Graph level



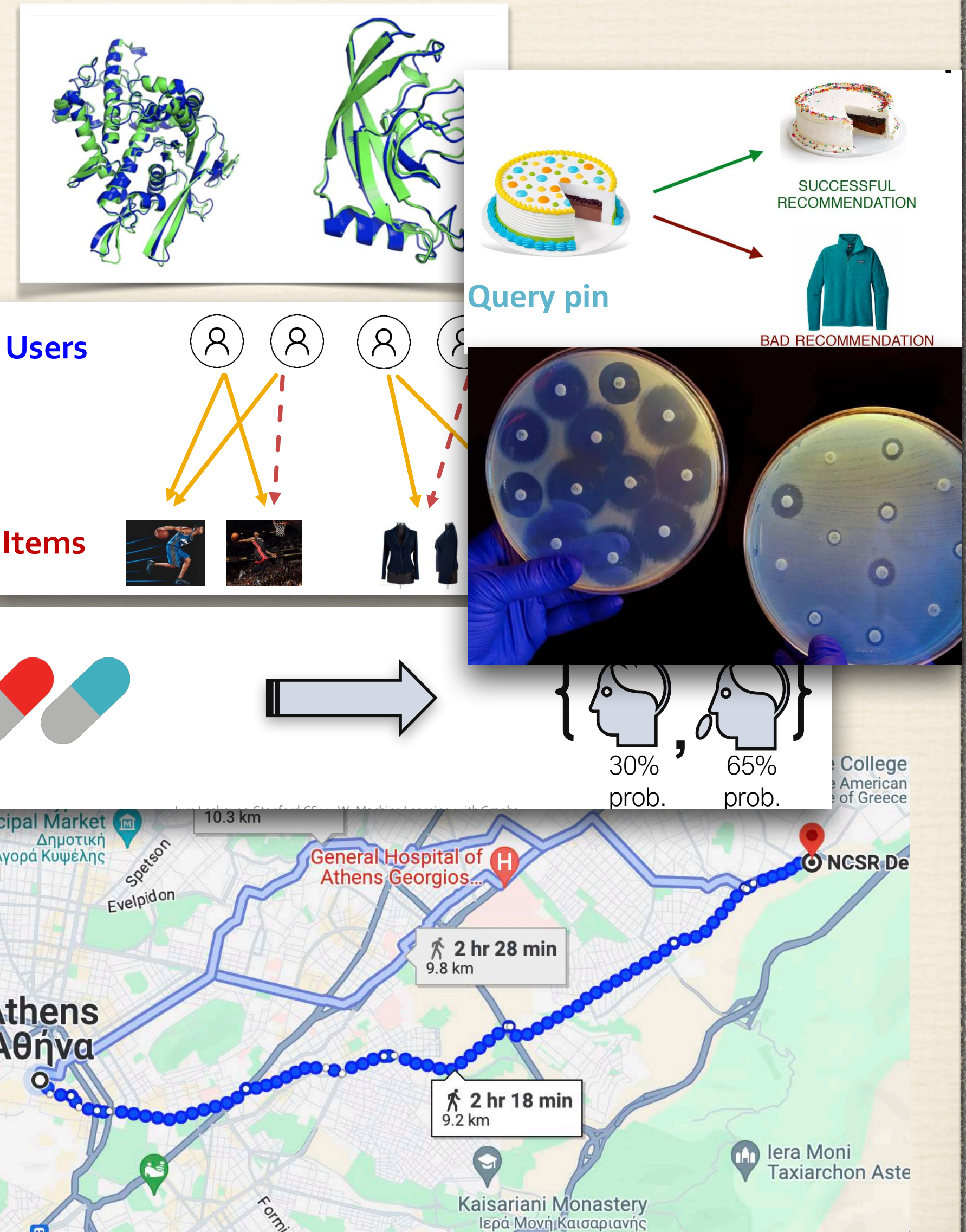
Vertex level

Subgraph level

Edge/link level

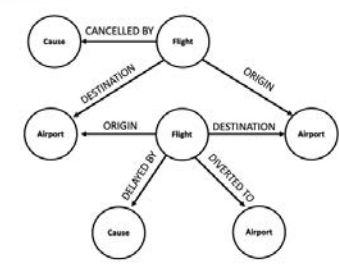
Examples

- ❖ **Vertex classification:** categorise online user/items, location amino acids (protein folding, alpha fold)
- ❖ **Link prediction:** knowledge graph completion, recommender systems, drug side effect discovery
- ❖ **Graph classification:** molecule property, drug discovery
- ❖ **Subgraph tasks:** traffic prediction

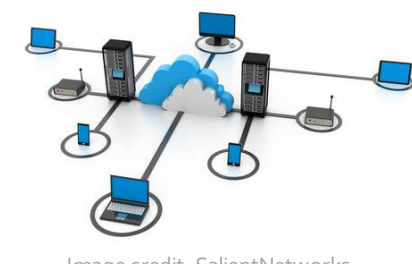


Why learning on graphs?

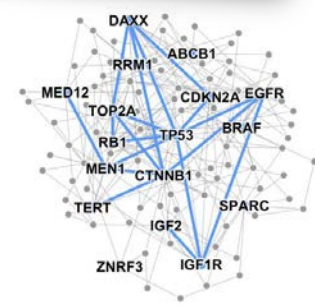
Graphs are everywhere!



Event Graphs



Computer Networks



Disease Pathways

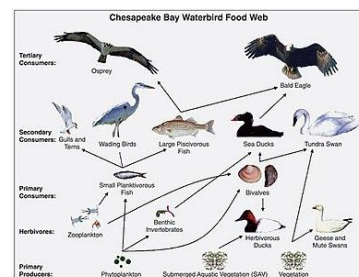


Image credit: Wikipedia

Food Webs



Image credit: Pinterest

Particle Networks



Image credit: visitlondon.com

Underground Networks



Image credit: Medium

Social Networks

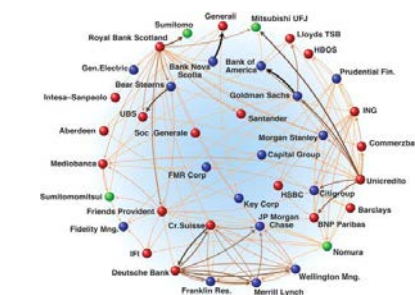


Image credit: Science

Economic Networks



Image credit: Lumen Learning

Communication Networks



Citation Networks



Image credit: Missoula Current News

Internet

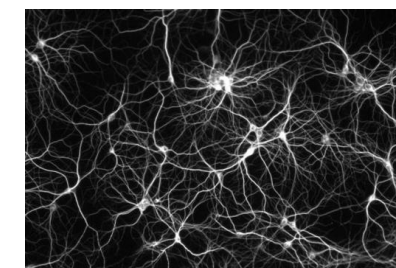


Image credit: The Conversation

Networks of Neurons

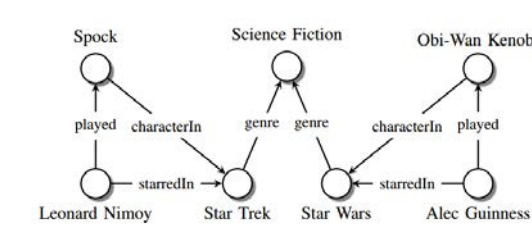


Image credit: Maximilian Nickel et al

Knowledge Graphs

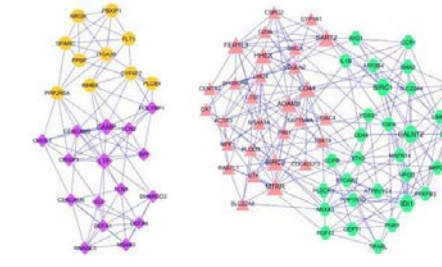


Image credit: ese.wustl.edu

Regulatory Networks

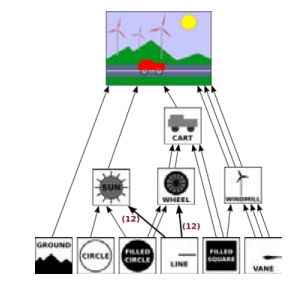


Image credit: math.hws.edu

Scene Graphs

Image credit: ResearchGate

Code Graphs

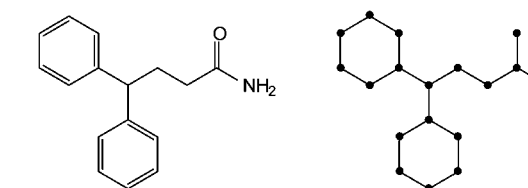


Image credit: MDPI

Molecules

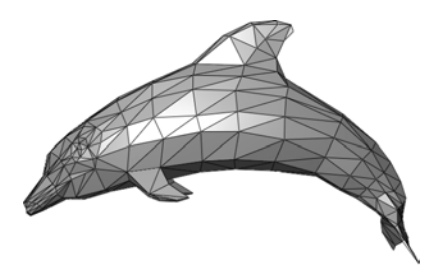


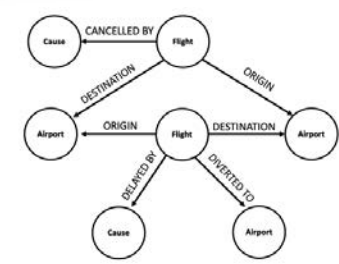
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3D Shapes

Graph learning methods are thus widely applicable

Why learning on graphs?

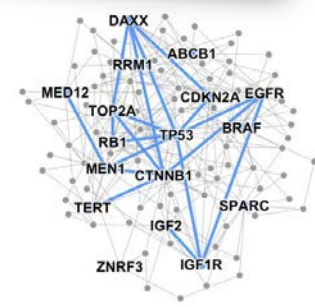
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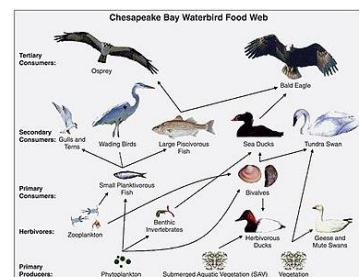


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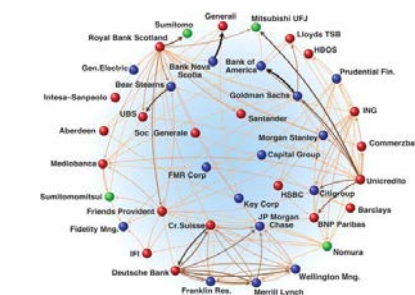


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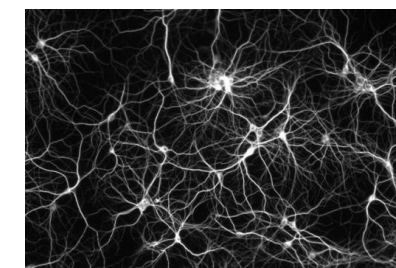


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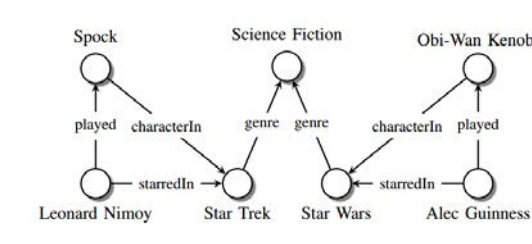


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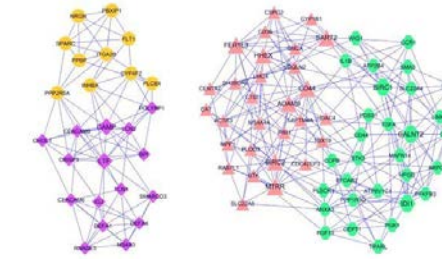


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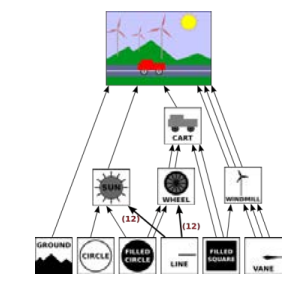


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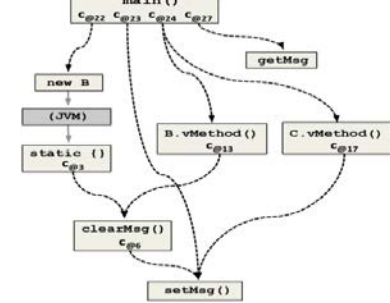


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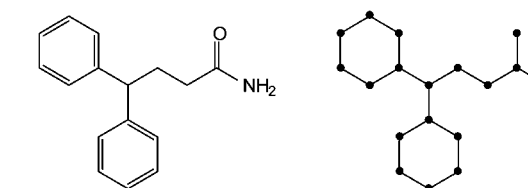


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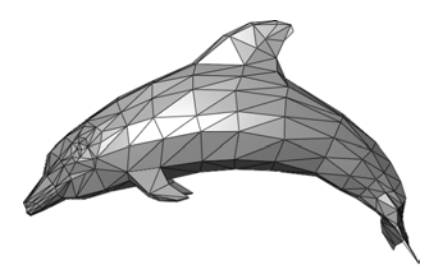


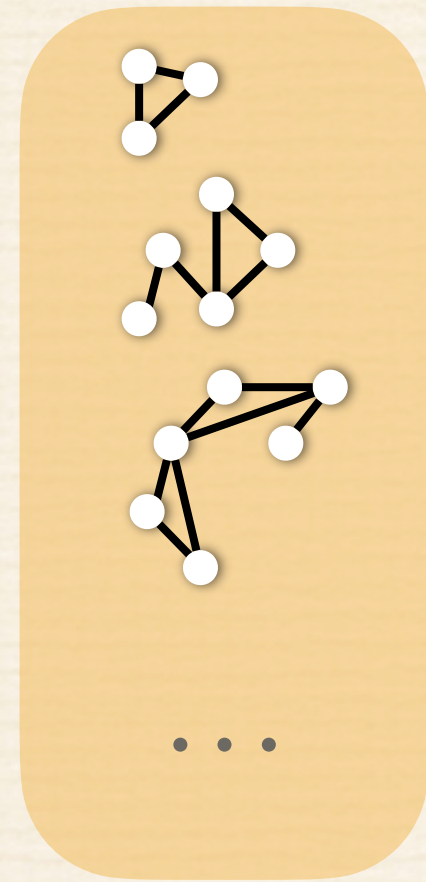
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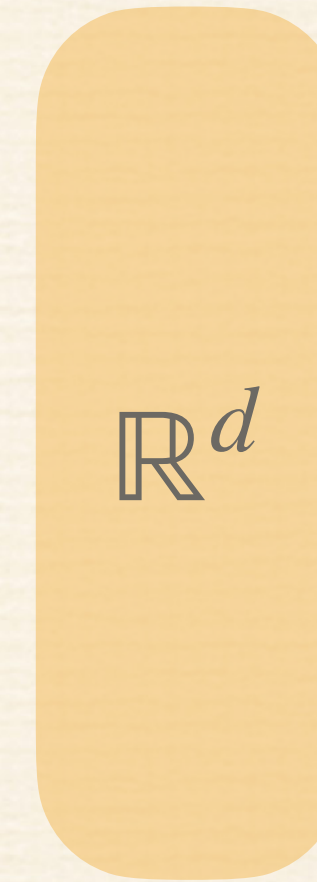
Graph learning methods are thus widely applicable

How is learning typical done?

Embedding-based graph learning

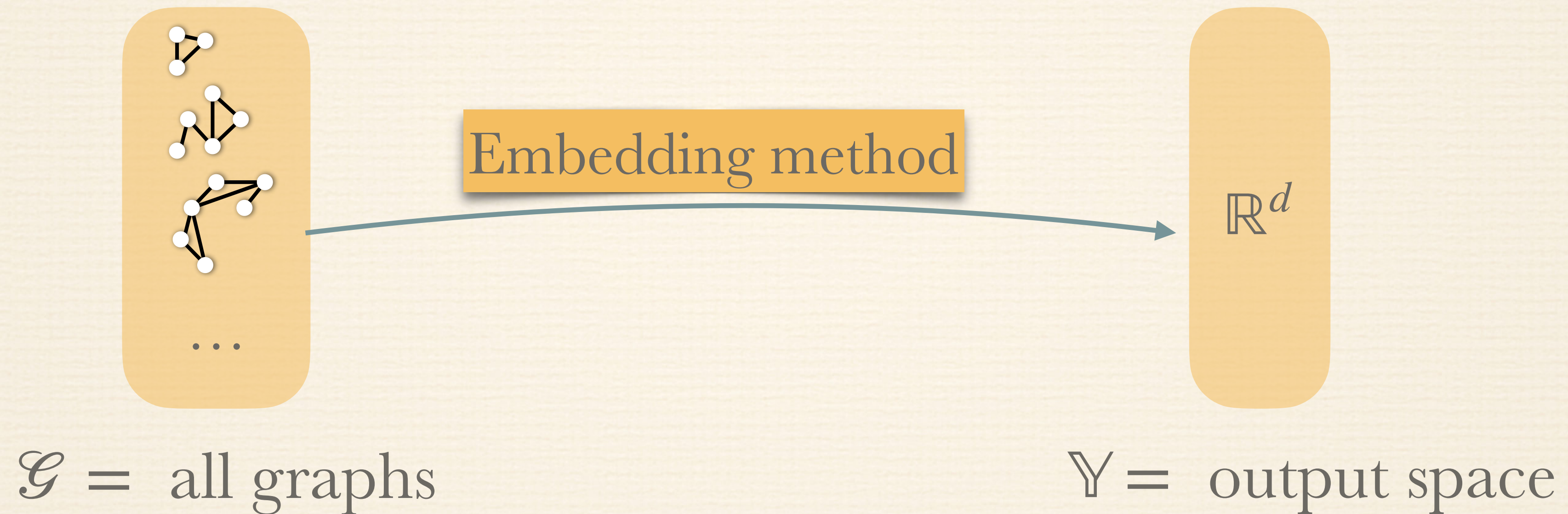


\mathcal{G} = all graphs

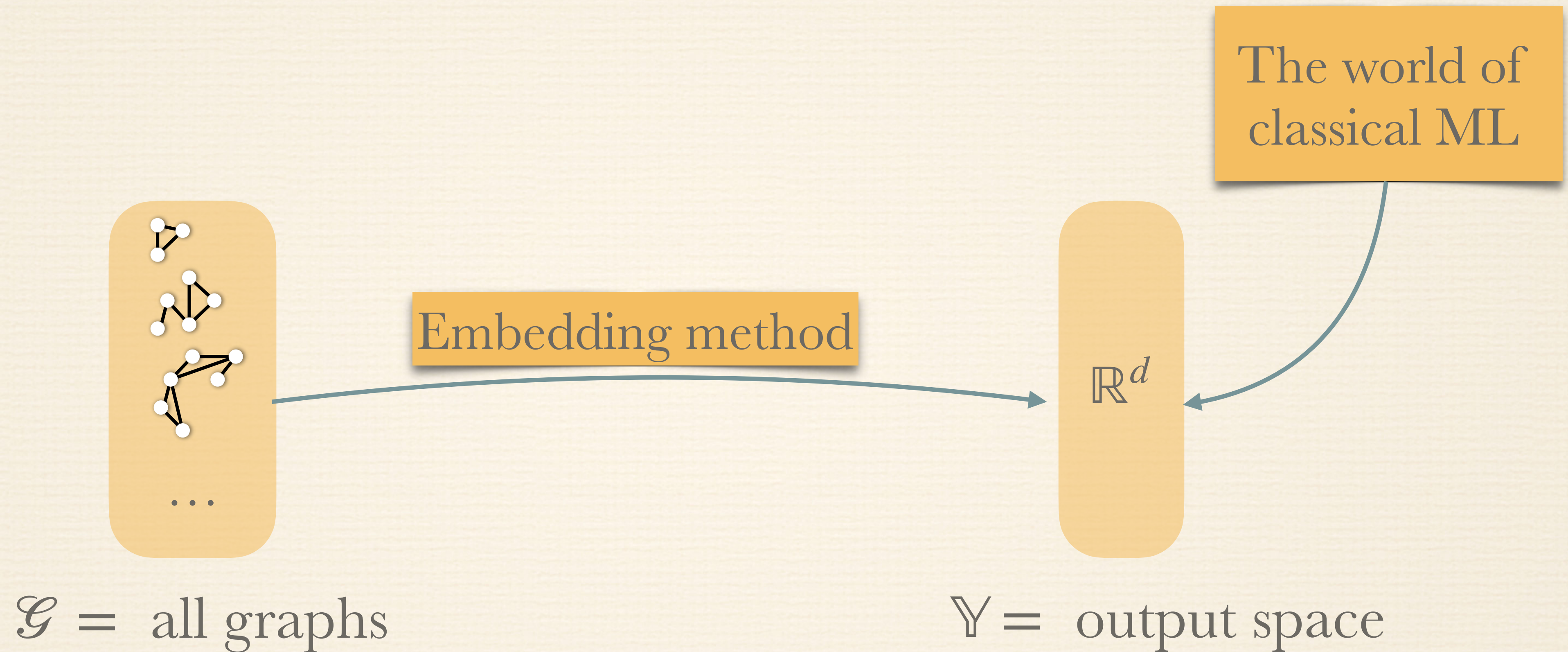


\mathbb{Y} = output space

Embedding-based graph learning



Embedding-based graph learning



Embeddings

\mathcal{G} = all graphs

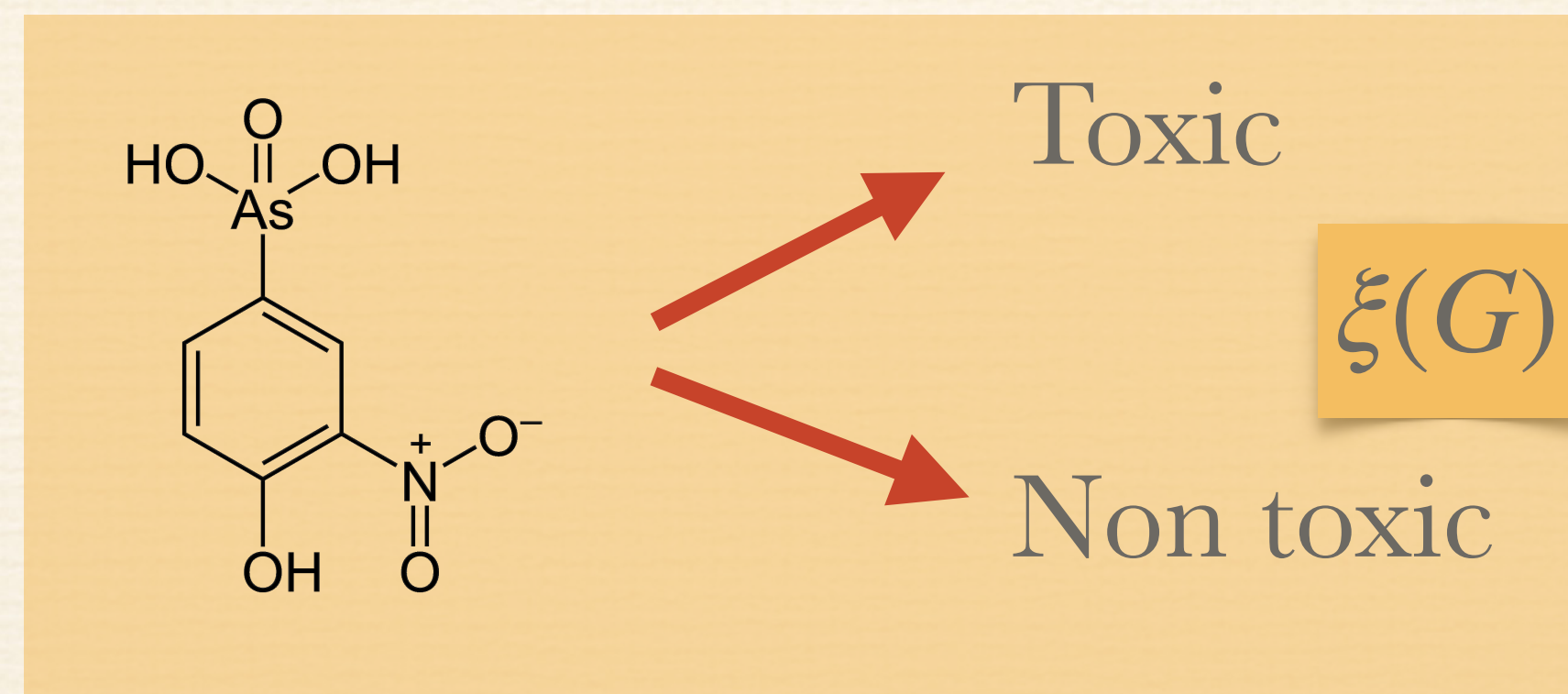
\mathcal{V} = all vertices

\mathbb{Y} = output space

- ❖ **Graph** embedding: $\xi : \mathcal{G} \rightarrow \mathbb{Y}$
- ❖ **Vertex** embedding: $\xi : \mathcal{G} \rightarrow (\mathcal{V} \rightarrow \mathbb{Y})$
- ❖ **p -Vertex** embedding: $\xi : \mathcal{G} \rightarrow (\mathcal{V}^p \rightarrow \mathbb{Y})$

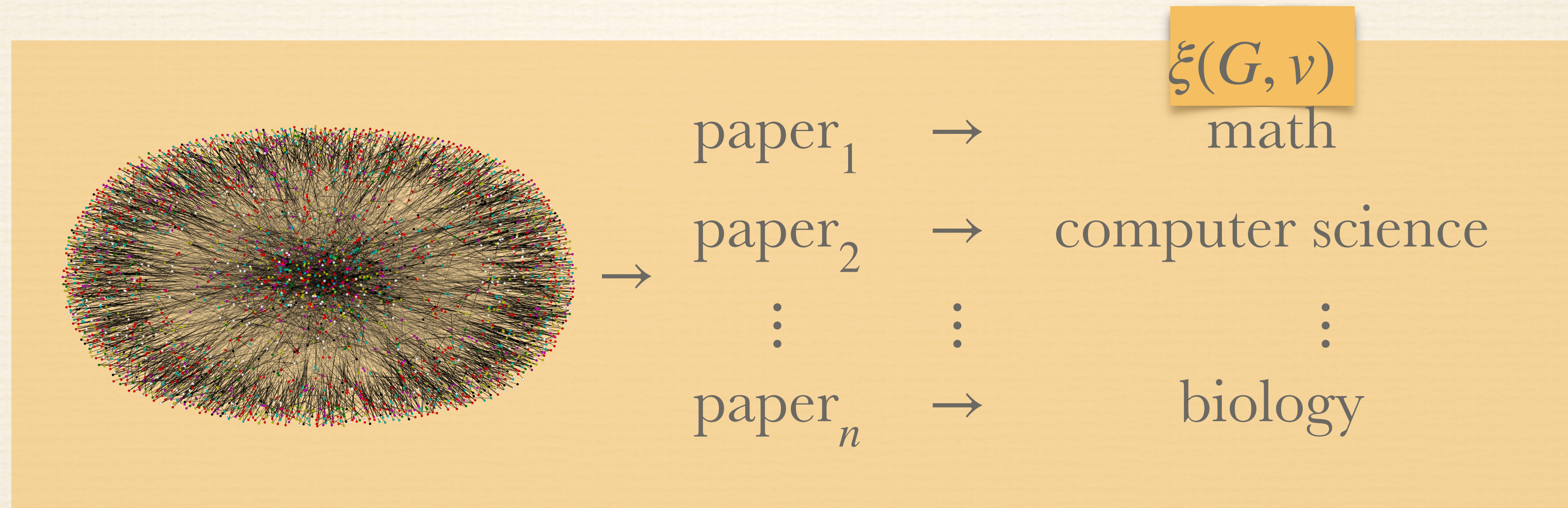
Graph embeddings

- ❖ Graph embedding: $\xi : \mathcal{G} \rightarrow \mathbb{Y}$
- ❖ Graph **classification/regression**



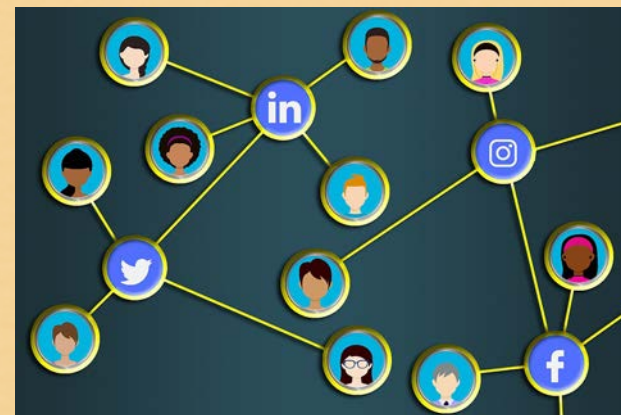
Vertex embeddings

- ❖ Vertex embedding: $\xi : \mathcal{G} \rightarrow (\mathcal{V} \rightarrow \mathcal{Y})$
- ❖ Vertex **classification/regression**. For example, prediction of subject of papers.



p-Vertex embeddings

- ❖ p -Vertex embedding: $\xi : \mathcal{G} \rightarrow (\mathcal{V}^p \rightarrow \mathbb{Y})$
- ❖ For example, 2-vertex embeddings: **link prediction**



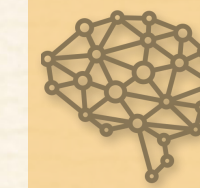
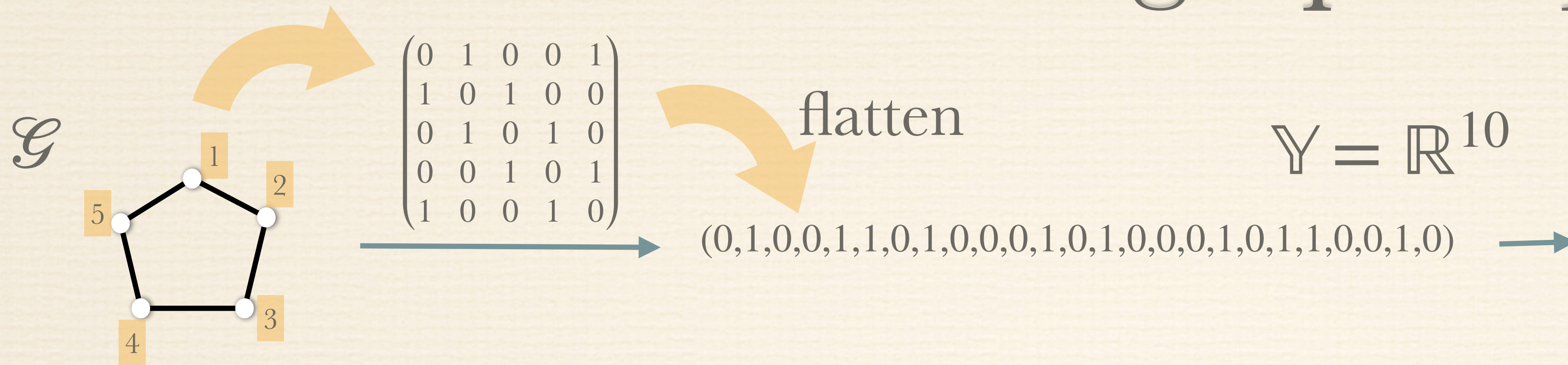
→ (Adam, Eve)
→ (Trump, Biden)
...

$\xi(G, v, w)$

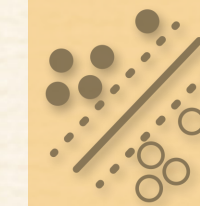
↦ link

↦ no link

What makes graphs special?



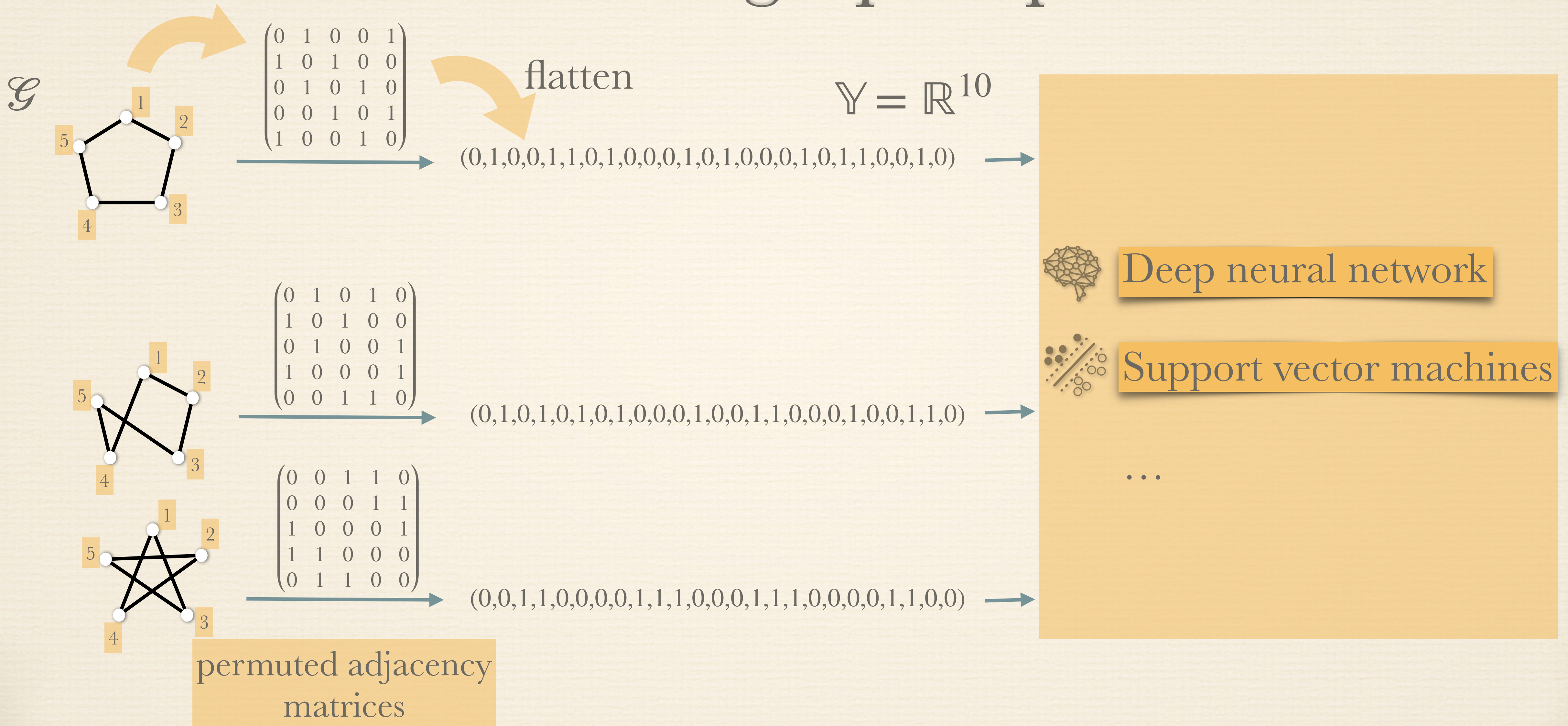
Deep neural network



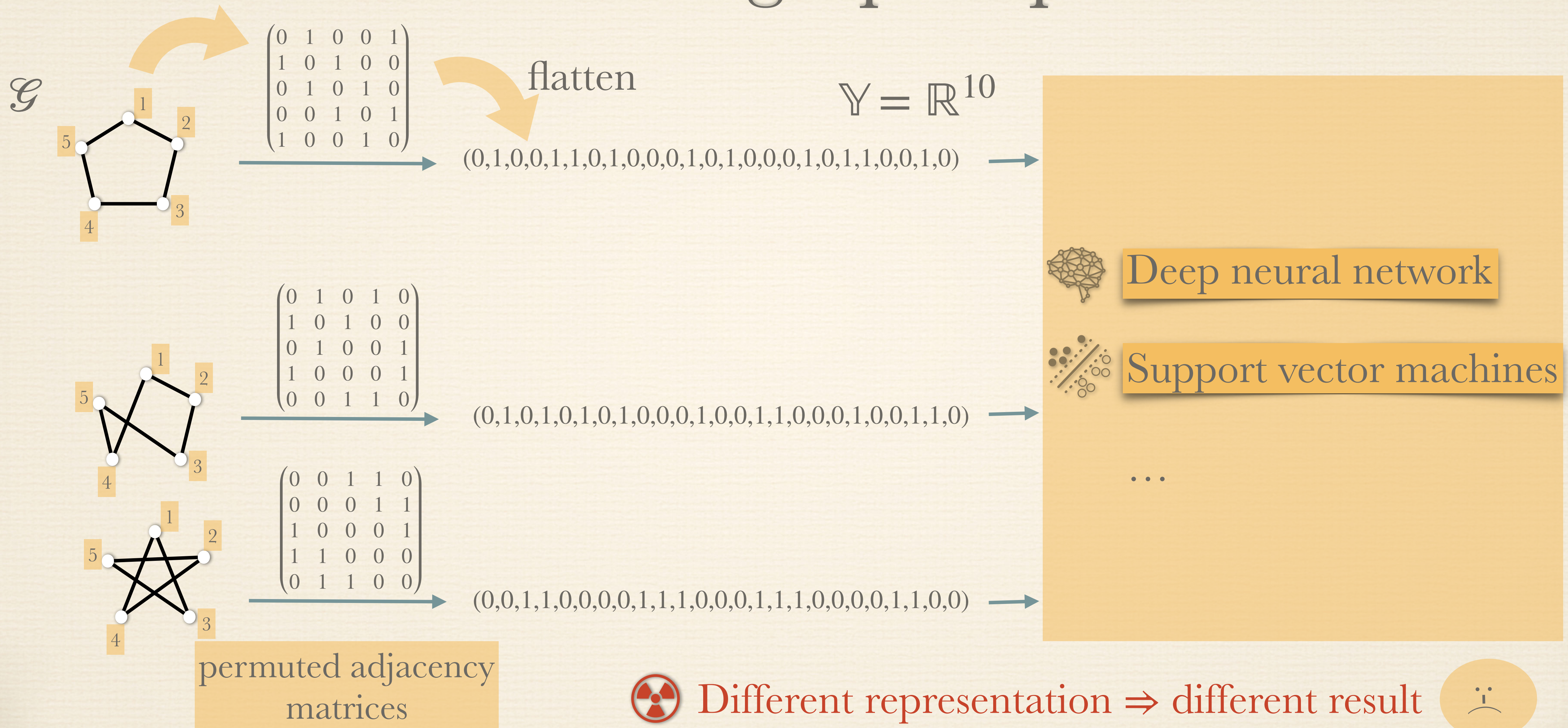
Support vector machines

...

What makes graphs special?



What makes graphs special?



 Different representation \Rightarrow different result 

Invariant embeddings

- ❖ We need embeddings to be **graph invariants**
- ❖ **Isomorphic** inputs should give the **same result**

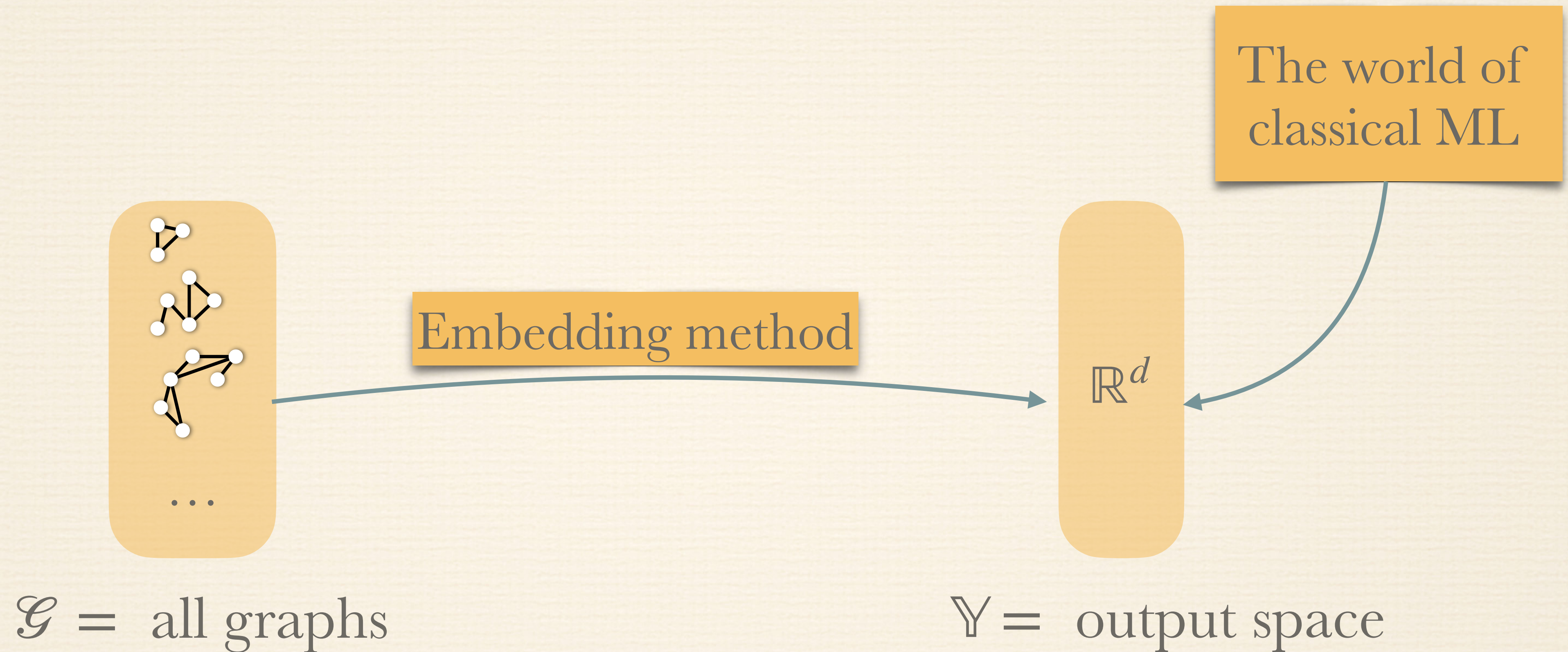
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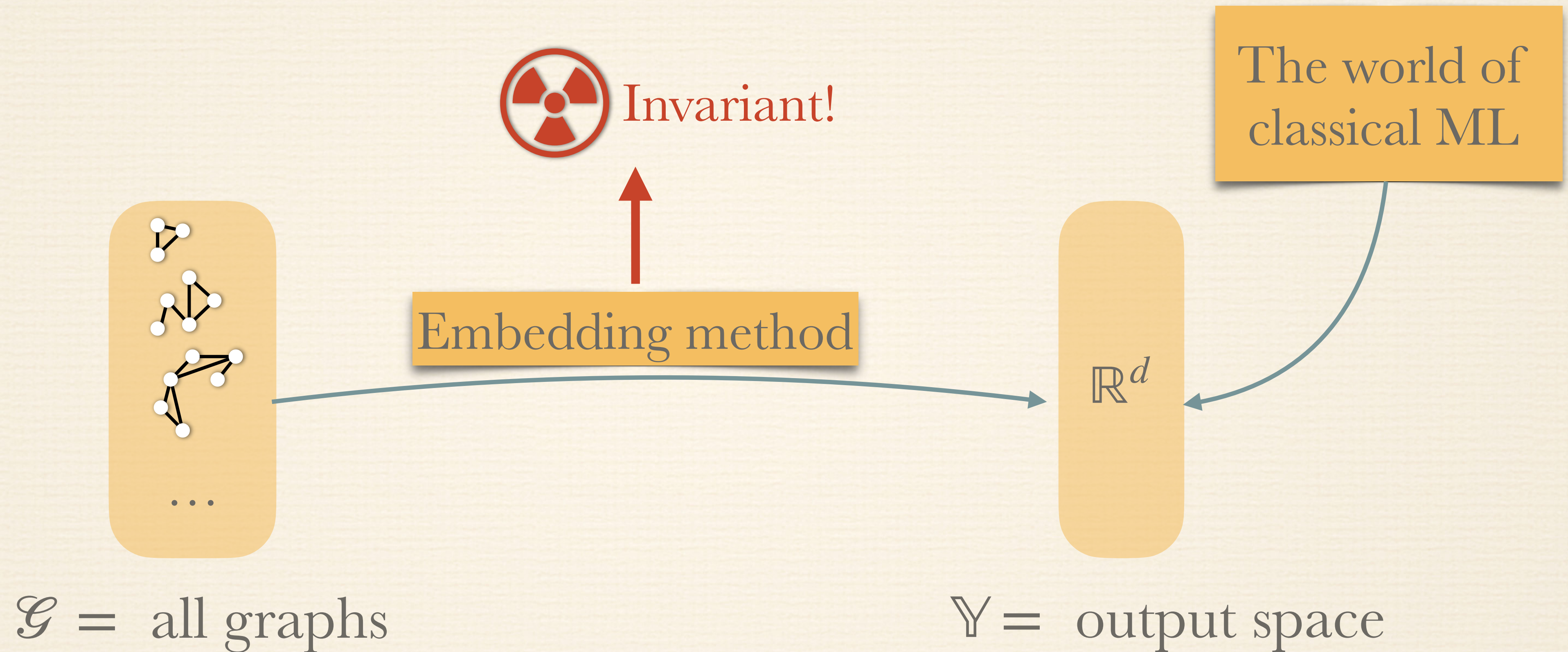
p -vertex embedding $\xi : \mathcal{G} \rightarrow (\mathcal{V}^p \rightarrow \mathbb{Y}) : (G, \mathbf{v}) \mapsto \xi(G, \mathbf{v})$ is invariant if for all G , all isomorphisms π , and $\mathbf{v} \in V_G^p : \xi(G, \mathbf{v}) = \xi(\pi(G), \pi(\mathbf{v}))$

- ❖ Invariance is typically achieved by **composing invariant building blocks** to build embeddings

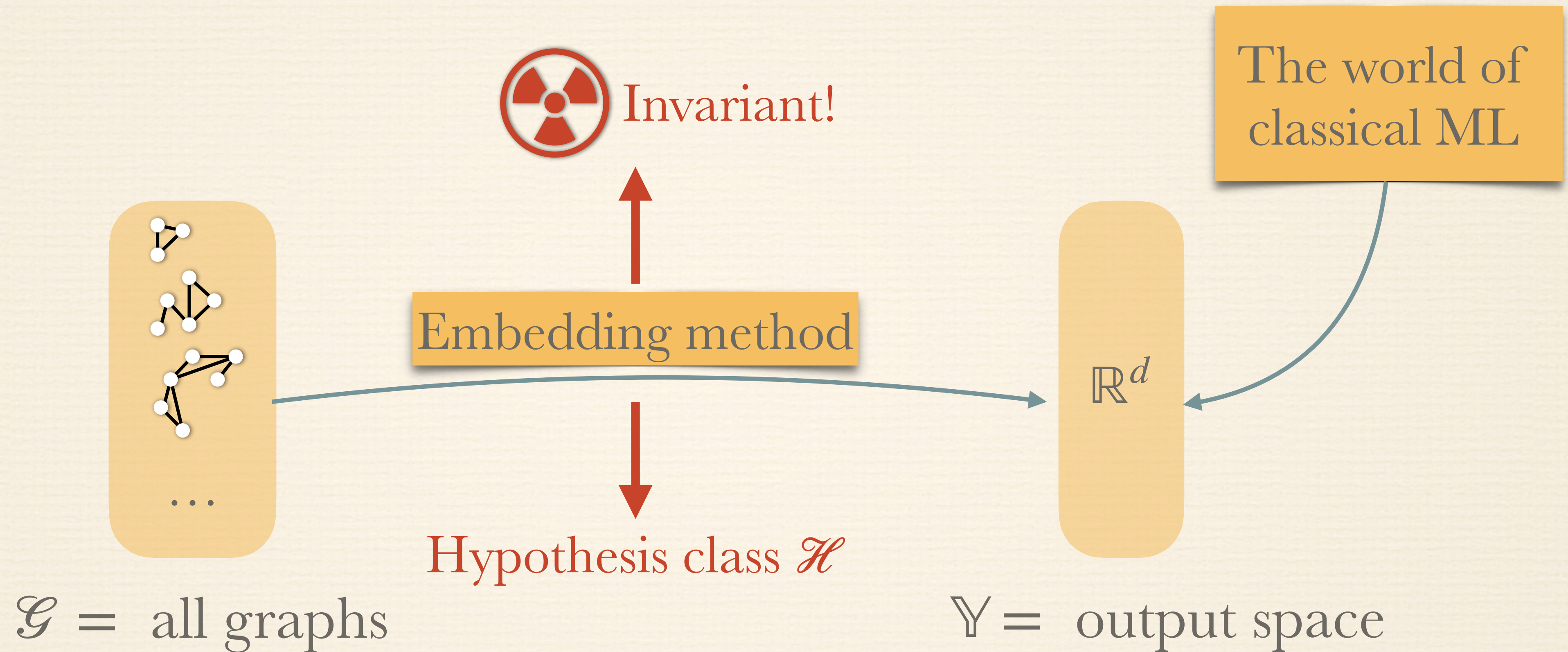
Graph learning: Invariant embeddings



Graph learning: Invariant embeddings

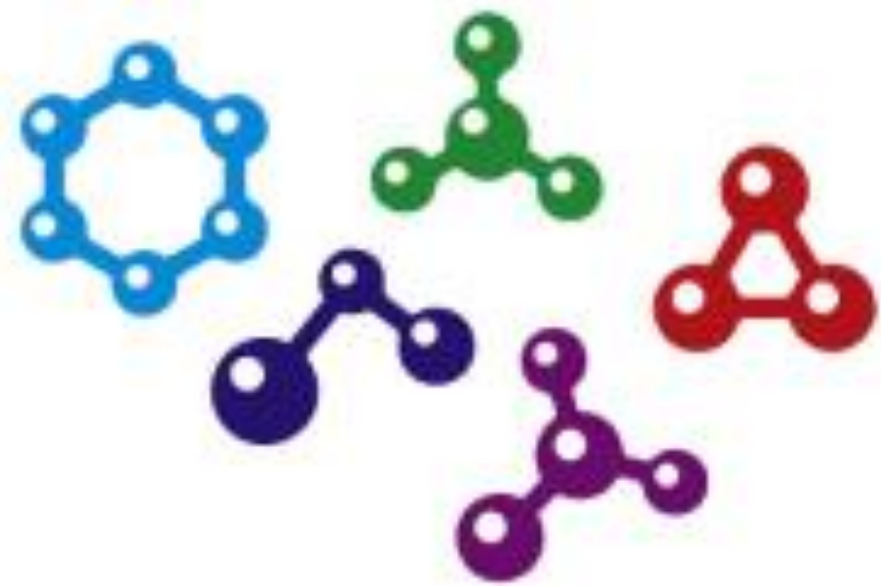


Graph learning: Invariant embeddings



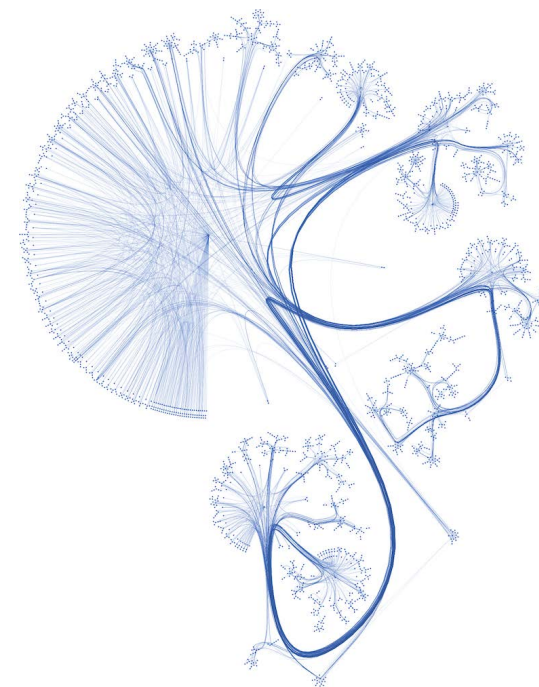
Graph learning: ERM

- Given **training set** \mathcal{T} and hypothesis class \mathcal{H} of invariant embedding methods $\mathcal{T} := \{(G_1, \mathbf{v}_1, y_1), \dots, (G_\ell, \mathbf{v}_\ell, y_\ell)\} \subseteq \mathcal{G} \times \mathcal{V}^p \times \mathcal{Y}$



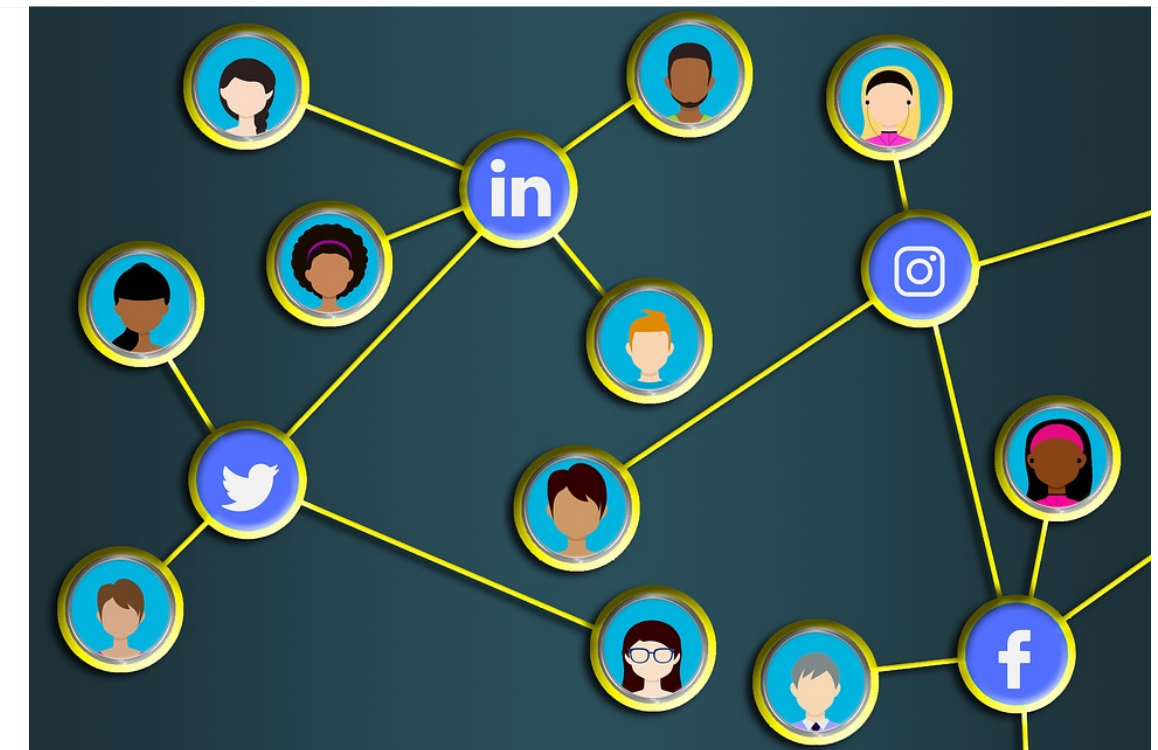
(molecule, yes/no)

Graph classification



(cora, paper, topic)

Vertex classification



(social, p_x, p_y , yes/no)

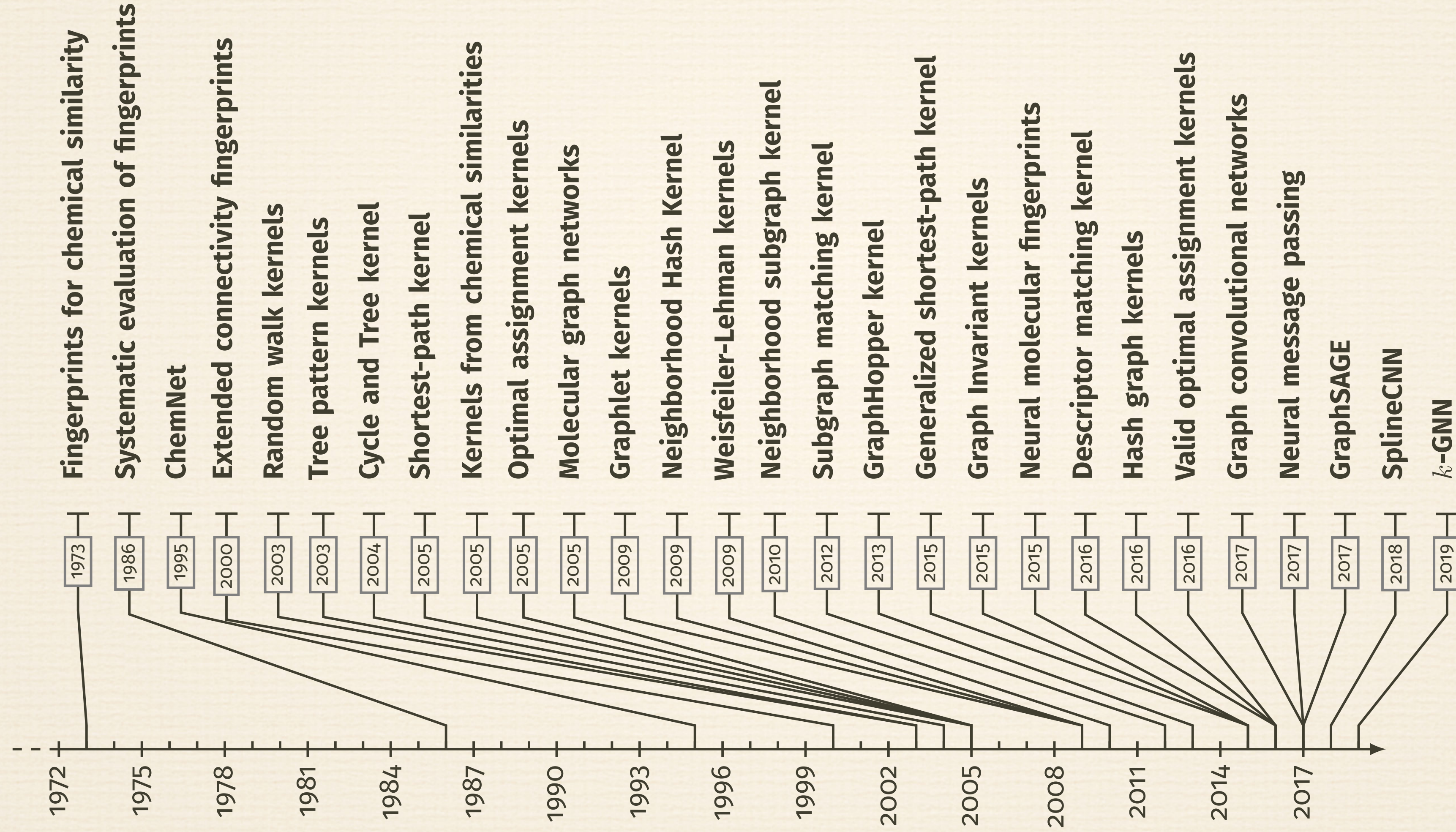
Link prediction

Graph learning: ERM

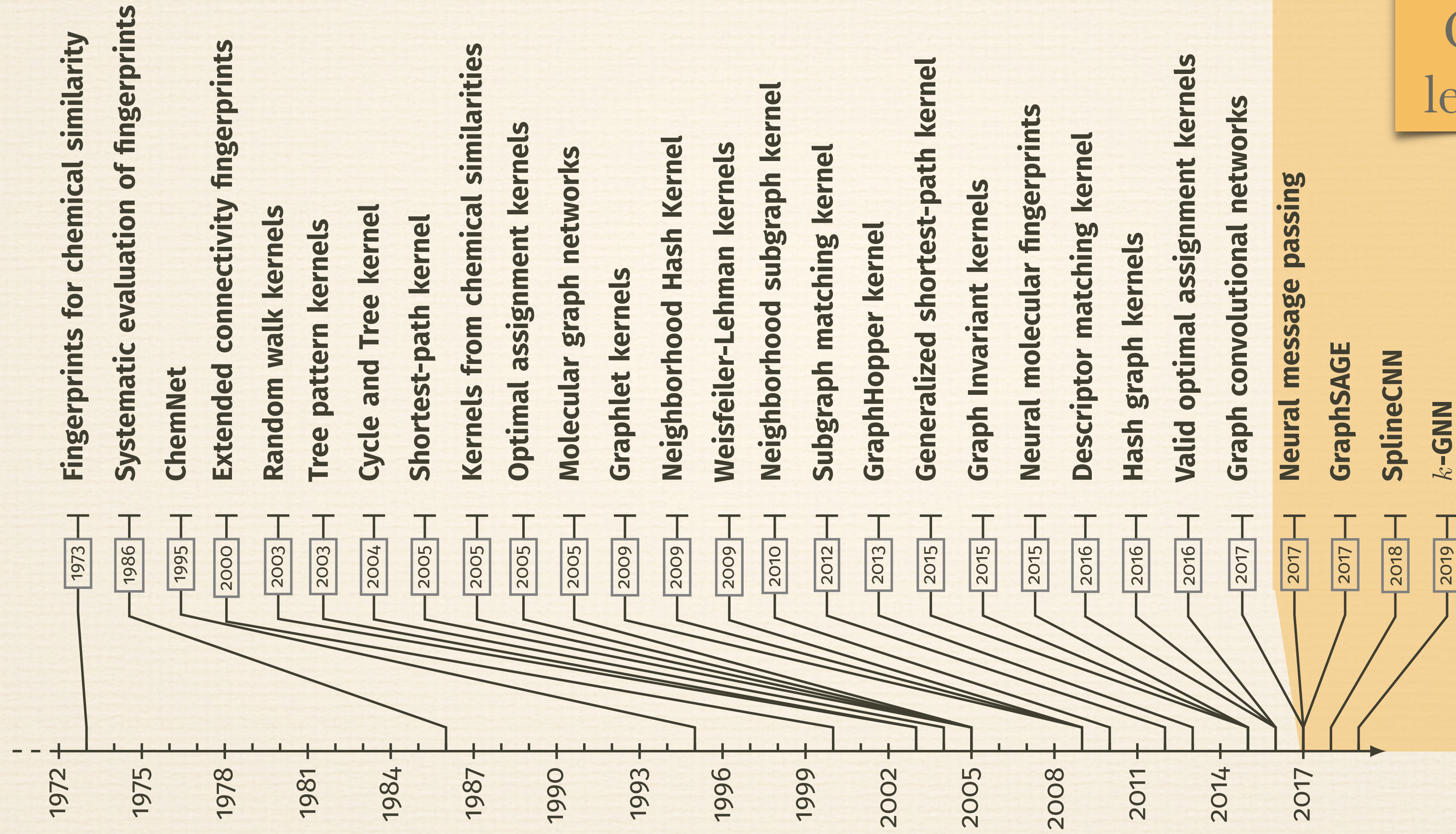
- ❖ Given **training set** \mathcal{T} and hypothesis class \mathcal{H} of invariant embedding methods $\mathcal{T} := \{(G_1, \mathbf{v}_1, y_1), \dots, (G_\ell, \mathbf{v}_\ell, y_\ell)\} \subseteq \mathcal{G} \times \mathcal{V}^p \times \mathbb{Y}$
- ❖ **Empirical risk minimisation**: Find embedding ξ in \mathcal{H} which minimises empirical loss on training set \mathcal{T} :

$$\hat{\xi} : \arg \min_{\xi \in \mathcal{H}} \frac{1}{\ell} \sum_{i=1}^{\ell} \text{loss}(\xi(G_i, \mathbf{v}_i), y_i)$$

Hypothesis classes?



Hypothesis classes?



Era of Deep Graph learning



“Deep” hypothesis classes



Hypothesis classes: how do they look like?

section 4. Consider the matrix $\mathbf{X} \in \mathbb{R}^{n \times 2a}$ defined by

$$\mathbf{X}_{j,:} = (\mathbf{B}_{j,i_2,:}, \mathbf{B}_{i_1,j,:}), \quad j \in [n]. \quad (7)$$

Our goal is to compute an output tensor $\mathbf{W} \in \mathbb{R}^{n^2 \times b}$, where $\mathbf{W}_{i_1,i_2,:} := u(\mathbf{X})$.

Consider the multi-index set $\{\alpha \mid \alpha \in [n]^{2a}, |\alpha| \leq n\}$ of cardinality $b = \binom{n+2a-1}{2a-1}$, and write it in the form $\{(\beta_l, \gamma_l) \mid \beta, \gamma \in [n]^a, |\beta_l| + |\gamma_l| \leq n, l \in [b]\}$.

Now define polynomial maps $\tau_1, \tau_2 : \mathbb{R}^a \rightarrow \mathbb{R}^b$ by $\tau_1(x) = (x^{\beta_l} \mid l \in [b])$, and $\tau_2(x) = (x^{\gamma_l} \mid l \in [b])$. We apply τ_1 to the features of \mathbf{B} , namely $\mathbf{Y}_{i_1,i_2,l} := \tau_1(\mathbf{B})_{i_1,i_2,l} = (\mathbf{B}_{i_1,i_2,:})^{\beta_l}$; similarly, $\mathbf{Z}_{i_1,i_2,l} := \tau_2(\mathbf{B})_{i_1,i_2,l} = (\mathbf{B}_{i_1,i_2,:})^{\gamma_l}$. Now,

$$\mathbf{W}_{i_1,i_2,l} := (\mathbf{Z}_{:,i_2,l} \cdot \mathbf{Y}_{:,i_1,l})_{i_1,i_2} = \sum_{j=1}^n \mathbf{Z}_{i_1,j,l} \mathbf{Y}_{j,i_2,l} = \sum_{j=1}^n \mathbf{B}_{j,i_2,:}^{\beta_l} \mathbf{B}_{i_1,j,:}^{\gamma_l} = \sum_{j=1}^n (\mathbf{B}_{j,i_2,:}, \mathbf{B}_{i_1,j,:})^{(\beta_l, \gamma_l)},$$

$$h_i = f_{\text{G-GRU}}(x_i, \{h_j : j \rightarrow i\}) = \mathcal{C}_{\text{G-GRU}}(x_i, \sum_{j \rightarrow i} h_j)$$

Equation (4) does not have an analytical solution, Li et al. propose the following scheme:

$$h_i^{t+1} = \mathcal{C}_{\text{G-GRU}}(h_i^t, \bar{h}_i^t), \quad h_i^{t=0} = x_i \quad \forall i,$$

where $\bar{h}_i^t = \sum_{j \rightarrow i} h_j^t$,

Equation (10) is equal to

$$\begin{aligned} z_i^{t+1} &= \sigma(U_z h_i^t + V_z \bar{h}_i^t) \\ r_i^{t+1} &= \sigma(U_r h_i^t + V_r \bar{h}_i^t) \\ \tilde{h}_i^{t+1} &= \tanh(U_h (h_i^t \odot r_i^{t+1}) + V_h \bar{h}_i^t) \\ h_i^{t+1} &= (1 - z_i^{t+1}) \odot h_i^t + z_i^{t+1} \odot \tilde{h}_i^{t+1}, \end{aligned}$$

is injective. We can make ϵ a learnable parameter or a fixed scalar. There may exist many other powerful GNNs. GIN is one such example.

$$h_v^{(k)} = \text{MLP}^{(k)} \left(\left(1 + \epsilon^{(k)}\right) \cdot h_v^{(k-1)} + \sum_{u \in \mathcal{N}(v)} h_u^{(k-1)} \right).$$

There may exist many other powerful GNNs. GIN is one such example.

$$\begin{aligned} m_v^{t+1} &= \sum_{w \in N(v)} M_t(h_v^t, h_w^t, e_{vw}) \\ h_v^{t+1} &= U_t(h_v^t, m_v^{t+1}) \end{aligned}$$

the sum, $N(v)$ denotes the neighbors of v in the graph. In the readout phase, the graph uses some readout function R according to

$$\hat{y} = R(\{h_v^T \mid v \in G\}).$$

$$h_i^{\ell+1} = f_{\text{S-GCN}}^\ell(\{h_j^\ell : j \rightarrow i\}) = \text{ReLU} \left(\sum_{j \rightarrow i} \eta_{ij} \odot V^\ell h_j^\ell \right)$$

edge gates, and are computed by:

$$\eta_{ij} = \sigma(A^\ell h_i^\ell + B^\ell h_j^\ell).$$

$$\psi \left(M_n H_n^{\text{in}} W_n + U_n H_{n-1}^{\text{in}} W_{n-1} + O_n H_{n+1}^{\text{in}} W_{n+1} \right), \quad (11)$$

where ψ is an entry-wise activation ($s \mapsto \max\{0, s\}$ for ReLU), $W_n \in \mathbb{R}^{d_n \times m_n}$ are trainable weight matrices and $M_n \in \mathbb{R}^{S_n \times S_n}$, $U_n \in \mathbb{R}^{S_n \times S_{n-1}}$, and $O_n \in \mathbb{R}^{S_n \times S_{n+1}}$ are some choice of adjacency matrices for the simplicial complex. These could be the Hodge Laplacian matrix L_n and the corresponding boundary matrices B_n^\top, B_{n+1} , or one of their variants (e.g. normalised).

It is convenient to write the entire layer output in standard form. Using Roth's lemma and concatenating over n we can write (11) as (details in Appendix B)

$$H^{\text{out}} = \psi(W H^{\text{in}}), \quad (12)$$

where $H^{\text{in}} = \text{vec}([H_0^{\text{in}} | H_1^{\text{in}} | \dots | H_p^{\text{in}}]) \in \mathbb{R}^N$, $N = \sum_{n=0}^p S_n d_n$, $H^{\text{out}} = \text{vec}([H_0^{\text{out}} | H_1^{\text{out}} | \dots | H_p^{\text{out}}]) \in \mathbb{R}^M$, $M = \sum_{n=0}^p S_n m_n$, and

$$W = \begin{bmatrix} W_0^\top \otimes M_0 & W_1^\top \otimes O_0 & & & \\ W_0^\top \otimes U_1 & W_1^\top \otimes M_1 & W_2^\top \otimes O_1 & & \\ & W_1^\top \otimes U_2 & W_2^\top \otimes M_2 & W_3^\top \otimes O_2 & \\ & & & & \ddots \end{bmatrix}. \quad (13)$$

As a recurrent formula is the general case of graphs, we proceed as follows: iterative process to solve Eq. (10): At layer ℓ , for $t = 0, 1, \dots, T$

$$\begin{aligned} \bar{h}_i^{\ell,t} &= \sum_{j \rightarrow i} h_j^{\ell,t}, \\ i_i^{\ell,t+1} &= \sigma(U_i^\ell x_i^\ell + V_i^\ell \bar{h}_i^{\ell,t}), \\ o_i^{\ell,t+1} &= \sigma(U_o^\ell x_i^\ell + V_o^\ell \bar{h}_i^{\ell,t}), \\ \tilde{c}_i^{\ell,t+1} &= \tanh(U_c^\ell x_i^\ell + V_c^\ell \bar{h}_i^{\ell,t}), \\ f_{ij}^{\ell,t+1} &= \sigma(U_f^\ell x_i^\ell + V_f^\ell h_j^{\ell,t}), \\ c_i^{\ell,t+1} &= i_i^{\ell,t+1} \odot \tilde{c}_i^{\ell,t+1} + \sum_{j \rightarrow i} f_{ij}^{\ell,t+1} \odot c_j^{\ell,t+1}, \\ h_i^{\ell,t+1} &= o_i^{\ell,t+1} \odot \tanh(c_i^{\ell,t+1}) \end{aligned}$$

and initial conditions: $h_i^{\ell,t=0} = c_i^{\ell,t=0} = 0, \quad \forall i, \ell$
 $r^\ell = h^{\ell-1,T} \quad r^{\ell=0} = r. \quad \forall i, \ell$

How to compare different classes?

- ❖ How to compare such embedding classes **theoretically**?
- ❖ How to bring **order to the chaos**?

How to compare different classes?

- ❖ How to compare such embedding classes **theoretically**?
- ❖ How to bring **order to the chaos**?

1. See graph embedding methods as queries in some **query language**



3. **Transfer understanding back** to graph learning world

2. **Analyse expressive power** of query language

How to compare different classes?

- ❖ How to compare such embedding classes **theoretically**?
- ❖ How to bring **order to the chaos**?

What kind of language?

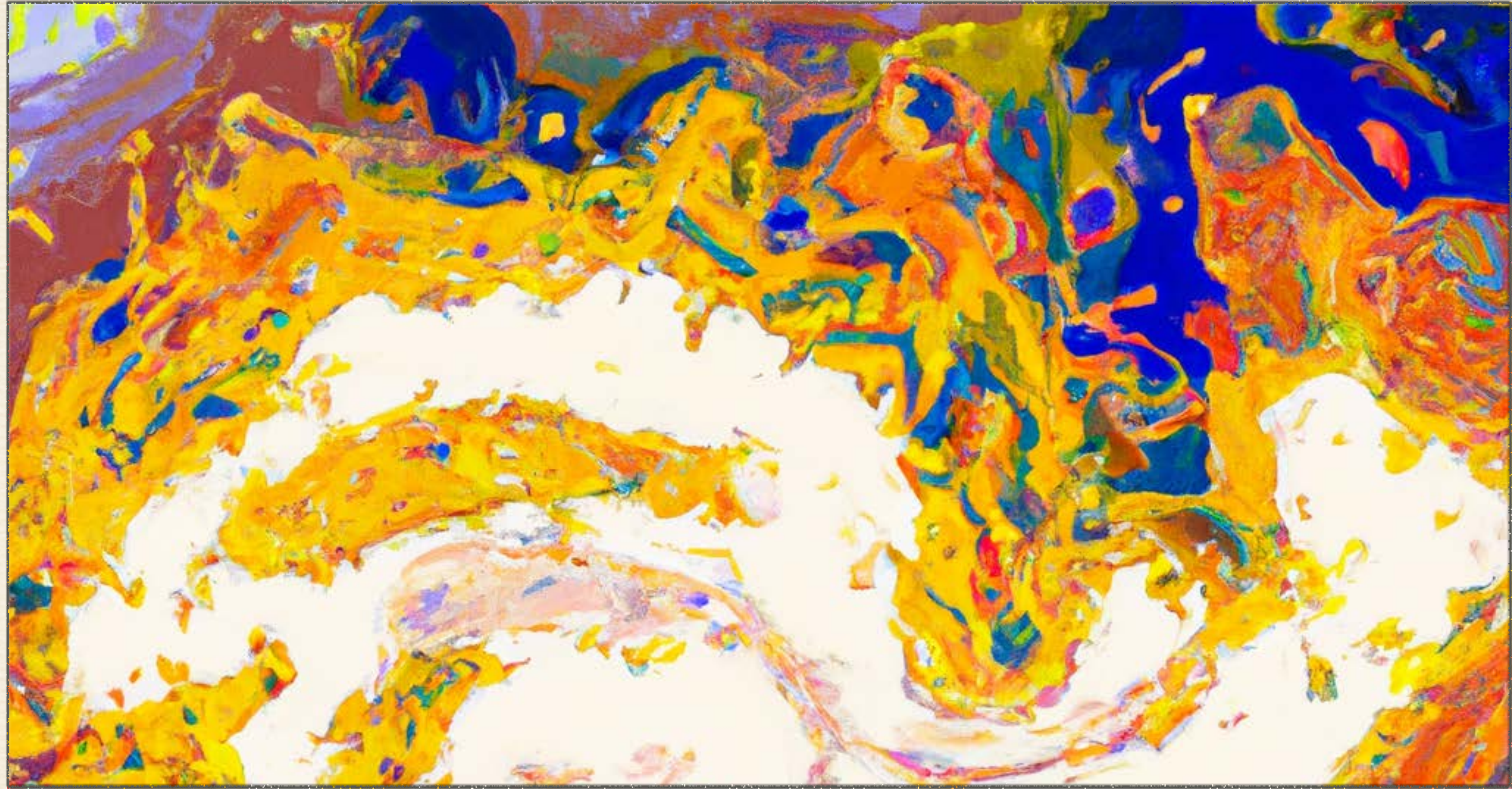
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Expressive power?

3. **Transfer understanding back** to graph learning world

2. **Analyse expressive power** of query language





Graph Embedding Language

Graph Embedding Language (GEL)

Hypothesis classes: how do they look like?

section 4. Consider the matrix $X \in \mathbb{R}^{n \times n}$ defined by $X_{ij} = \langle \mathbf{b}_i, \mathbf{b}_j \rangle$, $j \in [n]$. (7)

Our goal is to compute an output tensor $\mathbf{W} \in \mathbb{R}^{n \times b}$, where $\mathbf{W}_{i,\alpha} = w_i(X)$. Consider the multi-index set $\{\alpha \in [b]^n, |\alpha| \leq n\}$ of cardinality $b = \binom{n+b-1}{n}$, and write it in the form $\{(b, \gamma) \mid \gamma \in [n]^b, |\gamma| + |\alpha| \leq n, l \in [b]\}$. Now define polynomial maps $\tau_1, \tau_2: \mathbb{R}^n \rightarrow \mathbb{R}^b$ by $\tau_1(x) = \{x^{\gamma} \mid \gamma \in [n]^b, |\gamma| \leq n\}$, and $\tau_2(x) = \{x^{\gamma} \mid \gamma \in [n]^b, |\gamma| = n\}$. We apply τ_1 to the features of \mathbf{X} , namely $\mathbf{V}_{i,\alpha} := \tau_1(\mathbf{b}_i)_{\alpha} = \langle \mathbf{b}_i, \mathbf{b}_{\alpha} \rangle$, similarly $\mathbf{Z}_{i,\alpha} := \tau_2(\mathbf{b}_i)_{\alpha} = \langle \mathbf{b}_i, \mathbf{b}_{\alpha} \rangle$. Now, $\mathbf{W}_{i,\alpha} := \langle \mathbf{Z}_i, \mathbf{Y}_{\alpha} \rangle_{\alpha} = \sum_{j=1}^n \sum_{\beta \in [b]^n, |\beta| = |\alpha|} \mathbf{b}_{i,\beta} \mathbf{b}_{j,\alpha} = \sum_{j=1}^n \langle \mathbf{b}_i, \mathbf{b}_{\beta} \rangle \langle \mathbf{b}_j, \mathbf{b}_{\alpha} \rangle$.

where ψ is an entry-wise activation ($\psi(x) = \max\{0, x\}$ for ReLU), $W_i \in \mathbb{R}^{b \times n}$ are trainable weight matrices and $M_i \in \mathbb{R}^{n \times n}$, $L_i \in \mathbb{R}^{n \times n}$, and $G_i \in \mathbb{R}^{n \times n}$ are some choice of adjacency matrices for the simplicial complex. These could be the Hodge Laplacian matrix L_i and the corresponding boundary matrices M_i, B_i , or one of their variants (e.g. normalised).

It is convenient to write the entire layer output in standard form. Using ReLU's linearity and concatenating over α we can write (11) as (details in Appendix B)

$$H^m = \psi(WH^m), \quad (12)$$

where $H^m = \text{vec}([M_i^m H_i^{m-1}, \dots, B_i^m]) \in \mathbb{R}^n$, $N = \sum_{i=1}^n \sum_{\alpha \in [b]^n, |\alpha| = m} \mathbf{b}_{i,\alpha}$, and $M_i^m = \sum_{\alpha \in [b]^n, |\alpha| = m} \mathbf{b}_{i,\alpha} \mathbf{b}_{i,\alpha}^T$.

$$W = \begin{bmatrix} w_{1,1} & \dots & w_{1,b} \\ \vdots & \ddots & \vdots \\ w_{n,1} & \dots & w_{n,b} \end{bmatrix}. \quad (13)$$

iterative process to solve Eq. (10): At layer ℓ , for $\ell = 0, 1, \dots, T$

$$\tilde{h}_i^{\ell+1} = \sum_{j=1}^n h_j^{\ell+1}$$

$$e_i^{\ell+1} = \sigma(U_i^{\ell} \tilde{e}_i^{\ell} + V_i^{\ell} h_i^{\ell})$$

$$f_i^{\ell+1} = \sigma(U_i^{\ell} \tilde{e}_i^{\ell} + V_i^{\ell} h_i^{\ell})$$

$$g_i^{\ell+1} = \tanh(U_i^{\ell} \tilde{e}_i^{\ell} + V_i^{\ell} h_i^{\ell})$$

$$h_i^{\ell+1} = \sigma(U_i^{\ell} \tilde{e}_i^{\ell} + V_i^{\ell} h_i^{\ell})$$

$$e_i^{\ell+1} = e_i^{\ell+1} \odot e_i^{\ell+1} + \sum_{j=1}^n f_j^{\ell+1} \odot e_j^{\ell+1}$$

$$h_i^{\ell+1} = e_i^{\ell+1} \odot \tanh(e_i^{\ell+1})$$

and initial conditions: $h_i^{\ell=0} = e_i^{\ell=0} = 0, \forall i, \ell$
 $e_i^{\ell} = h_i^{\ell-1, T} \odot e_i^{\ell=0} = \dots, \forall i, \ell$

$h_i^{(k)} = \text{MLP}^{(k)} \left((1 + \epsilon^{(k)}) \cdot h_i^{(k-1)} + \sum_{j \in N(i)} h_j^{(k-1)} \right)$.

is injective. We can make ϵ a learnable parameter or a fixed constant.

may exist many other powerful GNNs. GIN is one such example.

$m_i^{\ell+1} = \sum_{w \in N(i)} M_i(h_w^{\ell}, h_w^{\ell}, e_{iw})$

$h_i^{\ell+1} = U_i(h_i^{\ell}, m_i^{\ell+1})$

the sum, $N(i)$ denotes the neighbors of i in the graph. The readout phase computes a feature vector \hat{y} using some readout function R according to $\hat{y} = R(\{h_i^{\ell} \mid i \in G\})$.

$h_i^{\ell+1} = f_{\text{GEL}}^{\ell}(h_i^{\ell}; j \rightarrow i) = \text{ReLU} \left(\sum_{j \in N(i)} \eta_{ij} \odot V_j^{\ell} h_j^{\ell} \right)$

edge gates, and are computed by: $\eta_{ij} = \sigma(A^{\ell} h_i^{\ell} + B^{\ell} h_j^{\ell})$.

- ❖ Most methods are specified in terms of **linear algebra computations** interleaved with **non-linear function** applications
- ❖ Crucial component is **multiplication with adjacency matrix** which corresponds to **neighbourhood aggregation**

 Desired language needs **function application** and **aggregation**

Graph Neural Networks 101

❖ **Non-linear activation** function σ (ReLU, sign, sigmoid, ...)

❖ $\mathbf{F}_G^{(t)} \in \mathbb{R}^{n \times d}$ denotes embedding of vertices in graph G

$$\begin{matrix} v_1 \\ v_2 \\ v_3 \end{matrix} \begin{pmatrix} 0.1 & 31 & 8 & 4.03 \\ 5 & 0.03 & 9.7 & -1 \\ -3 & 118 & -63 & 0.204 \end{pmatrix}$$

❖ **Weight** matrices $\mathbf{W}_1^{(t)} \in \mathbb{R}^{d \times d}$ and $\mathbf{W}_2^{(t)} \in \mathbb{R}^{d \times d}$ and **bias** vector $\mathbf{b} \in \mathbb{R}^{1 \times d}$

$\mathbf{F}_G^{(0)}$ ← Initial hot-one embedding of vertex labels

Matrix form $\mathbf{F}_G^{(t)} := \sigma \left(\mathbf{F}_G^{(t-1)} \mathbf{W}_1^{(t)} + \mathbf{A}_G \mathbf{F}_G^{(t-1)} \mathbf{W}_2^{(t)} + \mathbf{B}^{(t)} \right) \in \mathbb{R}^{n \times d}$

Adjacency matrix

Aggregation over neighbours

GNN 101: Graph embedding

- ❖ **Weight** matrix $\mathbf{W} \in \mathbb{R}^{d \times d}$ and **bias vector** $\mathbf{b} \in \mathbb{R}^{1 \times d}$

$$\mathbf{F}_G := \sigma \left(\sum_{v \in V_G} \mathbf{F}_G^{(L)} \mathbf{W} + \mathbf{b} \right) \in \mathbb{R}^{1 \times d}$$

Aggregation over all vertices

- ❖ **Hypothesis class** \mathcal{H} consists of $\xi_{\Theta} : G \mapsto \mathbf{F}_G$ parametrised by weights and biases $\Theta = \mathbf{W}_1^{(1)}, \dots, \mathbf{W}_1^{(L)}, \mathbf{W}_2^{(1)}, \dots, \mathbf{W}_2^{(L)}, \mathbf{W}, \mathbf{b}^{(1)}, \dots, \mathbf{b}^{(L)}, \mathbf{b}$
- ❖ **Empirical Risk Minimisation:** Find best parameters Θ

Graph Embedding Language (GEL)

GEL expression

Syntax

$\varphi(\mathbf{x})$ of dimension d and free variables $\mathbf{x} = \{x_1, \dots, x_\ell\}$



Higher order embedding

Semantics

$$\xi_\varphi : \mathcal{G} \rightarrow (\mathcal{V}^\ell \rightarrow \mathbb{R}^d)$$

A simplified version of a query languages with aggregates studied in database theory and it resembles Datalog°

Atomic GEL expressions

Atomic expressions

Label: $\varphi(x_i) := \text{Lab}_j(x_i)$ of dim 1 and free var x_i

Edge: $\varphi(x_i, x_j) := E(x_i, x_j)$ of dim 1, free vars x_i, x_j

Equality: $\varphi(x_i, x_j) := \mathbf{1}[x_i = x_j]$ of dim 1, free vars x_i, x_j

Assigning vertex v to x_i

Semantics

$\xi_\varphi(G, x_i/v) := j$ th feature of v

$\xi_\varphi(G, x_i/v, x_j/w) := \begin{cases} 1 & (v, w) \in E_G \\ 0 & \text{otherwise} \end{cases}$

$\xi_\varphi(G, x_i/v, x_j/w) := \begin{cases} 1 & v = w \\ 0 & \text{otherwise} \end{cases}$

GEL: Function Application

Function application: Syntax

Let $\varphi_1(\mathbf{x}_1), \dots, \varphi_\ell(\mathbf{x}_1)$ be GEL expressions of **dim** d_1, \dots, d_ℓ and **free vars** $\mathbf{x}_1, \dots, \mathbf{x}_\ell$

Let $F : \mathbb{R}^{d_1 + \dots + d_\ell} \rightarrow \mathbb{R}^d$ be a function. Then,

$$\varphi(\mathbf{x}) = F(\varphi_1, \dots, \varphi_\ell)$$

is a GEL expression of **dim** d and **free vars** $\mathbf{x} = \mathbf{x}_1 \cup \dots \cup \mathbf{x}_\ell$

GEL: Function Application

Function application: Syntax

Let $\varphi_1(\mathbf{x}_1), \dots, \varphi_\ell(\mathbf{x}_\ell)$ be GEL expressions of **dim** d_1, \dots, d_ℓ and **free vars** $\mathbf{x}_1, \dots, \mathbf{x}_\ell$
Let $F : \mathbb{R}^{d_1 + \dots + d_\ell} \rightarrow \mathbb{R}^d$ be a function. Then,

$$\varphi(\mathbf{x}) = F(\varphi_1, \dots, \varphi_\ell)$$

is a GEL expression of **dim** d and **free vars** $\mathbf{x} = \mathbf{x}_1 \cup \dots \cup \mathbf{x}_\ell$

Semantics

$$\xi_\varphi(G, \mathbf{x}/\mathbf{v}) := F\left(\underbrace{\xi_{\varphi_1}(G, \mathbf{x}_1/\mathbf{v}_1)}_{\mathbb{R}^{d_1}}, \dots, \underbrace{\xi_{\varphi_\ell}(G, \mathbf{x}_\ell/\mathbf{v}_\ell)}_{\mathbb{R}^{d_\ell}}\right) \in \mathbb{R}^d$$

Linear algebra
Activation functions
Anything you want...

GEL: Aggregation

Aggregation: Syntax

Let $\varphi_1(\mathbf{x}, \mathbf{y})$ and $\varphi_2(\mathbf{x}, \mathbf{y})$ be GEL expressions of **dim** d_1 and d_2 and **free vars** \mathbf{x}, \mathbf{y} . Let Θ be a function mapping bags of vectors in \mathbb{R}^{d_1} to a vector in \mathbb{R}^d . Then,

$$\varphi(\mathbf{x}) = \text{agg}_{\mathbf{y}}^{\Theta}[\varphi_1 \mid \varphi_2]$$

is a GEL expression of **dim** d and **free vars** \mathbf{x}

Semantics

$$\xi_{\varphi}(G, \mathbf{x}/\mathbf{v}) := \Theta \left(\left\{ \left\{ \xi_{\varphi_1}(G, \mathbf{x}/\mathbf{v}, \mathbf{y}/\mathbf{w}) \mid \mathbf{w} \in V_G^{\mathbf{y}} \right\} \mid \bigcap_{\mathbb{R}^{d_1}} \right. \right)$$

GEL: Aggregation

Aggregation: Syntax

Let $\varphi_1(\mathbf{x}, \mathbf{y})$ and $\varphi_2(\mathbf{x}, \mathbf{y})$ be GEL expressions of **dim** d_1 and d_2 and **free vars** \mathbf{x}, \mathbf{y} . Let Θ be a function mapping bags of vectors in \mathbb{R}^{d_1} to a vector in \mathbb{R}^d . Then,

$$\varphi(\mathbf{x}) = \text{agg}_{\mathbf{y}}^{\Theta}[\varphi_1 \mid \varphi_2]$$

is a GEL expression of **dim** d and **free vars** \mathbf{x}

Semantics

$$\xi_{\varphi}(G, \mathbf{x}/\mathbf{v}) := \Theta \left(\left\{ \left\{ \xi_{\varphi_1}(G, \mathbf{x}/\mathbf{v}, \mathbf{y}/\mathbf{w}) \mid \xi_{\varphi_2}(G, \mathbf{x}/\mathbf{v}, \mathbf{y}/\mathbf{w}) \neq \mathbf{0}, \mathbf{w} \in V_G^{\mathbf{y}} \right\} \right\}_{\mathbb{R}^{d_1}} \right)$$

guard

GEL: Aggregation example

$$\varphi = \text{agg}_{x,y,z}^{\text{sum}} \left[\mathbf{1}[y = y] \mid E(x, y) \cdot E(y, z) \cdot E(x, z) \cdot \mathbf{1}[x \neq y] \cdot \mathbf{1}[x \neq z] \cdot \mathbf{1}[y \neq z] \right]$$

\cdot = shorthand for product function application

What does this compute?

GEL: Aggregation example

$$\varphi = \text{agg}_{x,y,z}^{\text{sum}} \left[\mathbf{1}[y = y] \mid E(x, y) \cdot E(y, z) \cdot E(x, z) \cdot \mathbf{1}[x \neq y] \cdot \mathbf{1}[x \neq z] \cdot \mathbf{1}[y \neq z] \right]$$

\cdot = shorthand for product function application

What does this compute? 6 x Triangle count

GEL: Aggregation example

$$\varphi = \text{agg}_{x,y,z}^{\text{sum}} \left[\mathbf{1}[y = y] \mid E(x, y) \cdot E(y, z) \cdot E(x, z) \cdot \mathbf{1}[x \neq y] \cdot \mathbf{1}[x \neq z] \cdot \mathbf{1}[y \neq z] \right]$$

\cdot = shorthand for product function application

What does this compute? 6 x Triangle count

Let us see a more elaborate example

Message Passing Neural Networks

We define $\varphi^{(0)}(x_1) := \mathbf{1}[x_1 = x_1]$

Then for $t > 0$, we get

$$\varphi^{(t)}(x_1) := \text{Upd}^{(t)} \left(\varphi^{(t-1)}(x_1), \text{agg}_{x_2}^{\Theta^{(t)}} [\varphi^{(t-1)}(x_2) \mid E(x_1, x_2)] \right)$$

For **readout** layer, we get

$$\varphi := \text{agg}_{x_1}^{\Theta} \left(\varphi^{(L)}(x_1) \mid \mathbf{1}[x_1 = x_1] \right)$$

dummy guard

edge guarded aggregation

This encompasses the **GNNs 101**

Fragments of GEL

- ❖ $\text{GEL}_k(\Omega, \Theta)$: k variable fragment of GEL with functions in Ω and aggregations in Θ
- ❖ $\text{GGEL}_2(\Omega, \Theta)$: 2 variable fragment GEL with edge guarded aggregation only $\varphi(x) = \text{agg}_y^\Theta[\varphi_1 \mid E(x, y)]$

MPNNs without readout phase fit in $\text{GGEL}(\Omega, \Theta)$

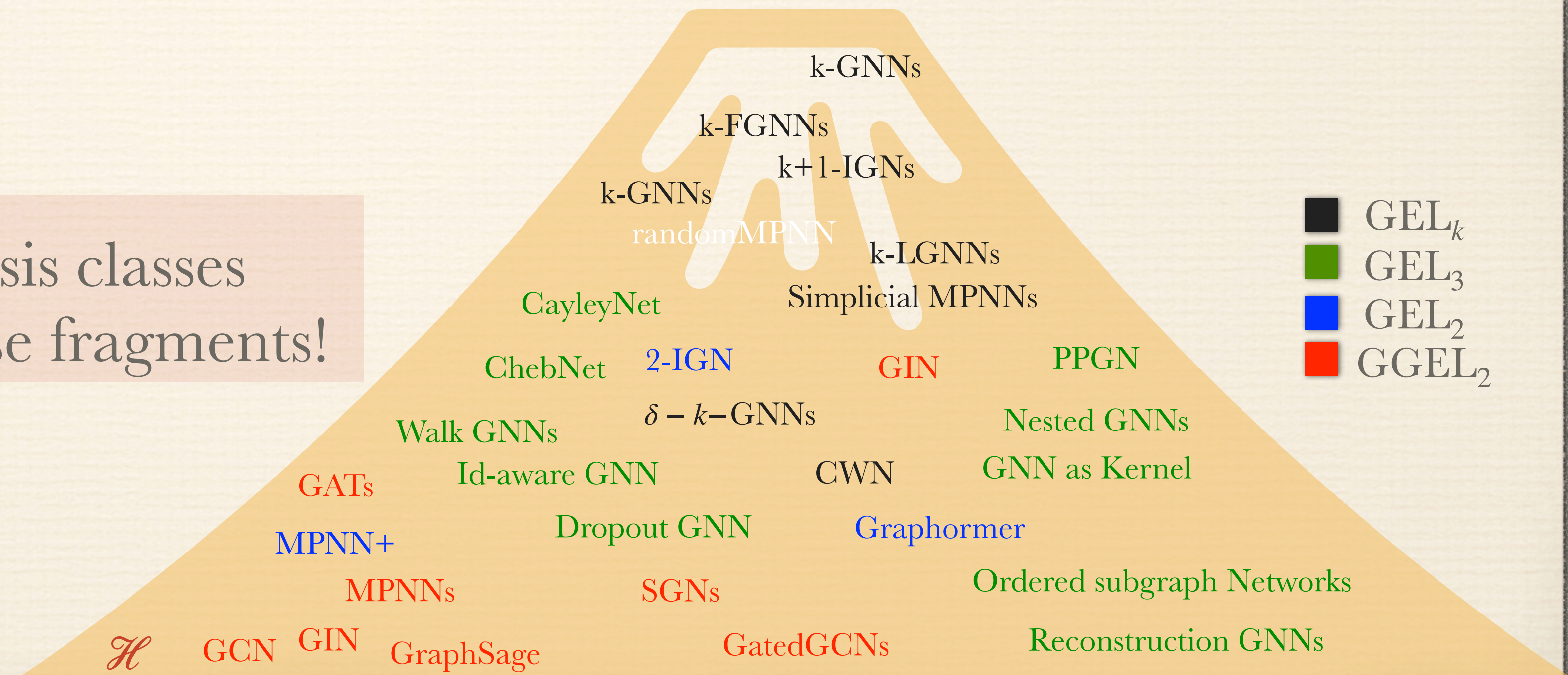
MPNNs including readout phase fit in $\text{GEL}_2(\Omega, \Theta)$

Fragments of GEL

- ❖ $GEL_k(\Omega, \Theta)$: k variable fragment of GEL with functions in Ω and aggregations in Θ
- ❖ $GGEL_2(\Omega, \Theta)$: 2 variable fragment GEL with edge guarded aggregation only



Most hypothesis classes fit in one of those fragments!



Graph Convolutional Networks

Use $D^{-1/2}(I + A)D^{-1/2}$ as propagation matrix

$$\varphi(x_1) := F(\text{agg}_{x_2}^{\text{sum}}[\mathbf{1}[x_2 = x_2] | E(x_1, x)]) \text{ with } F : \mathbb{R} \rightarrow \mathbb{R} : x \mapsto \frac{1}{\sqrt{1 + x}}$$

Hence, $\xi_\phi(G, v) = \frac{1}{\sqrt{1 + \text{deg}_G(v)}}$ and we can use

$\psi(x_1, x_2) := \varphi(x_1)(\mathbf{1}[x_1 = x_2] + E(x_1, x_2))\varphi(x_2)$ as the “adjacency” matrix in the MPNN expressions we have seen before.

$$\text{GCN} \in \text{GGEL}_2(\Omega, \Theta)$$

Simplified GCNs

- ❖ Uses path information $\mathbf{A}^p \mathbf{F}^{(0)}$ in a single layer.
- ❖ For $p = 3$ and for $\varphi^{(0)}(x_1)$ initial feature:

$$\psi(x_1) := \text{agg}_{x_2}^{\text{sum}} \left[\text{agg}_{x_1}^{\text{sum}} \left[\text{agg}_{x_2}^{\text{sum}} \left[\varphi^{(0)}(x_2) \mid E(x_1, x_2) \right] \mid E(x_2, x_1) \right] \mid E(x_1, x_2) \right]$$

$$\text{SGNs} \in \text{GGEL}_2(\Omega, \Theta)$$

k-GNNs

$$\xi^{(t)}(x_1, \dots, x_k) := \sigma \left(\xi^{(t-1)}(x_1, \dots, x_k) \mathbf{W}_1^{(t)} + \left(\sum_{i=1}^k \text{agg}_y^{\text{sum}} [\xi^{(t)}(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_k)] \right) \mathbf{W}_2^{(t)} \right)$$

k -vertex embedding Activation Function Weight matrix Global aggregation Weight matrix

$$k\text{-GNNs} \in \text{GEL}_{k+1}(\Omega, \Theta)$$

k-Folklore GNNs (k-FGNs)

$$\xi^{(t)}(x_1, \dots, x_k) := \text{MLP}_1^{(t)}\left(\text{agg}_y^{\text{sum}}\left[\prod_{i=1}^k \text{MLP}_2^{(t)}(\xi^{(t-1)}(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_k))\right]\right)$$

k -vertex embedding

Global aggregation

$$k\text{-FGNs} \in \text{GEL}_k(\Omega, \Theta)$$

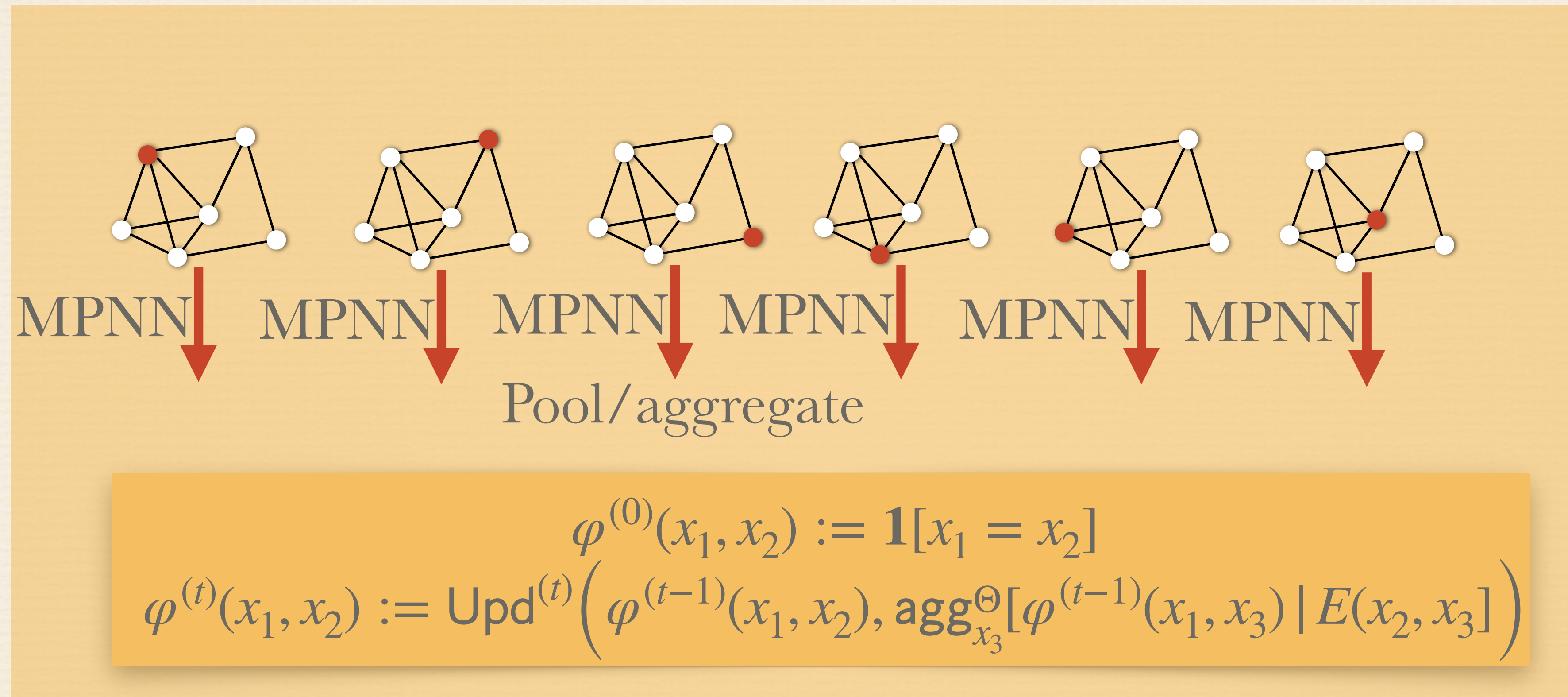
Subgraph count GNNs

- ❖ Use **count of subgraphs** to augment MPNNs
 - ❖ **homomorphism count** $\text{hom}(P^r, G^v)$ for rooted motif P ,
 - ❖ **subgraph iso count** $\text{sub}(P^r, G^v)$ for rooted motif P
- ❖ If motif has **tree width k** then $\text{hom}(P^r, G^v)$ can be computed using **$k+1$ variables**.
- ❖ For example, $(G, v) \mapsto \text{hom}\left(\triangle, G^v\right)$ can be expressed as

$$\varphi(x_1) := \text{agg}_{x_2}^{\text{sum}} \text{agg}_{x_3}^{\text{sum}} [E(x_1, x_2)E(x_1, x_3)E(x_2, x_3)(\mathbf{1}[x_1 = x_1] - \mathbf{1}[x_1 = x_2]) \\ (\mathbf{1}[x_1 = x_1] - \mathbf{1}[x_1 = x_3])(\mathbf{1}[x_1 = x_1] - \mathbf{1}[x_2 = x_3])]$$

Tree width $k \mapsto \text{GEL}_{k+1}(\Omega, \Theta)$

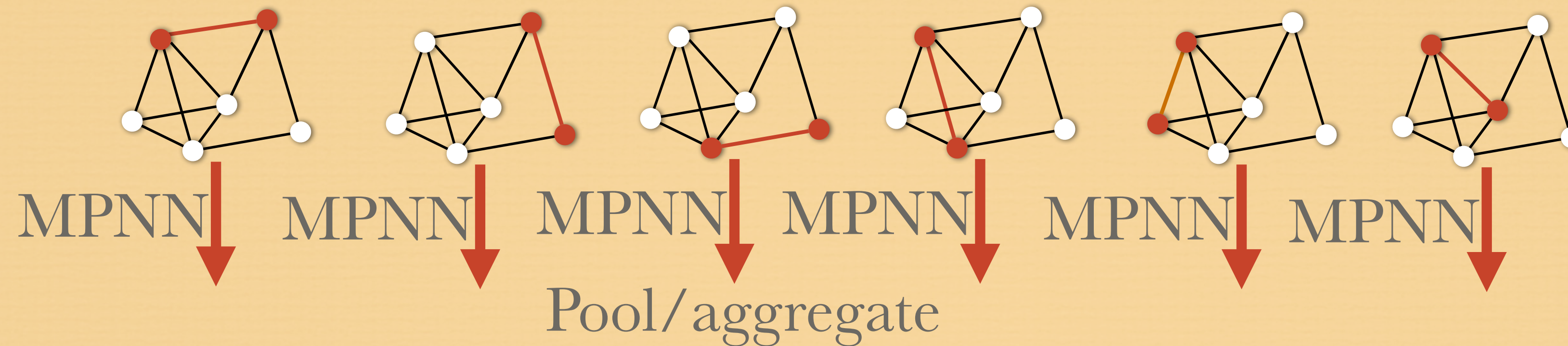
Subgraph GNNs: vertices



3 variables $\mapsto \text{GEL}_3(\Omega, \Theta)$

Bevilacqua et al.: *Equivariant subgraph aggregation network* (2022)
 Cotta et al.: *Reconstruction for powerful graph representations* (2021)
 Bevilacqua et al.: *Understanding and extending subgraph GNNs by rethinking their symmetries* (2022)
 Huang et al.: *Boosting the cycle counting power of graph neural networks with I2-GNNs* (2022)
 Papp et al.: *DropGNN: Random dropouts increase the expressiveness of graph neural networks.* (2021)
 Qian et al.: *Ordered subgraph aggregation networks.* (2022)
 You et al.: *Identity-aware graph neural networks.* (2021)
 Zhang and P. Li. *Nested graph neural networks* (2021)
 Zhao et al.: *From stars to subgraphs: Uplifting any GNN with local structure awareness* (2022)

Subgraph GNNs: edges



$$\varphi^{(t)}(x_1, x_2, x_3) := \text{Upd}^{(t)}\left(\varphi^{(t-1)}(x_1, x_2, x_3), \text{agg}_{x_4}^{\Theta}[\varphi^{(t-1)}(x_1, x_2, x_4) \mid E(x_3, x_4)]\right)$$

4 variables $\mapsto \text{GEL}_4(\Omega, \Theta)$

Bevilacqua et al.: *Equivariant subgraph aggregation network* (2022)

Cotta et al.: *Reconstruction for powerful graph representations* (2021)

Bevilacqua et al.: *Understanding and extending subgraph GNNs by rethinking their symmetries* (2022)

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Zhao et al.: *From stars to subgraphs: Uplifting any GNN with local structure awareness* (2022)

Takeaway message #1:

Classification in terms of number of variables

Hypothesis classes: how do they look like?

$h_i = f_{\text{GCRU}}(x_i, \{h_j : j \rightarrow i\}) = C_{\text{GCRU}}(x_i, \sum_{j \rightarrow i} h_j)$

tion of Eq. (4) does not have an analytical solution, Li et al. scheme:

$$h_i^{t+1} = C_{\text{GCRU}}(h_i^t, \tilde{h}_i^t), \quad h_i^{t=0} = x_i \quad \forall i,$$

where $\tilde{h}_i^t = \sum_{j \rightarrow i} h_j^t$.

) is equal to

$$\begin{aligned} z_i^{t+1} &= \sigma(U_z h_i^t + V_z \tilde{h}_i^t) \\ r_i^{t+1} &= \sigma(U_r h_i^t + V_r \tilde{h}_i^t) \\ \tilde{h}_i^{t+1} &= \tanh(U_h(h_i^t \odot r_i^{t+1}) + V_h \tilde{h}_i^t) \\ h_i^{t+1} &= (1 - z_i^{t+1}) \odot h_i^t + z_i^{t+1} \odot \tilde{h}_i^{t+1}, \end{aligned}$$

is injective. We can make ϵ a learnable parameter or a fixed representations as

$$h_v^{(k)} = \text{MLP}^{(k)}\left(\left(1 + \epsilon^{(k)}\right) \cdot h_v^{(k-1)} + \sum_{u \in \mathcal{N}(v)} h_u^{(k-1)}\right).$$

may exist many other powerful GNNs. GIN is one such exam

section 4. Consider the matrix $X \in \mathbb{R}^{n \times m}$ defined by

$$X_{j,i} = (\mathbf{B}_{i,i_1}, \mathbf{B}_{i,i_2}), \quad j \in [n]. \quad (7)$$

Our goal is to compute an output tensor $W \in \mathbb{R}^{n \times k}$, where $W_{i,i_2} = u(X)$.

Consider the multi-index set $\{\alpha \mid \alpha \in [n]^{2m}, |\alpha| \leq n\}$ of cardinality $b = \binom{n+2m-1}{2m-1}$, and write it in the form $\{(\beta, \gamma) \mid \beta, \gamma \in [n]^m, |\beta| + |\gamma| \leq n, l \in \beta\}$.

Now define polynomial maps $\tau_1, \tau_2: \mathbb{R}^n \rightarrow \mathbb{R}^b$ by $\tau_1(x) = (x^{\beta}, l \in \beta)$, and $\tau_2(x) = (x^{\gamma}, l \in \gamma)$. We apply τ_1 to the features of \mathbf{B} , namely $\mathbf{Y}_{i,i_1,i_2} := \tau_1(\mathbf{B}_{i,i_1,i_2})^{\beta}$; similarly, $\mathbf{Z}_{i,i_2,i_1} := \tau_2(\mathbf{B}_{i,i_2,i_1})^{\gamma}$. Now,

$$W_{i,i_2,i_1} := (\mathbf{Z}_{i,i_2,i_1} \cdot \mathbf{Y}_{i,i_1,i_2}) = \sum_{j=1}^n \mathbf{Z}_{i,i_2,i_1} \mathbf{Y}_{j,i_1,i_2} = \sum_{j=1}^n \sum_{\beta} \mathbf{B}_{i,i_1,j}^{\beta} \mathbf{B}_{j,i_2,i_1}^{\gamma} = \sum_{j=1}^n (\mathbf{B}_{j,i_1,i_2}, \mathbf{B}_{i,i_2,i_1})^{\beta, \gamma},$$

where ψ is an entry-wise activation ($s \mapsto \max(0, s)$ for ReLU), $W_{i_1} \in \mathbb{R}^{b \times m}$ are trainable weight matrices and $M_{i_1} \in \mathbb{R}^{b \times b}$, $U_{i_1} \in \mathbb{R}^{b \times b-1}$, and $O_{i_1} \in \mathbb{R}^{b \times b-1}$ are some choice of adjacency matrices for the simplicial complex. These could be the Hodge Laplacian matrix L_{i_1} and the corresponding boundary matrices $B_{i_1}^1, B_{i_1}^2$, or one of their variants (e.g. normalised).

It is convenient to write the entire layer output in standard form. Using Roth's lemma and concatenating over n we can write (11) as (details in Appendix B)

$$H^{i_1} = \psi(W H^{i_1}), \quad (12)$$

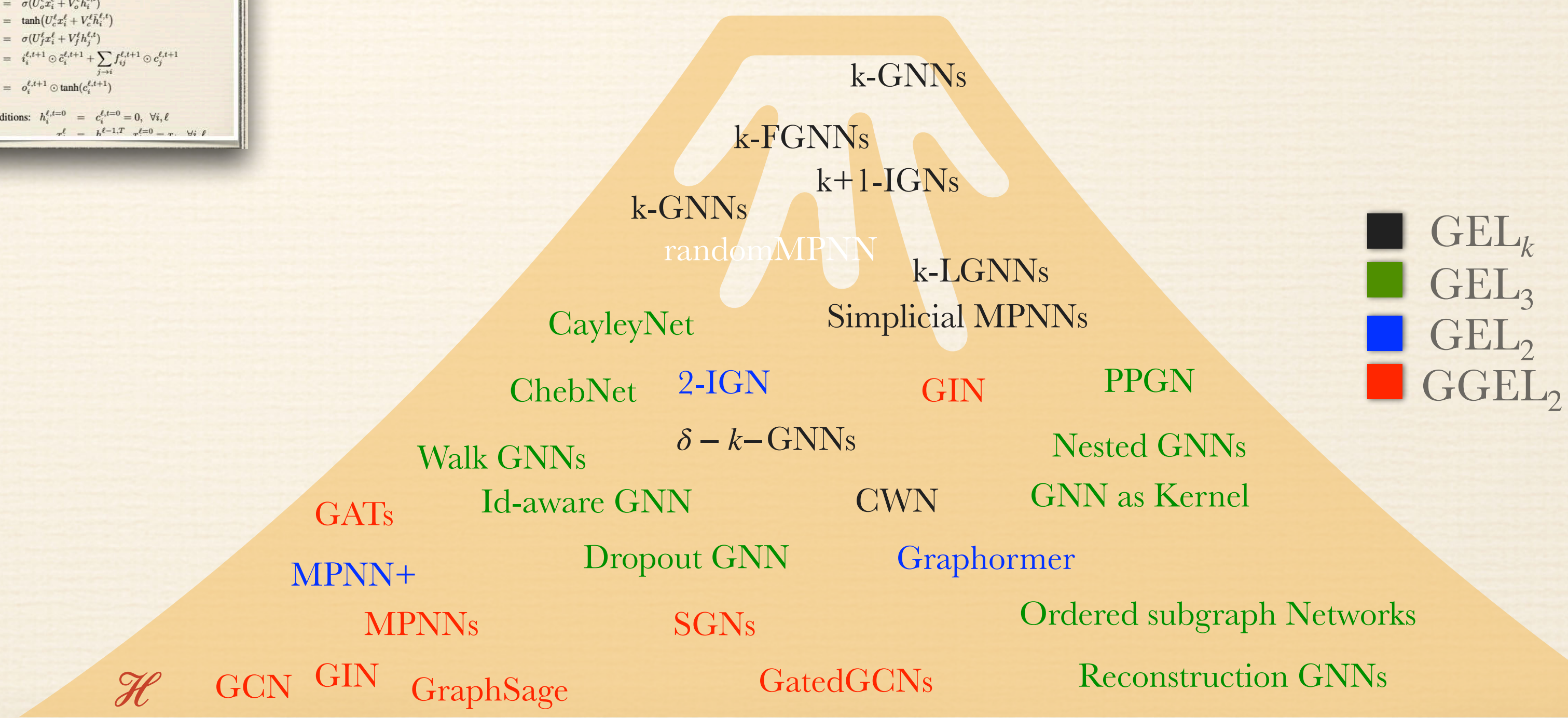
where $H^{i_1} = \text{vec}([H^{i_1} H^{i_1} \dots H^{i_1}]) \in \mathbb{R}^N$, $N = \sum_{i_1=0}^m S_{i_1} d_{i_1}$, $H^{i_1} = \text{vec}([H^{i_1} H^{i_1} \dots H^{i_1}]) \in \mathbb{R}^M$, $M = \sum_{i_1=0}^m S_{i_1} m$, and

$$W = \begin{bmatrix} W_{i_1}^1 \otimes M_{i_1} & W_{i_1}^2 \otimes O_{i_1} \\ W_{i_1}^2 \otimes U_{i_1} & W_{i_1}^1 \otimes M_{i_1} \\ W_{i_1}^1 \otimes O_{i_1} & W_{i_1}^2 \otimes M_{i_1} \end{bmatrix}. \quad (13)$$

iterative process to solve Eq. (10): At layer ℓ , for $t = 0, 1, \dots, T$

$$\begin{aligned} \tilde{h}_i^{\ell,t} &= \sum_{j \rightarrow i} h_j^{\ell,t}, \\ i_i^{\ell,t+1} &= \sigma(U_i^{\ell} x_i^{\ell,t} + V_i^{\ell} \tilde{h}_i^{\ell,t}), \\ o_i^{\ell,t+1} &= \sigma(U_o^{\ell} x_i^{\ell,t} + V_o^{\ell} \tilde{h}_i^{\ell,t}), \\ c_i^{\ell,t+1} &= \tanh(U_c^{\ell} x_i^{\ell,t} + V_c^{\ell} \tilde{h}_i^{\ell,t}), \\ f_{ij}^{\ell,t+1} &= \sigma(U_f^{\ell} x_i^{\ell,t} + V_f^{\ell} h_j^{\ell,t}), \\ c_i^{\ell,t+1} &= i_i^{\ell,t+1} \odot c_i^{\ell,t+1} + \sum_{j \rightarrow i} f_{ij}^{\ell,t+1} \odot c_j^{\ell,t+1}, \\ h_i^{\ell,t+1} &= o_i^{\ell,t+1} \odot \tanh(c_i^{\ell,t+1}) \end{aligned}$$

and initial conditions: $h_i^{\ell,t=0} = c_i^{\ell,t=0} = 0, \forall i, \ell$
 $\ast \ell = h^{\ell-1,T} \ast \ell=0 = \dots \forall i, \ell$



How to compare different classes?

- ❖ How to compare such embedding classes **theoretically**?
- ❖ How to bring **order to the chaos**?

Which language?

1. See graph embedding methods as queries in some **query language**

3. **Transfer understanding back** to graph learning world

2. **Analyse expressive power** of query language



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- ❖ How to bring **order to the chaos**?

Which language?

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GEL_k
 $GGEL_2$

3. **Transfer understanding back** to graph learning world

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Expressive power

Distinguishing power

- ❖ Which **inputs** can be **separated/distinguished** by embeddings in \mathcal{H} ?
- ❖ Captured by the following equivalence relation on $\mathcal{G} \times \mathcal{V}^p$:

$$\rho(\mathcal{H}) := \{(G, \mathbf{v}, H, \mathbf{w}) \mid \forall \xi \in \mathcal{H} : \xi(G, \mathbf{v}) = \xi(H, \mathbf{w})\}$$

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❖ **Strongest power**: \mathcal{H} powerful enough to detect non-isomorphic graphs: $\rho(\mathcal{H})$ only contains **isomorphic pairs**

❖ **Weakest power**: \mathcal{H} cannot differentiate any two graphs: $\rho(\mathcal{H})$ contains **all pairs** of graphs.

Distinguishing power

- ❖ Allows for comparing **different classes of** embeddings methods

$$\rho(\text{methods}_1) \subseteq \rho(\text{methods}_2)$$

methods₁ is more powerful than methods₂
methods₂ is bounded by methods₁ in power

$$\rho(\text{methods}_1) = \rho(\text{methods}_2)$$

Both methods are as powerful

- ❖ Allows for comparing embedding methods with **algorithms, logic, ...**
on graphs

Expressive power in ML community

- ❖ Focus has been on **characterising the distinguishing power** of classes \mathcal{H} of embedding methods.
- ❖ Hopefully, characterisations of $\rho(\mathcal{H})$ shed light on what **graph properties** a learning method in \mathcal{H} can detect/use.

Logic

- ❖ First-order logic with k variables and counting quantifiers (C_k).

$k=2$

$$\varphi(x) = \exists^{\leq 5} y \left(E(x, y) \wedge \exists^{\geq 2} x \left(E(y, x) \wedge L_a(x) \right) \right)$$

binary edge predicate

unary label predicate

- ❖ Given graph G , vertex $v \in V_G$ satisfies φ : It has at most 5 neighbours each with at least two neighbours labeled “a”

- ❖ Guarded fragment GC_2 of C_2

only existential quantification for the form $\exists^{\geq n} y (E(x, y) \wedge \varphi(y))$

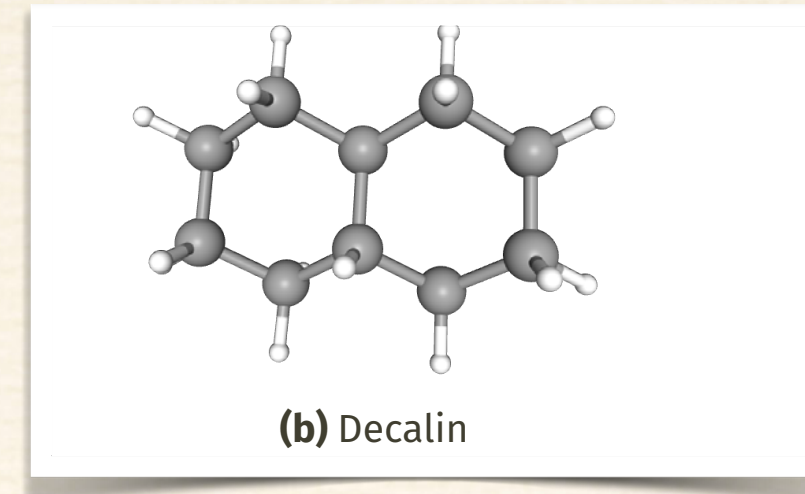
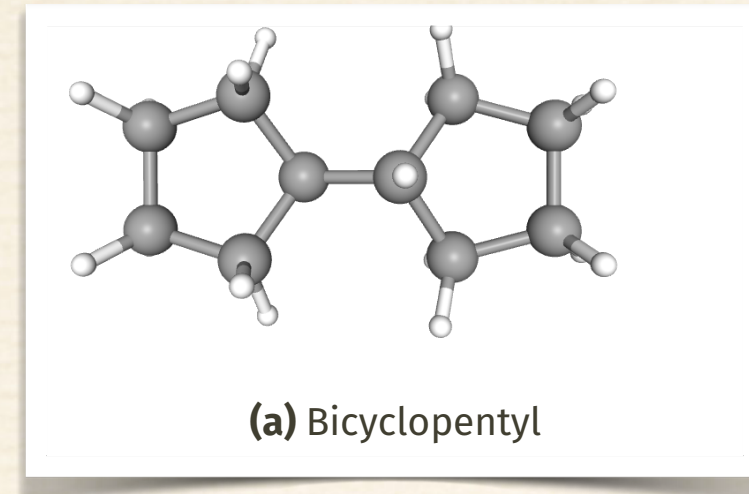
Logic

- ❖ We can consider $\rho(\mathbf{C}_k)$ and $\rho(\text{GC}_2)$

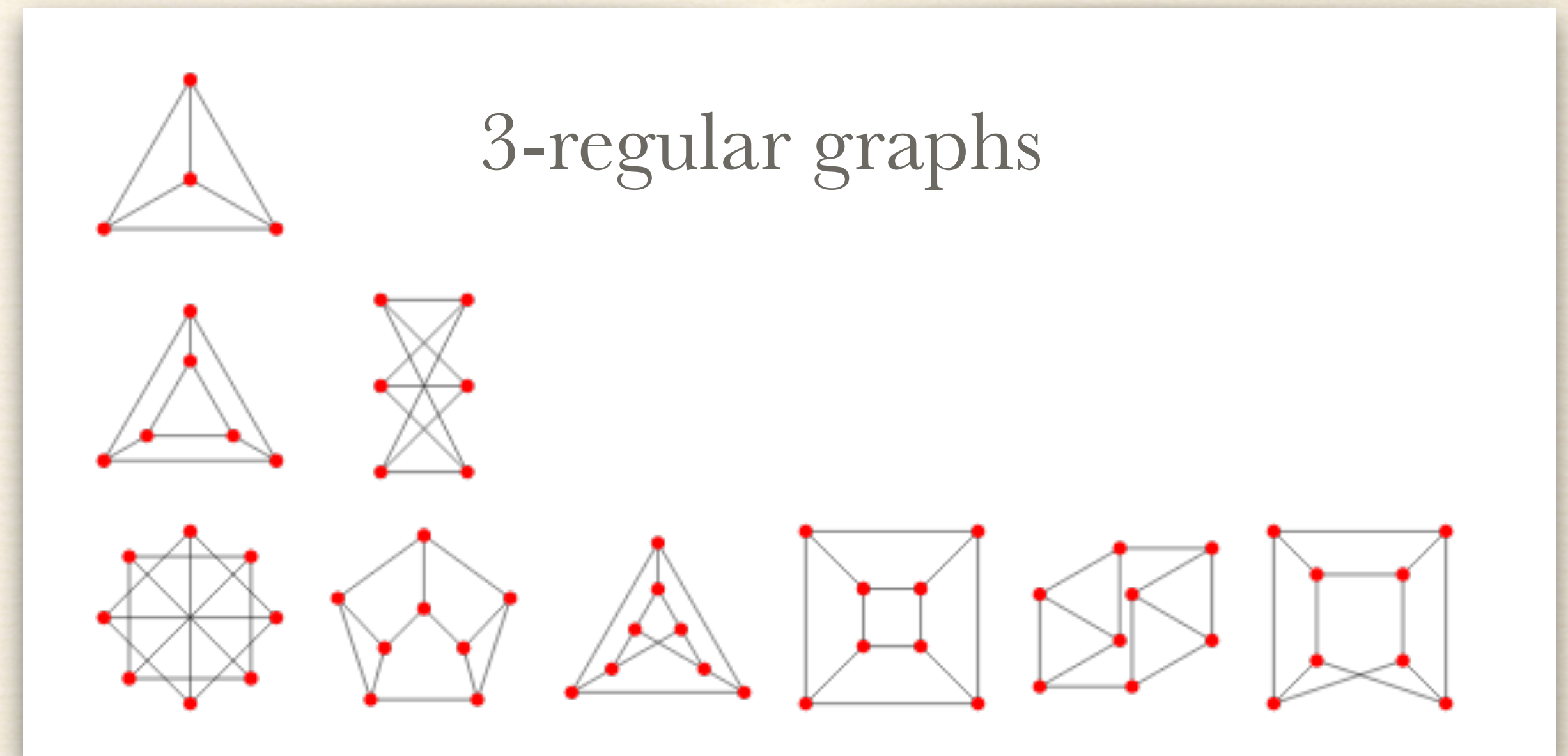
$$\rho(\mathbf{C}_k) := \{(G, \mathbf{v}, H, \mathbf{w}) \mid \forall \varphi \in \mathbf{C}_k : (G, \mathbf{v}) \models \varphi \iff (H, \mathbf{w}) \models \varphi\}$$

- ❖ The **distinguishing power** of these logics is well **understood**

$$\rho(C_2)$$



- ❖ Cannot distinguish **d-regular graphs**
- ❖ Cannot **count cycles** (triangles)
- ❖ **Only tree information**



Expressive power of GEL: Main result

- ❖ The following results follow from standard analysis of aggregate query languages: **all real number arithmetic can be eliminated.**

Theorem (Xu et al. 2019, Morris et al. 2019, G. and Reutter 2022)

$$\rho(\text{GGEL}(\Omega, \Theta)) = \rho(\text{GC}_2)$$

Theorem (G. and Reutter 2022)

$$\rho(\text{GEL}_k(\Omega, \Theta)) = \rho(\text{C}_k)$$

- ❖ **Lower bounds:** Ω contains linear combinations, concatenation, product (or activation functions) and Θ contains summation

Xu, Hu, Leskovec, Jegelka: *How powerful are graph neural networks?* (2019)

Morris, Ritzert, Fey, Hamilton, Lenssen, Rattan, Grohe: *Weisfeiler and Leman go neural: Higher-order graph neural networks.* (2019)

Hella, Libkin, Nurmonen, Wong: *Logics with Aggregates.* (2001)

Cai, Fürer, Immerman: *An optimal lower bound on the number of variables for graph identification.* (1992)

G., Reutter: *Expressiveness and approximation properties of graph neural networks.* (2022)

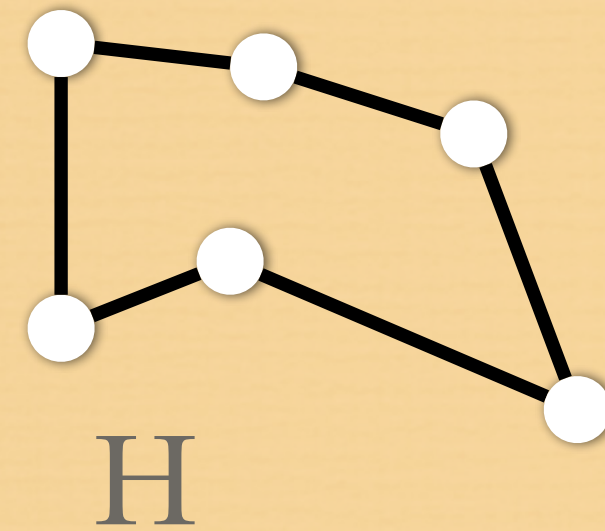
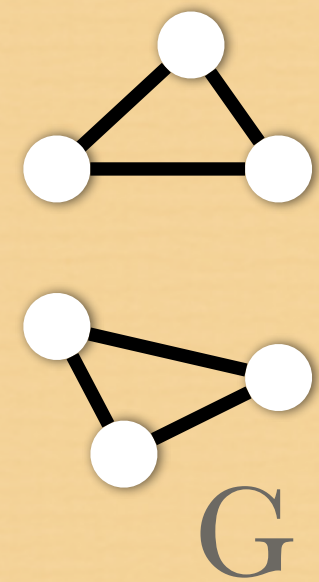
M. Grohe: *The logic of graph neural networks.* (2021)

GNN 101

Theorem (Morris et al. 2019)

$$\rho(\text{GNN101}) = \rho(C_2)$$

GNN 101s, MPNNs are pretty weak



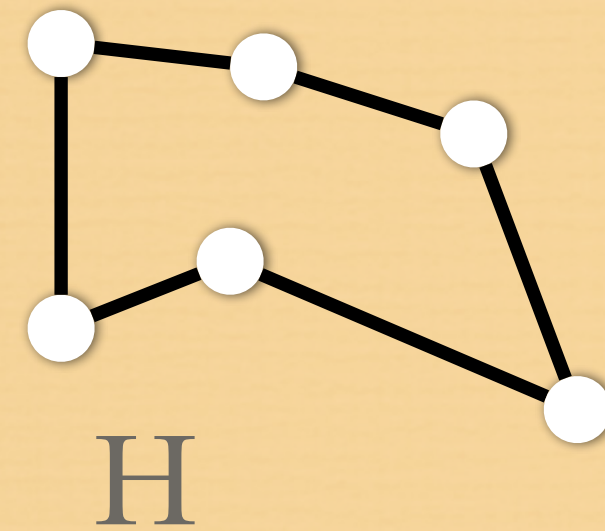
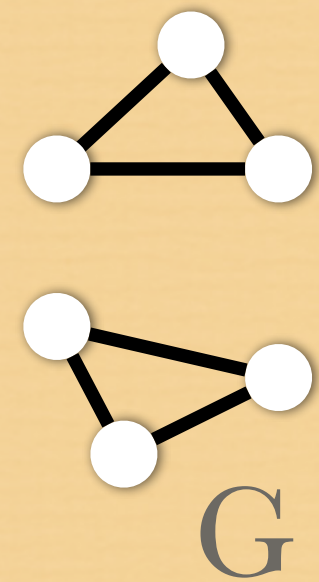
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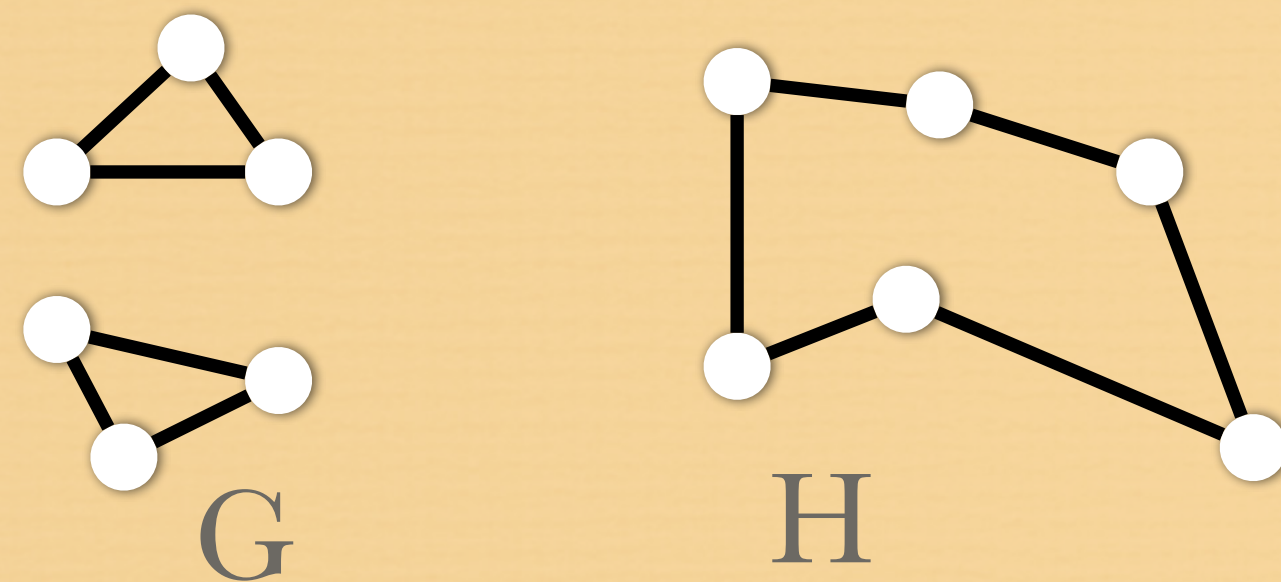
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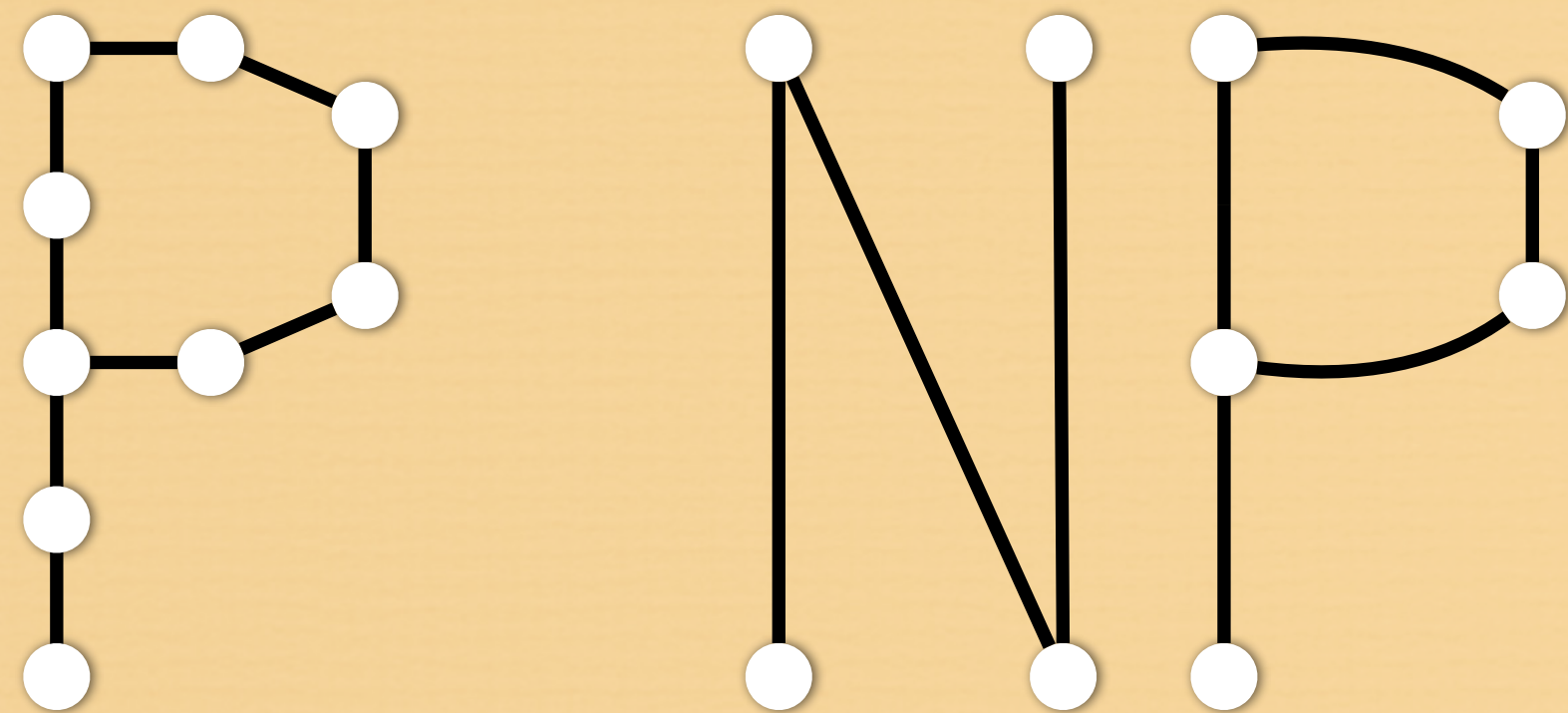
G and H are known to be indistinguishable by \mathbb{C}_2

$$\Rightarrow (G, H) \in \rho(\mathbb{C}_2) = \rho(\text{GNN101})$$

GNN 101

Theorem (Morris et al. 2019)

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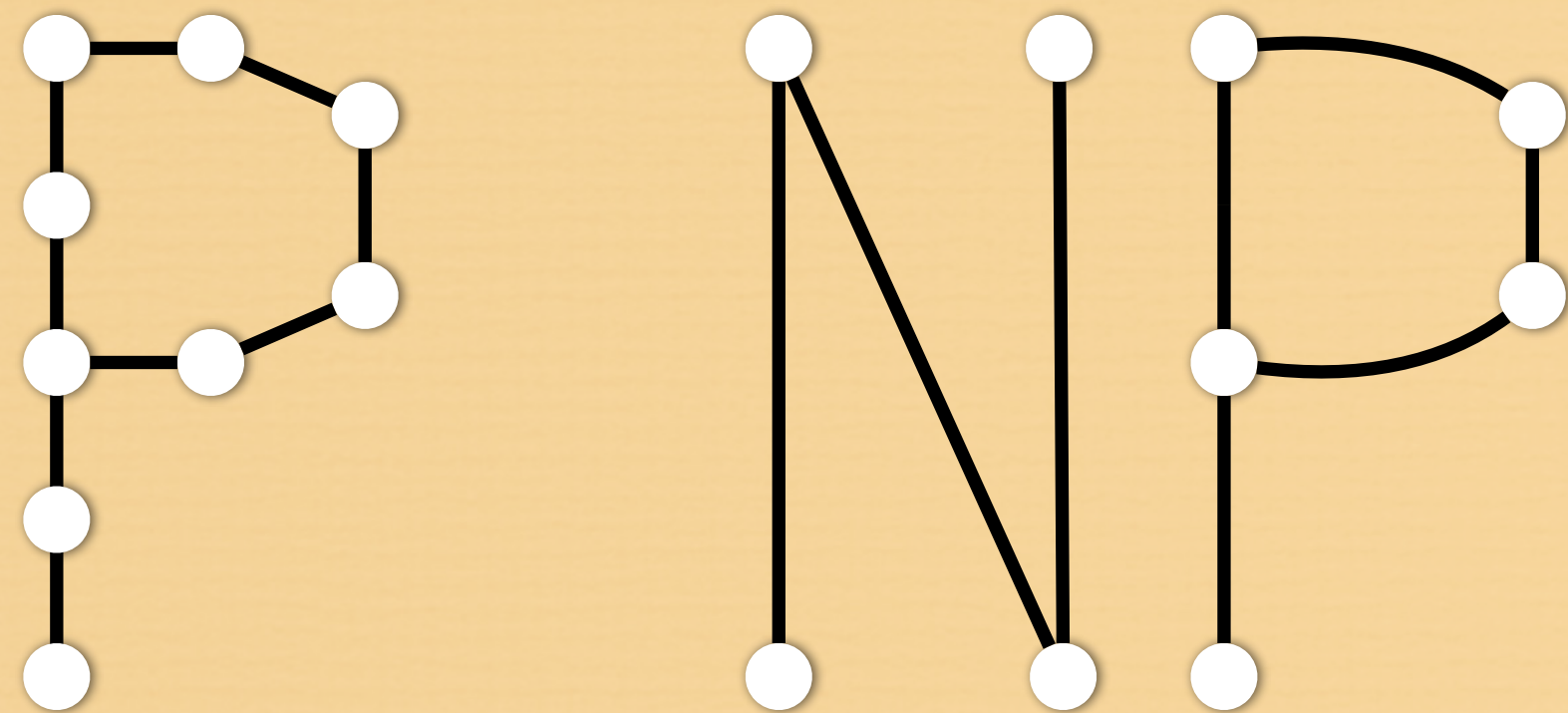


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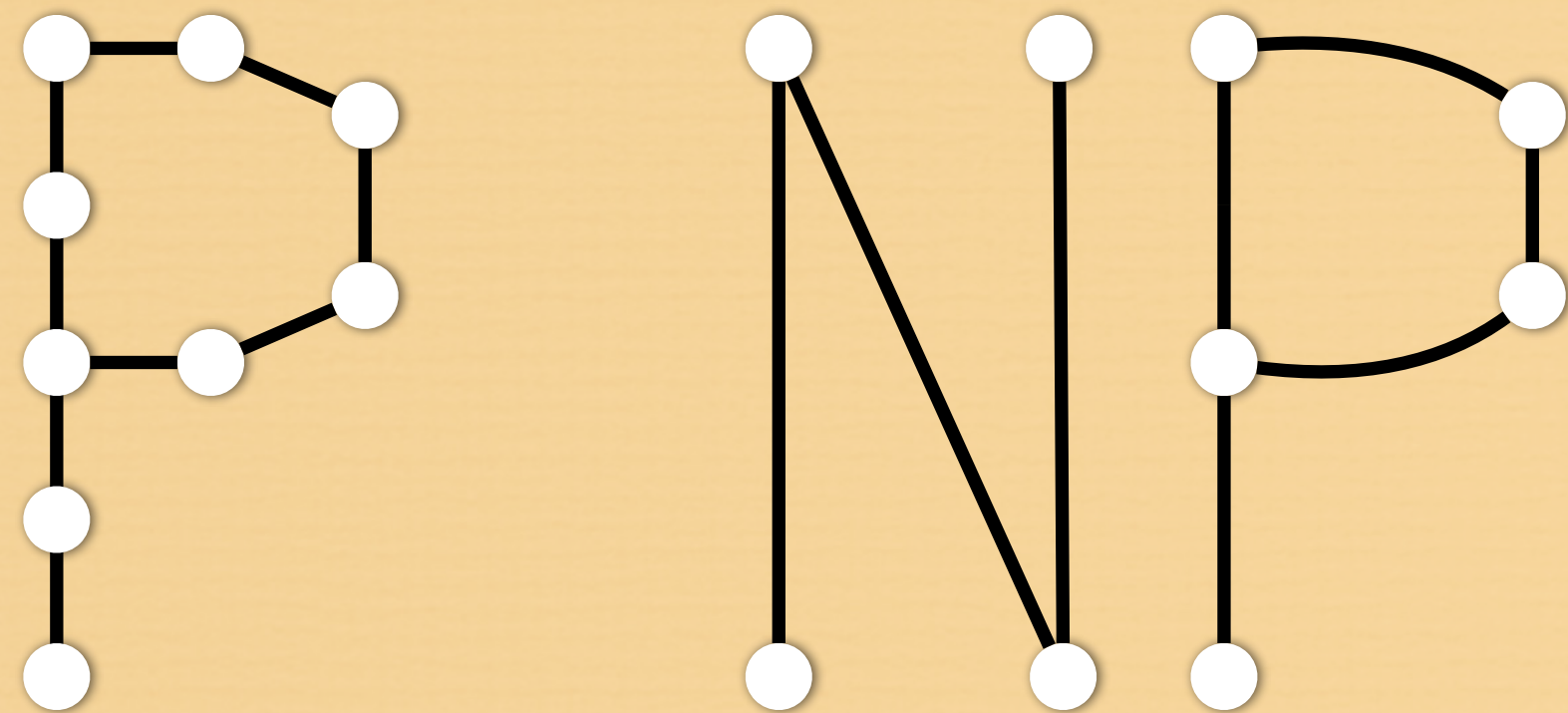
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GNN 101

Theorem (Morris et al. 2019)

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Can we train a GNN101 such that P embeds **differently** from NP?

YES!

single degree one node

P satisfies $\exists^{=1}x \exists^{=1}y E(x, y)$ but NP does not

\Downarrow

$(P, NP) \notin \rho(\mathbb{C}_2) \Rightarrow (P, NP) \notin \rho(\text{GNN101})$

Consequences

- ❖ If embedding method M can be **cast** in $\text{GEL}_k(\Omega, \Theta)$ then $\rho(\mathbf{C}_k) \subseteq \rho(M)$
- ❖ If embedding method M can also **encode formulas** in \mathbf{C}_k then $\rho(\mathbf{C}_k) \supseteq \rho(M)$

Message Passing Neural Networks

We define $\varphi^{(0)}(x_1) := \mathbf{1}[x_1 = x_1]$
Then for $t > 0$, we get

$$\varphi^{(t)}(x_1) := \text{Upd}^{(t)}\left(\varphi^{(t-1)}(x_1), \text{agg}_{x_2}^{\Theta^{(t)}}[\varphi^{(t-1)}(x_2) | E(x_1, x_2)]\right)$$

For

k-GNNs

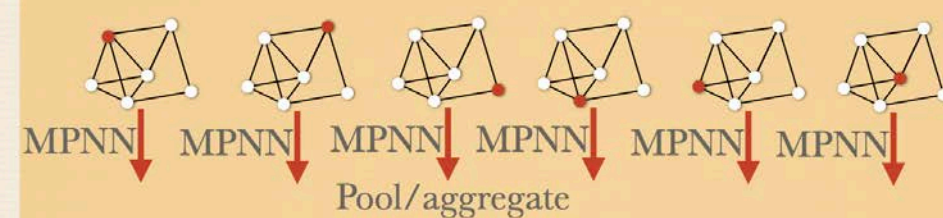
$$\xi^{(t)}(x_1, \dots, x_k) := \sigma\left(\xi^{(t-1)}(x_1, \dots, x_k) \mathbf{W}_1^{(t)} + \left(\sum_{i=1}^k \text{agg}_{y_i}^{\text{sum}}[\xi^{(t)}(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_k)] \mathbf{W}_2^{(t)}\right)\right)$$

This

Activation Function Weight matrix Weight matrix

k-vertex embed

Subgraph GNNs: vertices

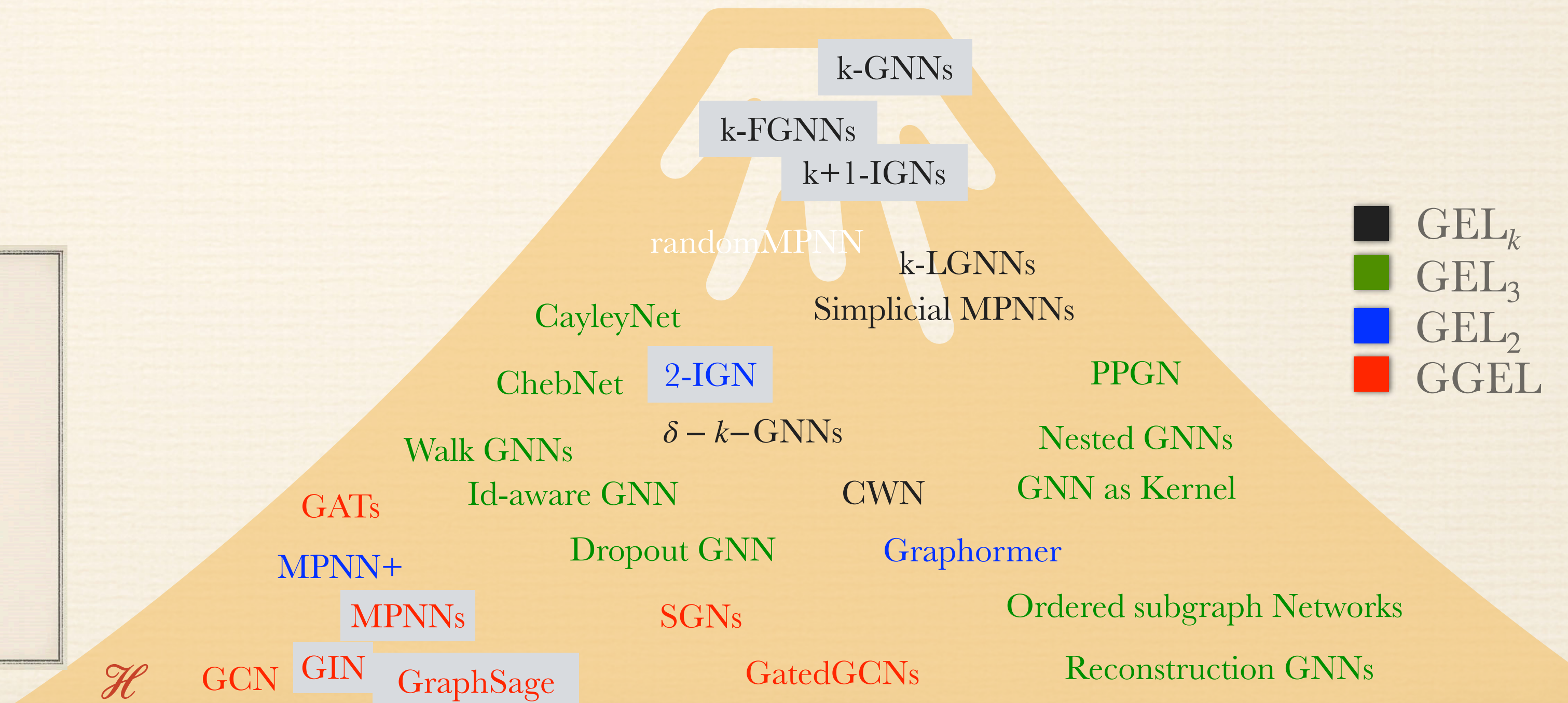


$$\varphi^{(0)}(x_1, x_2) := \mathbf{1}[x_1 = x_2]$$

$$\varphi^{(t)}(x_1, x_2) := \text{Upd}^{(t)}\left(\varphi^{(t-1)}(x_1, x_2), \text{agg}_{x_3}^{\Theta}[\varphi^{(t-1)}(x_1, x_3) | E(x_2, x_3)]\right)$$

3 variables $\mapsto \text{GEL}_3(\Omega, \Theta)$

Bevilacqua et al.: Equivariant subgraph aggregation network (2022)
Catta et al.: Reconstruction for powerful graph representations (2021)
Bevilacqua et al.: Understanding and extending subgraph GNNs by rethinking their symmetries (2022)
Huang et al.: Boosting the cycle counting power of graph neural networks with IZ-GNN (2022)
Papp et al.: DropGNN: Random drops increase the expressiveness of graph neural networks (2021)
Qian et al.: Ordered subgraph aggregation networks (2022)
You et al.: Identity-aware graph neural networks (2021)
Zhang and P. Li: Nested graph neural networks (2021)
Zhao et al.: From stars to subgraphs: Unifying any GNN with local structure awareness (2022)



What else can we say?

$$\rho(\text{MPNNs}) = \rho(\text{C}_2)$$

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Other - more insightful - characterisations?

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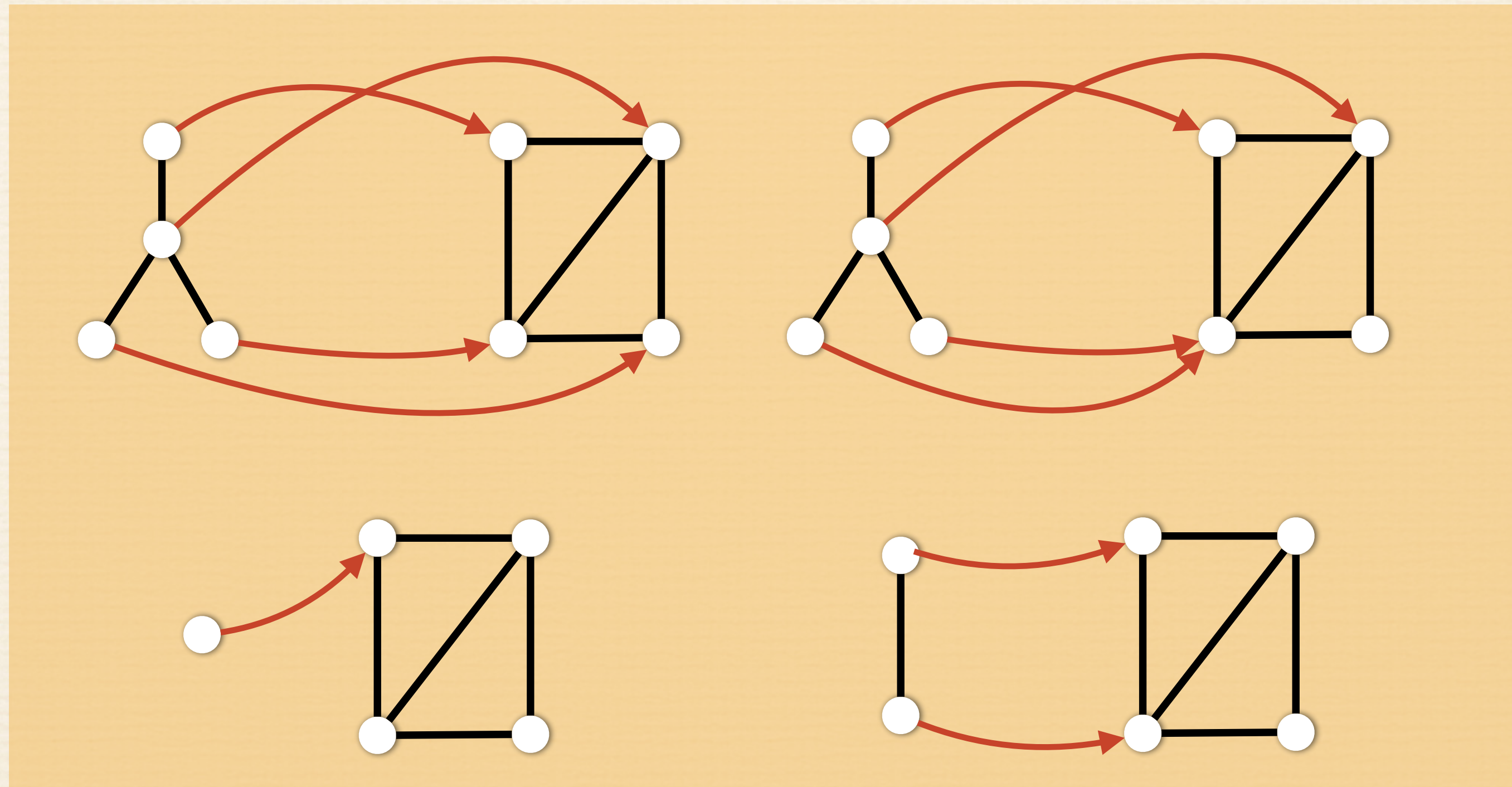


Other - more insightful - characterisations?

homomorphism counts

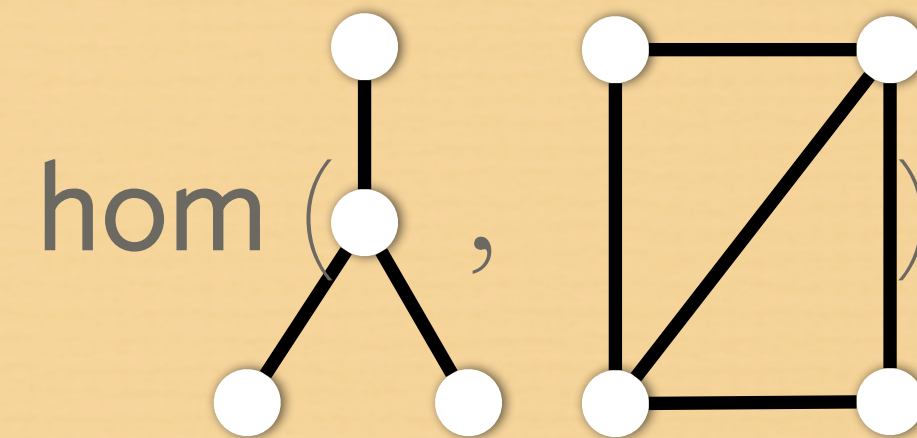
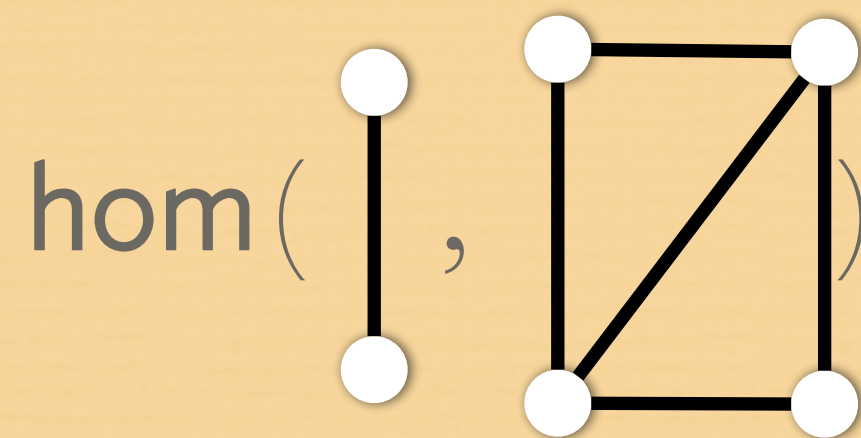
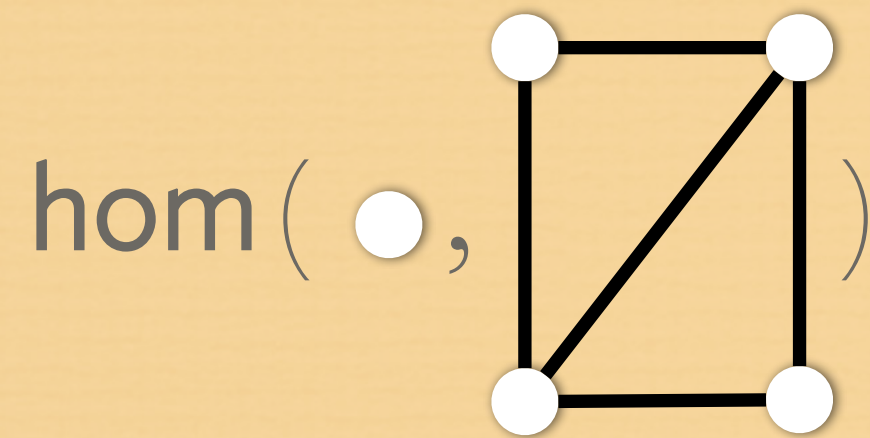
Homomorphisms

- ❖ Let $P = (V_P, E_P, L_P)$ and $G = (V_G, E_G, L_G)$ be graphs.
- ❖ A function $h : V_P \rightarrow V_G$ is a **homomorphism** if it is **edge preserving** $(v, w) \in E_P \Rightarrow (h(v), h(w)) \in E_G$ and **label preserving**.



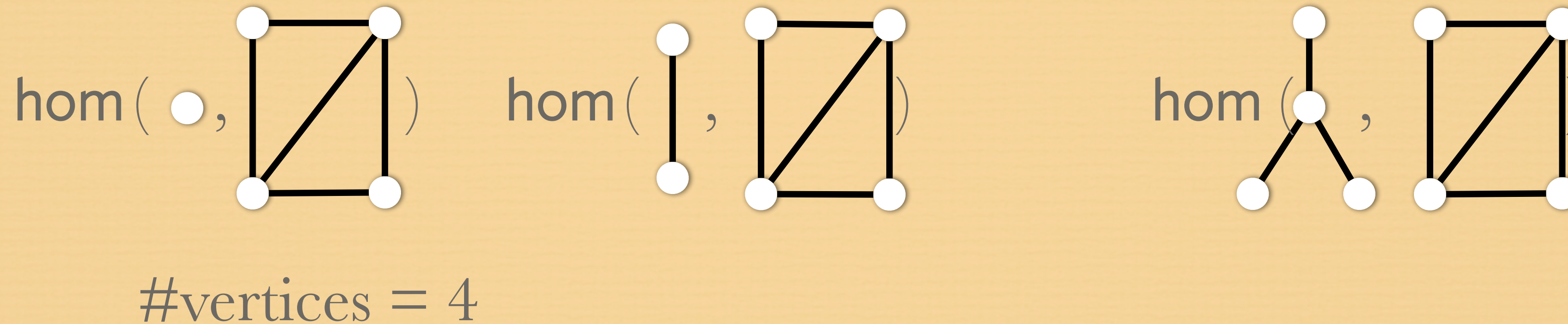
Homomorphism counts

- ❖ Define $\text{HOM}(P, G) := \{ \text{all homomorphisms from } P \text{ to } G \}$
- ❖ Define $\text{hom}(P, G) := |\text{HOM}(P, G)|$.



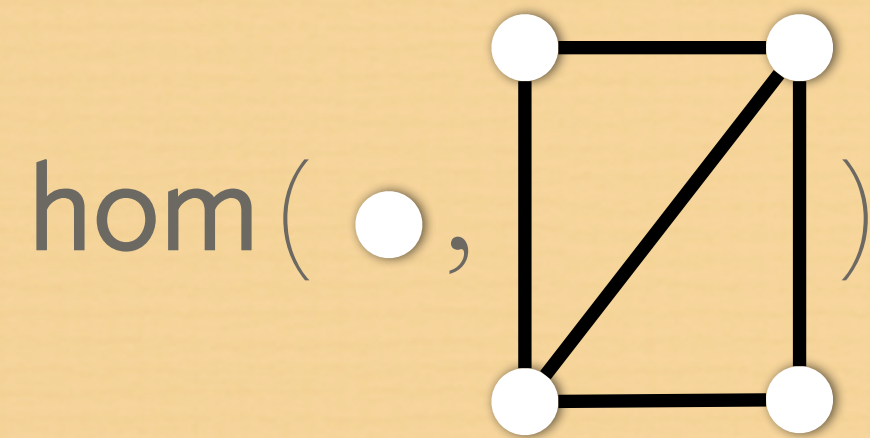
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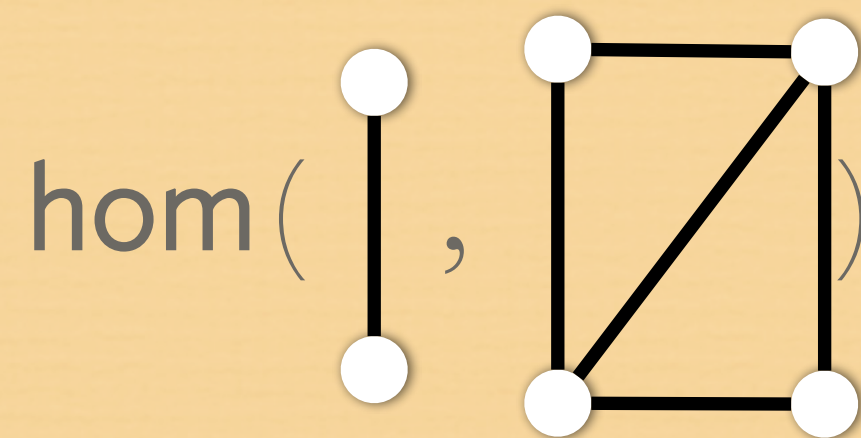


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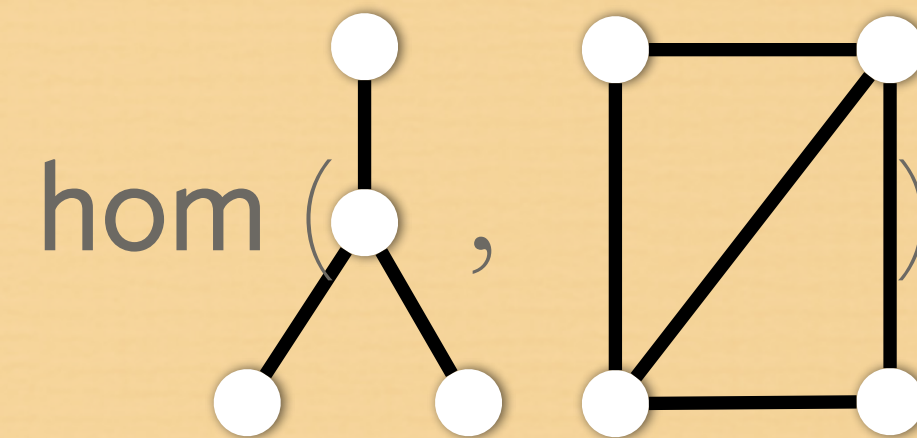
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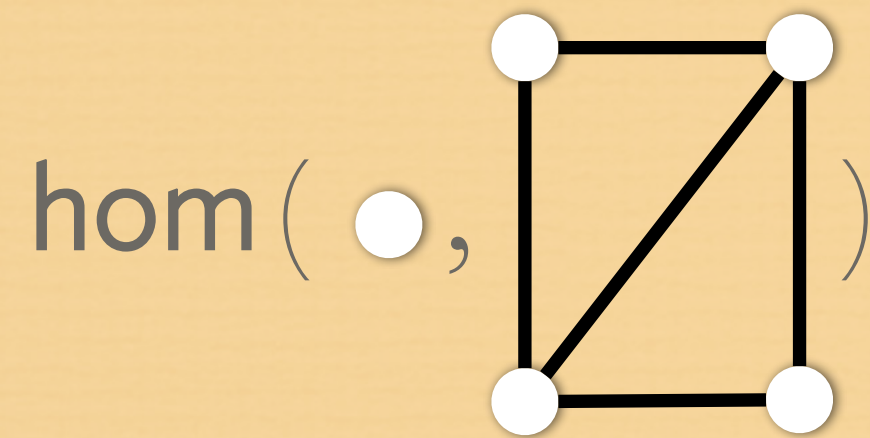


2#edges = 10

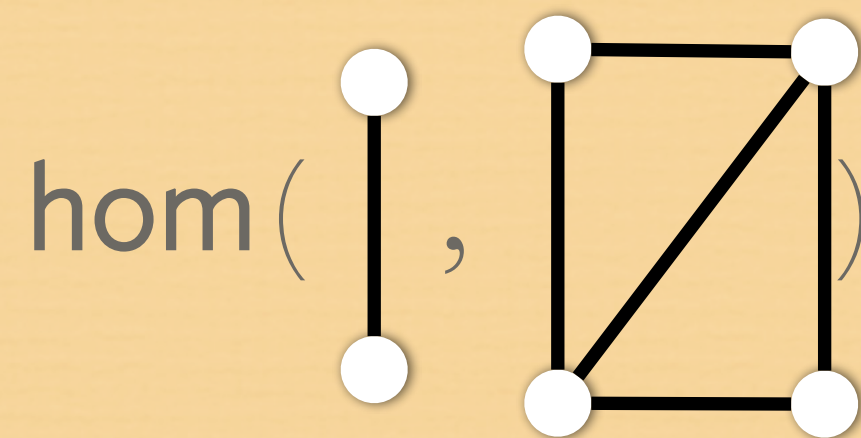


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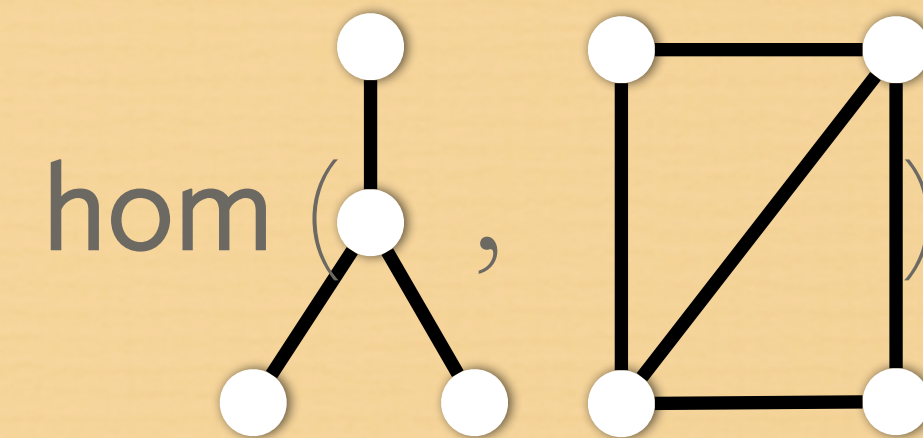
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$$70 = 2 \cdot 2^3 + 2 \cdot 3^3$$

Graph isomorphisms and homomorphisms

Theorem (Lovász 1967)

Two graph G and H are isomorphic if and only if
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Homomorphism count information is very insightful and a complete invariant.

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What if we do not consider all graphs P ?

Homomorphism count vectors

- ❖ We can consider $\rho(\mathcal{P})$ for a set of graphs \mathcal{P} :

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Beautiful characterisations

Theorem (Dell et al. 2019, Dvorák 2010)

$(G, H) \in \rho(\mathbb{C}_2)$
if and only if
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Important class of
MPNNs can only detect
tree-based information

Z. Dvorák: *On recognizing graphs by numbers of homomorphisms.* (2010)

Dell, Grohe, Rattan: *Lovász meets Weisfeiler and Leman.* (2018)

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All embedding methods in $\text{GEL}_2(\Omega, \Theta)$ can only distinguish graphs based on **tree information!**

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based on **treewidth $k - 1$ pattern information!**

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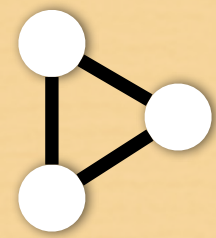
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Treewidth

- ❖ A **k-tree** is a graph that can be obtained starting from a $(k+1)$ -clique and then iteratively adding a vertex connected to a k -clique

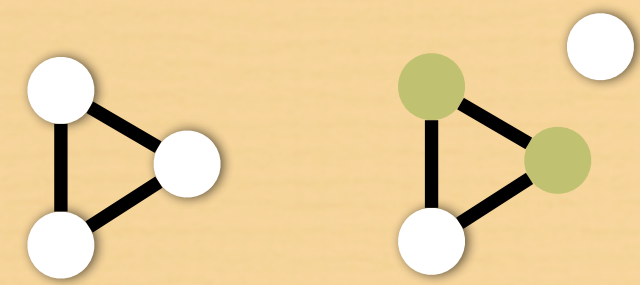
$k=2$



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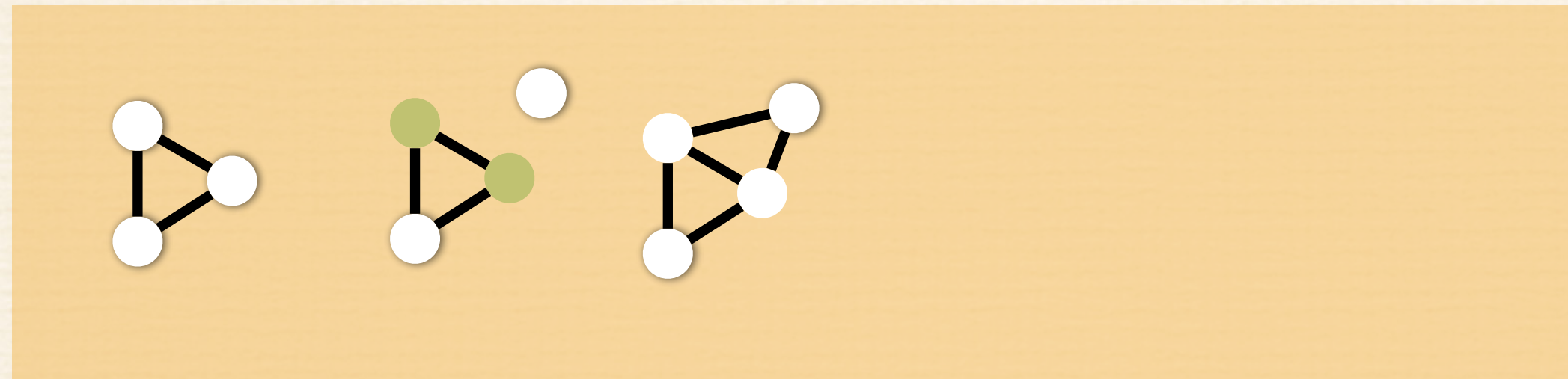
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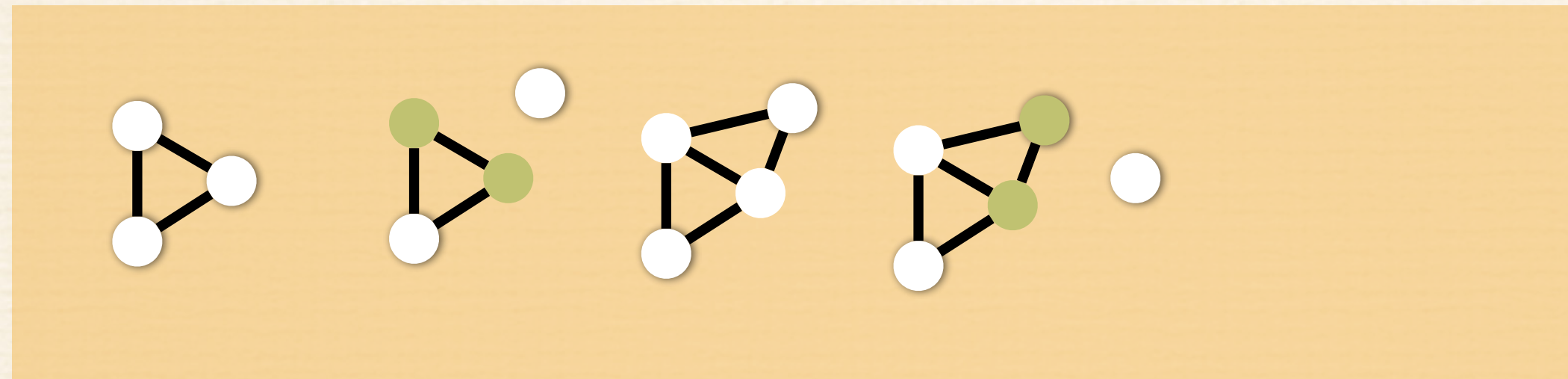
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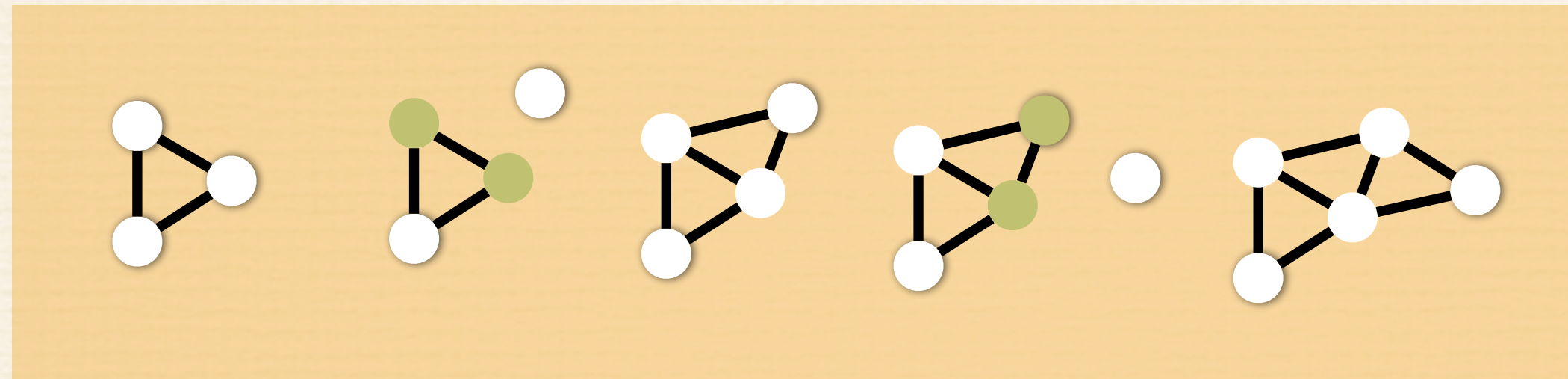
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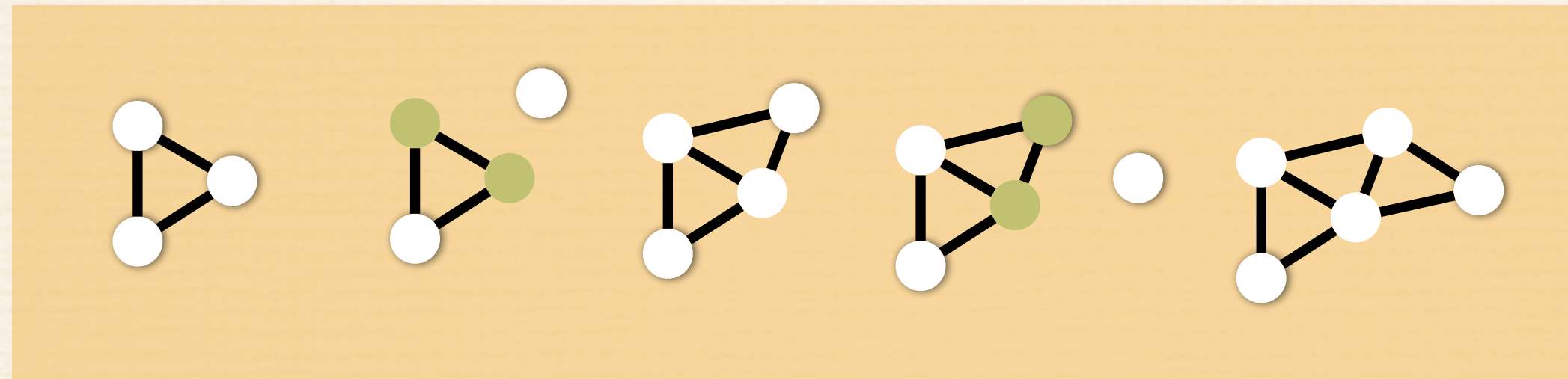
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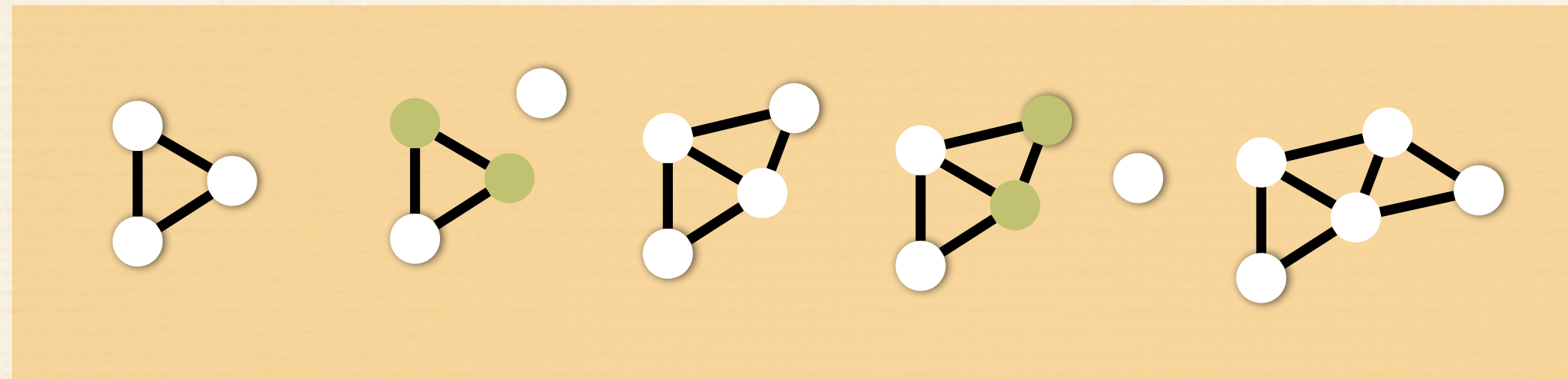


- ❖ A **partial k-tree** is a subgraph of a k -tree

Treewidth

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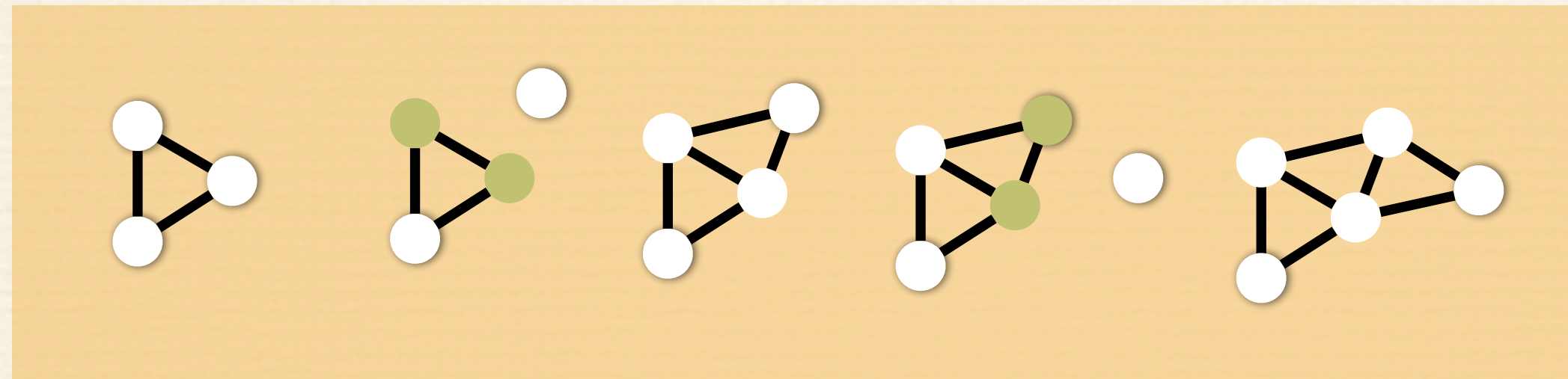
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Treewidth of a graph is smallest k such that the graph is a partial k -tree

Treewidth

- ❖ A **k-tree** is a graph that can be obtained starting from a $(k+1)$ -clique and then iteratively adding a vertex connected to a k -clique

$k=2$



- ❖ A **partial k-tree** is a subgraph of a k -tree

Treewidth of a graph is smallest k such that the graph is a partial k -tree

- ❖ Trees = Treewidth 1

More connections

- ❖ To combinatorial graph algorithms **color refinement** and **higher-dimensional Weisfeiler-Leman** graph isomorphism tests.
- ❖ To **linear algebraic congruences** between adjacency matrices and systems of equations.
- ❖ To **distance measures** on graphs and **metric equivalences**.

Z. Dvorák: *On recognizing graphs by numbers of homomorphisms*. (2010)

Dell, Grohe, Rattan: *Lovász meets Weisfeiler and Leman*. (2018)

Cai, Fürer, Immerman: *An optimal lower bound on the number of variables for graph identification*. (1992)

M. Grohe: *The logic of graph neural networks*. (2021)

Takeaway message #2:

Classification in terms of logic, homomorphism counts, ...

Hypothesis classes: how do they look like?

Equation: $h_i = f_{G,GRU}(x_i, \{h_j : j \rightarrow i\}) = C_{G,GRU}(x_i, \sum_{j \rightarrow i} h_j)$

Equation: $h_i^{t+1} = C_{G,GRU}(h_i^t, \tilde{h}_i^t), h_i^{t=0} = x_i \forall i$

Equation: $h_i^{t+1} = \sum_{j \rightarrow i} h_j^t$

Equation: $z_i^{t+1} = \sigma(U_z h_i^t + V_z \tilde{h}_i^t)$

Equation: $r_i^{t+1} = \sigma(U_r h_i^t + V_r \tilde{h}_i^t)$

Equation: $\tilde{h}_i^{t+1} = \tanh(U_h(h_i^t \odot r_i^{t+1}) + V_h \tilde{h}_i^t)$

Equation: $h_i^{t+1} = (1 - z_i^{t+1}) \odot h_i^t + z_i^{t+1} \odot \tilde{h}_i^{t+1}$

Equation: $X_{j,i} = (\mathbf{B}_{1,i,j}, \mathbf{B}_{1,j,i}), j \in [n], i \in [n]$

Equation: $m_v^{t+1} = \sum_{w \in N(v)} M_t(h_v^t, h_w^t, e_{vw})$

Equation: $h_v^{t+1} = U_t(h_v^t, m_v^{t+1})$

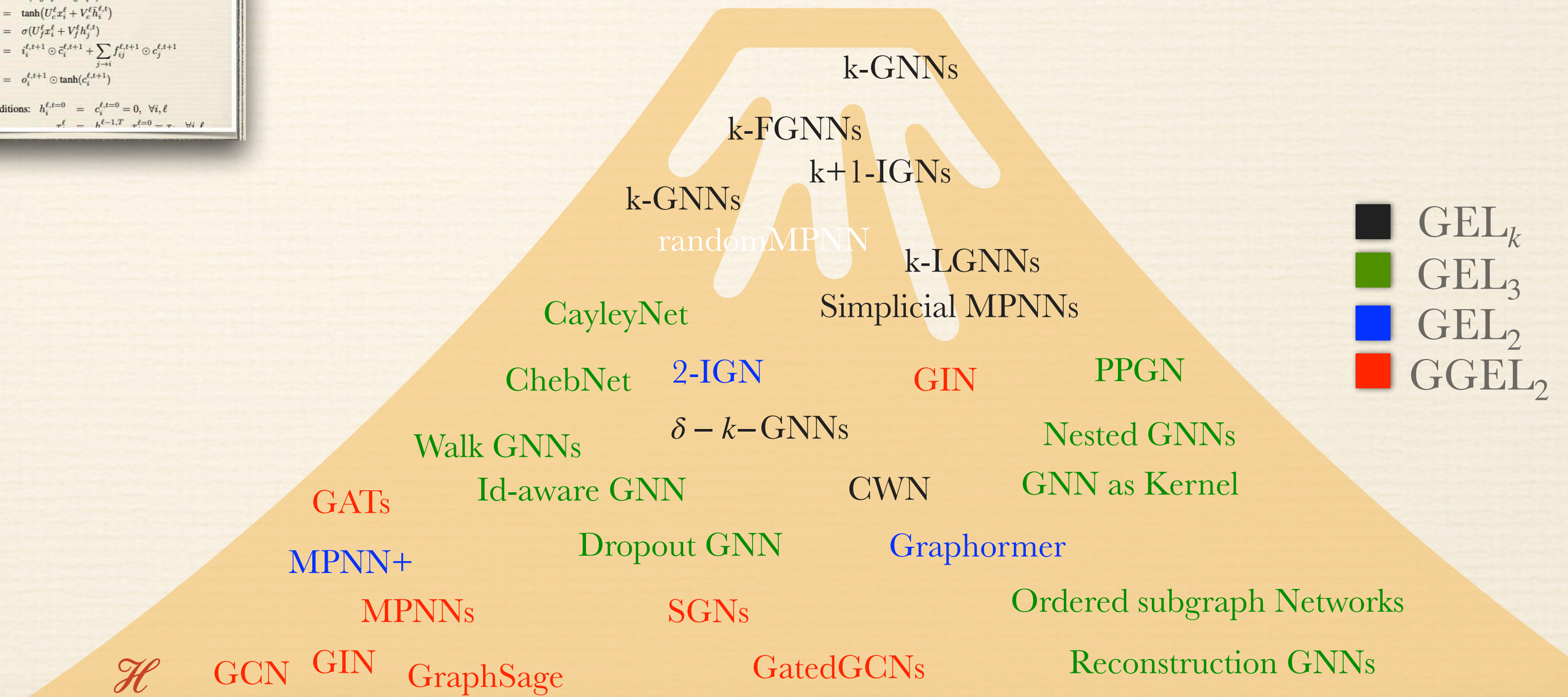
Equation: $h_i^{t+1} = f_{GCN}^t(\{h_j^t : j \rightarrow i\}) = \text{ReLU}(\sum_{j \rightarrow i} \eta_{ij} \odot V^t h_j^t)$

Equation: $\eta_{ij} = \sigma(A^t h_i^t + B^t h_j^t)$

Equation: $\psi(M_t H_t^m W_t + U_t H_{t-1}^m W_{t-1} + O_t H_{t-1}^m W_{t-1}), (11)$

Equation: $H^{m+1} = \psi(W H^m), (12)$

Equation: $W = \begin{bmatrix} W_1^m \otimes M_1 & W_2^m \otimes M_2 & \dots & W_n^m \otimes M_n \\ W_1^m \otimes U_1 & W_2^m \otimes U_2 & \dots & W_n^m \otimes U_n \\ W_1^m \otimes O_1 & W_2^m \otimes O_2 & \dots & W_n^m \otimes O_n \end{bmatrix}, (13)$



Expressive power

- ❖ Which inputs can be separated/distinguished by embeddings in \mathcal{H} .
- ❖ Which embeddings can be **approximated** by embeddings in \mathcal{H} ?

\mathcal{H} = class of embedding methods

Approximation properties

- ❖ Equip the set of graphs \mathcal{G} with a **topology** and assume that \mathcal{H} consists of **continuous graph embeddings** from \mathcal{G} to \mathbb{R} .
- ❖ Let $\mathcal{C} \subseteq \mathcal{G}$ be a **compact set** of graphs.

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Stone-Weierstrass

Theorem (Azizian & Lelarge 2021, G. and Reutter 2022)

If \mathcal{H} is closed under linear combinations and product, then \mathcal{H} can approximate any continuous function $\mathbb{E} : \mathcal{C} \rightarrow \mathbb{R}$ satisfying

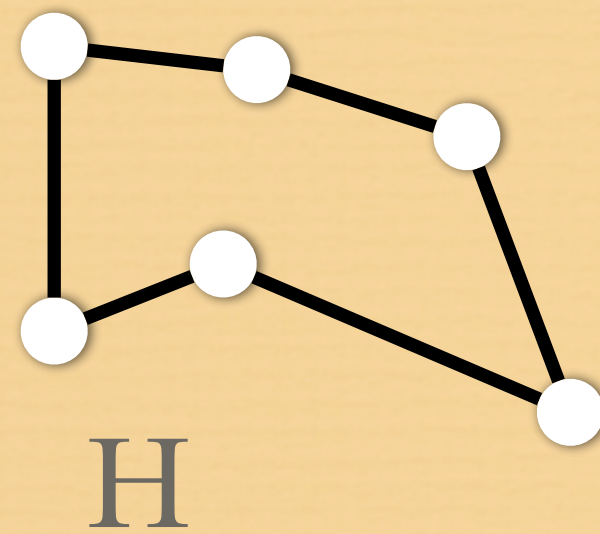
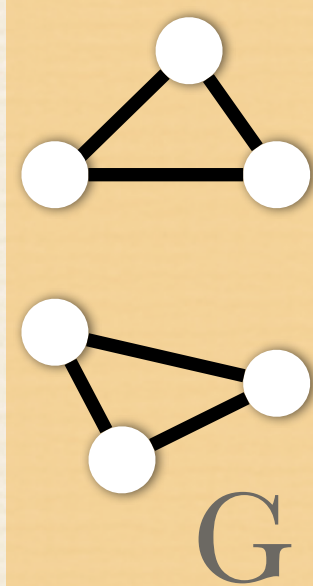
$$\rho(\mathcal{H}) \subseteq \rho(\{\mathbb{E}\}).$$

- ❖ Can be generalised to embeddings with output space \mathbb{R}^d

MPNNs: Approximation

Theorem

On compact set of graphs, MPNNs can approximate any continuous graph embedding $\Xi : \mathcal{C} \rightarrow \mathbb{R}$ satisfying $\rho(C_2) \subseteq \rho(\{\Xi\})$



$$(G, H) \in \rho(\text{MPNN}) \Rightarrow$$

Cannot approximate graph functions based on

- connected components
- 3-cliques
-

❖ Intricate relation between **distinguishing power** and **approximation properties**

Expressive power

- ❖ Which inputs can be separated/distinguished by embeddings in \mathcal{H} .
- ❖ Which embeddings can be approximated by embeddings in \mathcal{H} ?
- ❖ What is the **VC dimension** of \mathcal{H} ?

\mathcal{H} = class of embedding methods

VC dimension

- ❖ A set of graphs G_1, \dots, G_s can be **shattered by** \mathcal{H} if for any boolean vector $\tau \in \{0,1\}^s$, there is a $\xi_\tau \in \mathcal{H}$ such that $\xi_\tau(G_i) = \tau_i$ for all $i = 1, \dots, s$
- ❖ We define the **VC dimension of** \mathcal{H} on $\mathcal{G}' \subseteq \mathcal{G}$ as

$$\text{VC}_{\mathcal{G}'}(\mathcal{H}) := \max\{s \mid \exists G_1, \dots, G_s \text{ in } \mathcal{G}' \text{ which can be shattered by } \mathcal{H}\}$$

Theorem (Morris et al. 2023)

$$\text{VC}_{\mathcal{G}'}(\mathcal{H}) \leq |\mathcal{G}' / \rho(\mathcal{H})|$$

for some hypothesis classes also equality holds.

Equivalence classes induced by $\rho(\mathcal{H})$

Expressive power

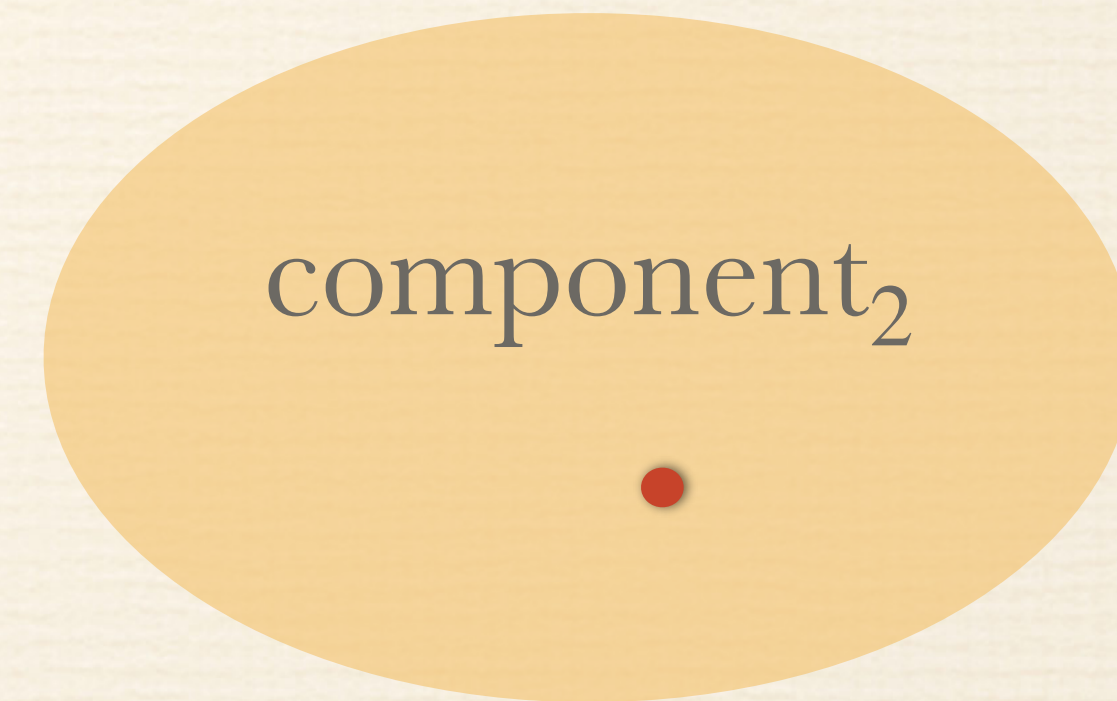
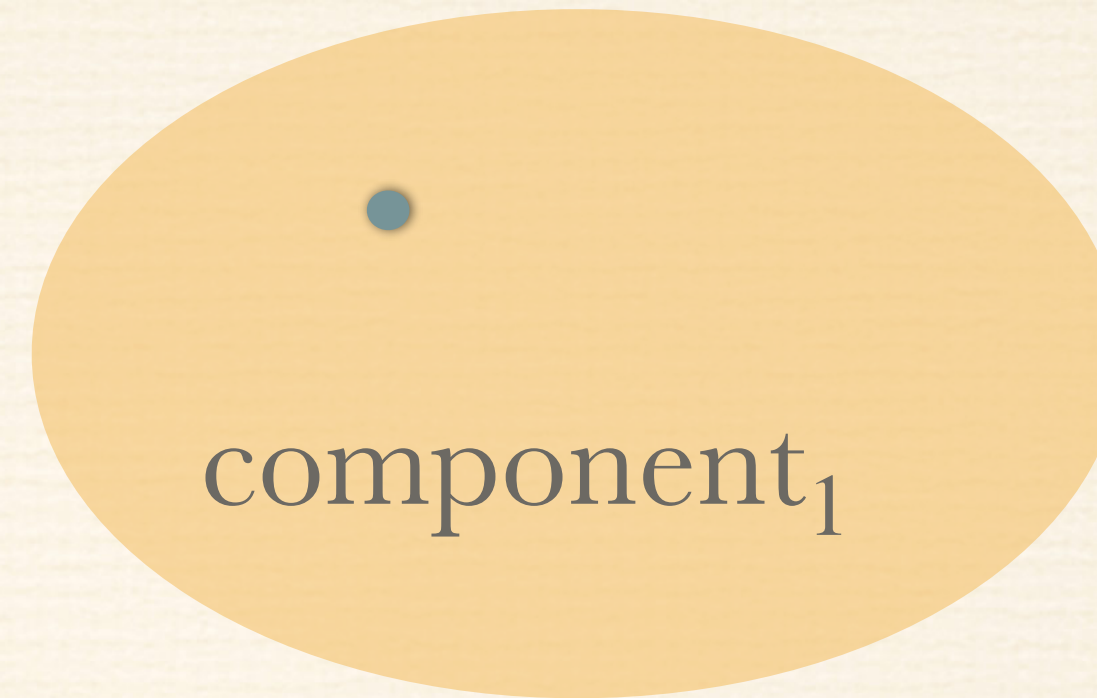
- ❖ Which inputs can be separated/distinguished by embeddings in \mathcal{H} .
- ❖ Which embeddings can be approximated by embeddings in \mathcal{H} ?
- ❖ What is the VC dimension of \mathcal{H} ?
- ❖ Which embeddings can **be expressed** by embeddings in \mathcal{H} ?

\mathcal{H} = class of embedding methods

Which unary C_2 formulas can MPNNs express?

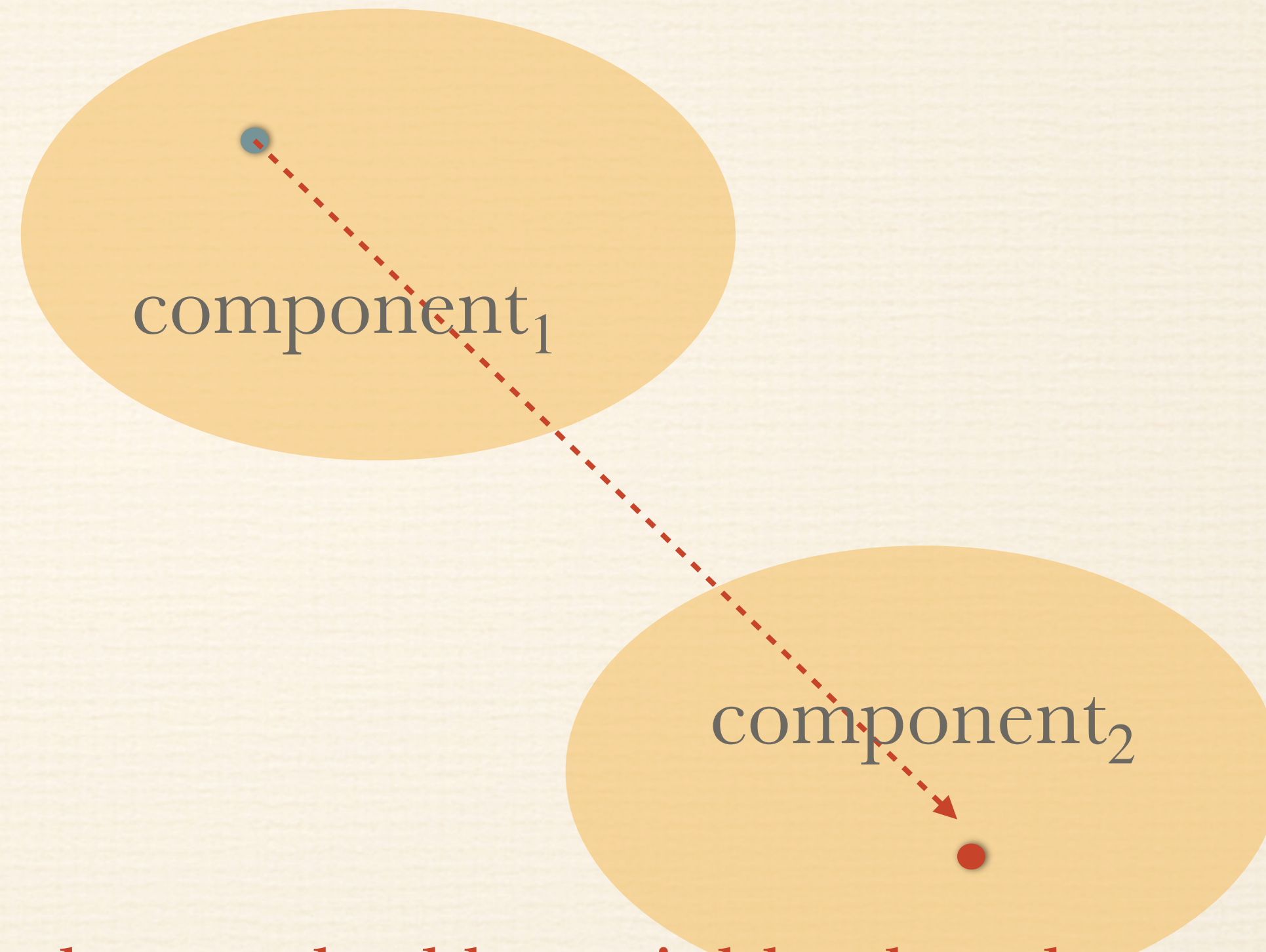
❖ Not all: $\varphi(x) := L_b(x) \wedge \exists y L_r(y)$

I am blue and there exist
a red vertex somewhere...



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I am blue and there exist a red vertex somewhere...



Cannot be reached by neighborhood aggregation

Which unary C_2 formulas can MPNNs express?

Theorem (Barceló et al. 2020)

Let $\varphi(x)$ be a unary C_2 formula. Then, $\varphi(x)$ is equivalent to a GC_2 formula *if and only if* $\varphi(x)$ is expressible by the class of MPNNs.

$$\exists \xi \in \text{MPNN} : \forall G \in \mathcal{G}, \forall v \in V_G : (G, v) \models \varphi \Leftrightarrow \xi(G, v) = 1$$

MPNNs+

Allow for **aggregation over all vertices** not only edge-guarded

Theorem (Barceló et al. 2020)

Every unary C_2 formula $\varphi(x)$ is expressible by the class of MPNNs+

Of course, there are queries beyond C_2 which MPNNs can express

Descriptive complexity of GNNs

Theorem (Grohe 2023)

If a unary query Q is computable by a GNN with rational weights and piecewise linear activation functions, then Q is definable in the guarded fragment of $\text{FO}_2 + \text{C}$

Different from C_2
Two sorted logic, numerical predicates etc.

- ❖ Extends to general GNNs with **real weights** and more **complex activation functions** \Rightarrow approximate with GNNs as in theorem

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Boolean functions computable by non-uniform polynomial-size bounded-depth family of **circuits** with threshold gates

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❖ Converse holds, with random vertex features.

Boolean functions computable by non-uniform polynomial-size bounded-depth family of **circuits** with threshold gates

Takeaway message #3:

Classification along different dimensions of expressibility, not only distinguishability

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Equation: $h_i^{t+1} = \mathcal{C}_{\text{G-GRU}}(h_i^t, \bar{h}_i^t)$, $h_i^{t=0} = x_i \forall i$, where $\bar{h}_i^t = \sum_{j \rightarrow i} h_j^t$

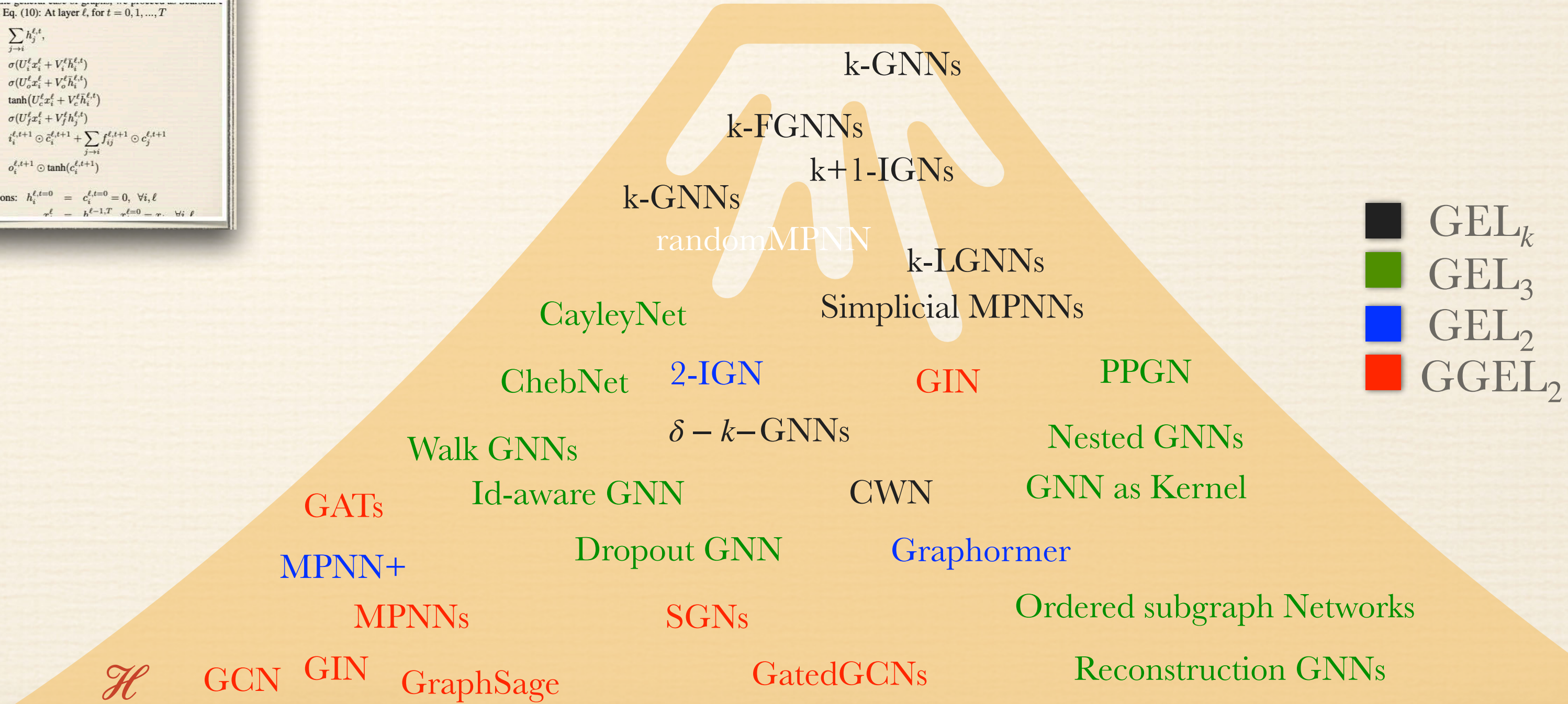
Equation: $z_i^{t+1} = \sigma(U_z h_i^t + V_z \bar{h}_i^t)$, $r_i^{t+1} = \sigma(U_r h_i^t + V_r \bar{h}_i^t)$, $\tilde{h}_i^{t+1} = \tanh(U_h(h_i^t \odot r_i^{t+1}) + V_h \bar{h}_i^t)$, $h_i^{t+1} = (1 - z_i^{t+1}) \odot h_i^t + z_i^{t+1} \odot \tilde{h}_i^{t+1}$

Equation: $h_i^{k+1} = \text{MLP}^{(k)}\left(\left(1 + \epsilon^{(k)}\right) \cdot h_i^{(k-1)} + \sum_{w \in N(v)} h_w^{(k-1)}\right)$

Equation: $m_v^{t+1} = \sum_{w \in N(v)} M_t(h_w^t, h_v^t, e_{vw})$, $h_v^{t+1} = U_t(h_v^t, m_v^{t+1})$

Equation: $h_i^{k+1} = f_{\text{GCN}}^k(\{h_j : j \rightarrow i\}) = \text{ReLU}\left(\sum_{j \rightarrow i} \eta_{ij} \odot V^k h_j^k\right)$, edge gates, and are computed by: $\eta_{ij} = \sigma(A^k h_i^k + B^k h_j^k)$

Equation: $\tilde{h}_i^{\ell,t} = \sum_{j \rightarrow i} h_j^{\ell,t}$, $z_i^{\ell,t+1} = \sigma(U_z^{\ell,t} x_i^{\ell,t} + V_z^{\ell,t} \tilde{h}_i^{\ell,t})$, $o_i^{\ell,t+1} = \sigma(U_o^{\ell,t} x_i^{\ell,t} + V_o^{\ell,t} \tilde{h}_i^{\ell,t})$, $c_i^{\ell,t+1} = \tanh(U_c^{\ell,t} x_i^{\ell,t} + V_c^{\ell,t} \tilde{h}_i^{\ell,t})$, $f_{ij}^{\ell,t+1} = \sigma(U_f^{\ell,t} x_i^{\ell,t} + V_f^{\ell,t} h_j^{\ell,t})$, $e_{ij}^{\ell,t+1} = z_i^{\ell,t+1} \odot c_i^{\ell,t+1} + \sum_{j \rightarrow i} f_{ij}^{\ell,t+1} \odot e_j^{\ell,t+1}$, $h_i^{\ell,t+1} = o_i^{\ell,t+1} \odot \tanh(e_i^{\ell,t+1})$



How to compare different classes?

- ❖ How to compare such embedding classes **theoretically**?
- ❖ How to bring **order to the chaos**?

1. See graph embedding methods as
queries in some **query language**

Distinguishability,
approximation, generalisation,
uniform and non-uniform
expressiveness

3. **Transfer**
understanding back to
graph learning world

2. **Analyse expressive**
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GEL

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Conclusion

Todos

- ❖ MPNNs: Efficient, most widely used but not expressive (C_2)
- ❖ Methods matching C_k for $k > 2$ require tensors making them inefficient
- ❖ Ongoing efforts to boost power but preserve efficiency

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Precompute hom/iso counts

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Spectral/Global properties

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Running graph learning method on a derived view.

Analysis of expressive power (logic, hom count,...)

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Huang et al.: *Boosting the cycle counting power of graph neural networks with I2-GNNs* (2022)
Papp et al.: *DropGNN: Random dropouts increase the expressiveness of graph neural networks*. (2021)
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Running graph learning method on many views, then aggregate. Analysis of expressive power

Todos

- ❖ Number of variables **depends on GEL skills**, are there better notions?
- ❖ **Specialized homomorphism count** characterizations, more fine grained than logic?
- ❖ Analysis **does not always explain experiments**. Is a more **fine grained** analysis possible, perhaps taking **learning process** into account?
- ❖ **Relational** embedding methods.
- ❖ **Recurrent GNNs** are closely related to fixpoint computations. Relationship to **query languages with recursion**?

Recipe for upper bounding architectures

1. **Take your GNN** architecture and **write it in GEL**, but using *a minimal number of variables* of variables.
2. Call this *number* of variables **k** .
3. Then the *power* of your architecture is **bounded by C_k**